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APPLICATION OF SINGULAR VALUE DECOMPOSITION
AND NONLINEAR FEEDBACK CONTROL
TO A MULTISPACE PROBLEM

A Thesis
Presented for the
Master of Science
Degree
The University of Tennessee, Knoxville

John H. E. Stelling III

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DEDICATION

This thesis is dedicated to two individuals who have had the greatest influence on my interests in science and research: my grandfather, Col. C. F. Myers, Jr., and my teacher, Dr. George B. Savitsky.

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ABSTRACT

Much has been written to indicate the desirability of process operation at or near an unstable steady state. A new control philosophy has been applied successfully to a first order experimental system to provide stable operation using a nonlinear feedback control device, a relay with hysteresis. Based on these encouraging results, the present study undertook to examine application of this control concept to a higher order system, the 2-azobisisobutyronitrile initiated bulk polymerization of styrene in a continuous flow stirred tank reactor.

The tenth order model developed for this polymerization system was studied using singular value decomposition, a mathematical analysis relatively new to the field of engineering applications. This process resulted in a simplification of the model to a lower order through a quantitative approach, improving on the qualitative arguments previously employed. A further application of singular value decomposition indicated specific control loops to be examined for best response to a step input change.

Tsyarkin's analysis, used when examining a relay control mechanism, was shown to be the necessary technique for design of the nonlinear control element for higher order systems, as the added complexity led to improper conclusions based on the standard Van Heerden graphical analysis approach. Due to the highly exothermic nature of the free radical polymerization process, control of the reactor temperature by inlet monomer concentration was shown to yield satisfactory process control about the unstable steady state. Period and amplitude of the oscillation as predicted by Tsyarkin's analysis compared very well with those resulting from the nonlinear simulation. Several new phenomena not previously observed in the application of this nonlinear scheme are reported. Other results of Tsyarkin's analysis of control strategies pointed toward interesting possibilities in the area of pushing (use of large relay drive levels) control theory.

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INTRODUCTION

The study of process control has become increasingly important in the years since World War II. Many of the questions regarding stability have been approached through investigations into process dynamics.

Through these studies of the process dynamics, it became obvious that many processes, spanning a wide variety of industrially significant reactions, exhibited steady state multiplicity, that is, more than a single unique set of operating conditions for any particular set of process parameters. For lumped-parameter systems having more than one stable steady state, there will be at least one unstable steady state. Quite often, it is the unstable steady state at which operation is desired, for example the lower steady state may have low yields associated with it and the upper steady state may represent an impractical operating condition or even perhaps a "runaway" condition. The unstable steady state may then be the logical compromise to obtain good yields and reasonable operating conditions.

Conventional linear control strategies have been applied successfully to a large number of industrially significant processes, but there is impetus to implement new methods of process control. A novel approach to process

control could provide stability of a periodic nature in a region about the unstable steady state. Furthermore, this idea of control "about" a steady state could yield some desirable product qualities unattainable with linear control.

This concept of nonlinear feedback control was set forth and mathematically investigated by Bruns, et. al., [23,24,25] and very recently by Matsubara and Onogi [27]. In a related study, Paredes [28,62] demonstrated the idea on an experimental system. Part of this work endeavored to investigate the nonlinear feedback control for a multispace complex process, a free radical polymerization reactor. Equally important in this current study was a survey of currently accepted models of the process. A comparison of the model used in this work and others was made to emphasize the role of process modeling and model simplification.

A new analysis technique in the field of engineering, singular value decomposition, was employed to study reactor modeling and control. Through the implementation of singular value decomposition, the process model was simplified to a reduced order using a quantitative approach rather than the qualitative "feel" generally employed for this purpose. Further application of singular value decomposition yielded an insight into the possible control strategies used to maintain process operation near the

unstable steady state.

CHAPTER I

LITERATURE SURVEY

Background Information

In a 1918 study by Liljenroth [1], the concept of a stability analysis in reaction engineering is first indicated, employing a Van Heerden [2] type of approach. Liljenroth used experimental data on the study of an ammonia oxidation burner (platinum wire gauze) to show that ammonia conversion to nitric oxide varied in a sigmoidal relationship with temperature; that is, a so-called "conversion curve" was constructed that was S-shaped. Further, he showed that the burner temperature was linearly related to the conversion, yielding his "heat of reaction line." By plotting both of these curves together, Liljenroth indicated the steady states of operation as the intersections of the lines. Even though he suggested the possibility of unstable steady states, he had observed none experimentally.

Van Heerden [2], in 1953, used a similar graphical approach to that of Liljenroth in his analysis of autothermic reactors. His ideas were more mathematically based by examining the system of interest from an energy

balance standpoint. He viewed the energy balance as being comprised of a heat generation contribution and a heat removal contribution. In the graphical analysis, the heat generation curve was sigmoidal in shape and the heat removal curve linear. His reasoning was that, at the intersections of these two curves, steady state conditions existed.

Van Heerden further indicated the "slope condition" of stability based on this graphical analysis. Now, it is well-known that the slope condition represents necessary and sufficient criteria for a single variable system and only a necessary condition for stability of multivariable systems [55,56,57]. Van Heerden [3] extended these concepts to the analysis of exothermic processes in continuous flow stirred-tank reactors (CSTRs) and various plug flow reactor (PFR) configurations.

Even though the mathematical analyses of Poincare [4], Lyapunov [5], and Minorsky [6] had been available, it was not until 1955 that these methods were applied by Bilous and Amundson [7] in the reaction engineering field. The idea of using perturbation theory of the linearized system was employed for an irreversible exothermic reaction occurring in a CSTR (continuous flow stirred tank reactor), a process described by two ordinary differential equations. Their results for the linearized system were then compared with analog "reaction paths" or phase plots developed from the

nonlinear equations.

In 1958, Aris and Amundson [8,9,10] investigated the stability problem in a now-classical series of papers. The problems of stability and transient behavior were mathematically theorized for the CSTR model used by Bilous and Amundson. Of equal significance was their presentation of stability analyses for the various modes of linear control (i.e. proportional, proportional-integral, etc.) applied to systems at the unstable steady state.

These initial investigations provided a firm base from which an ever-increasing volume of work has been accomplished. The following survey is but a brief review of some recent work which is central to the current research.

Recent Publications

Concepts and analyses illustrated by Van Heerden, Aris, Amundson, and others have stood to encourage much investigative work in the area of process dynamics and control. Through subsequent studies, much has been learned about steady state multiplicity and oscillatory chemical reactor behavior. Implementation of applicable control schemes to unstable systems has been a result of this work.

Chemical reactors have generally been designed under steady state conditions [37,51,52,53], with no regard to transient behavior. Since transients are encountered at reactor start-up and shutdown, as well as with any perturbation in operating parameters, these effects could well influence reactor performance and should, therefore, be considered. Further, steady state multiplicity and, thus, unstable steady states need to be accounted for in these designs.

In a review of practical applications of reactor stability, Schmeal and Barkelew [11] drew from their industrial setting various problems encountered in the operation of continuous stirred-tank reactors (the autocatalytic effect in the hydration of olefins to alcohols using sulfuric acid as catalyst), imperfectly mixed reactors, and packed bed reactors. Also discussed were the various effects of steady state multiplicity in slurry reactions, two-phase reactions, and metal-fluid reactions.

Similarly, ElNashaie, Marek and Ray [12] investigated the problem of catalyst deactivation in dispersed catalytic reactors. Their work showed that for some ranges of catalyst activity multiple steady states could occur. In their example they found when in a region of multiple steady states, operation at the unstable steady state was indicated as nearer optimal based on the moderate operating

temperature. Even though the upper steady state gave higher productivity initially, the higher operating temperature caused more rapid deactivation of the catalyst and a shift from a region of steady state multiplicity to a region of a single unproductive lower steady state. Therefore, operation at the unstable steady state provided a better time-averaged yield with slowly increasing moderate productivity and moderate decay rate.

Reaction multiplicity is common in biological and enzyme systems [58,59,60]. Bruns, et al., [13] presented a mathematical investigation of an enzymatic reaction exhibiting an inhibited substrate reaction mechanism. A stable oscillatory state was shown for the case of a unique steady state. For the case of steady state multiplicity, oscillatory behavior was observed outside the region of asymptotic stability. Stelling, et al., [61] used this same system to illustrate, via numerical simulation, limit cycle amplitude reduction by employing a relay with hysteresis as a feedback controller.

Chemical oscillations were found by Franck [15] to depend heavily upon complex kinetic mechanisms: coupling between reactions and various transport phenomena. Gilles, et al., [16] expanded on this concept in their study of the catalytic fixed bed reactor for an endothermic reaction with self-inhibiting or self-accelerating steps. They

included simulations of the dehydrogenation of alcohol on an oxide catalyst.

Ivanov, et al., [14] present investigations in the area of steady state multiplicity and stable limit cycles for a catalytic reaction system coupled to an adsorption process. In their study, periodic oscillatory behavior is correlated to the system kinetic and model parameters.

Knorr and O'Driscoll [17] used batch reactor data on the bulk polymerization of styrene to demonstrate mathematically the possible existence of multiple steady states in an isothermal CSTR. Through a Van Heerden-type approach using the steady state mass balance, they show that the middle steady state is necessarily unstable. In the case of the polymerization reactor, operation at or near the unstable steady state is desirable since little or no product is made at the lower steady state and, at the upper steady state, the so-called "gel effect" causes the product to be of undesirable characteristics. To attain operation at the intermediate conversion level, Knorr and O'Driscoll suggest an oscillating monomer feed concentration and reactor recycling.

In related work Ray [18] examined the effect on molecular weight distributions of sinusoidal perturbations in monomer feed concentrations for continuous stirred-tank

reactors. Laurence and Vasudevan [19] used very slow forced oscillations of feed concentrations of monomer and initiator to study the time-averaged effects on the molecular weight distributions. An experimental study of periodic operation of a styrene polymerization reactor using open loop on-off control of initiator feed was presented by Spitz, et al., [20]. Additional experimental studies of forced periodic open loop operation of polymerization reactors are cited in the literature.

Bruns, et al., [23,24,25] propose operation of a system near its unstable steady state using a nonlinear feedback control element. Matsubara and Onogi [27] recently showed for an example that, for performance at an unstable steady state, the nonlinear relay control should be used for stability reasons and that this novel controller is superior to the conventional linear controller in performance for this case. In an experimental study, Paredes [28,62] successfully applied the nonlinear feedback control element to maintain process operation near an unstable steady state in the bis-trichloromethyl-trisulfide-aniline reaction system in a CSTR [54].

These articles represent but a few of many regarding the phenomenon of steady state multiplicity. Further examples may be found in a comprehensive review of multiplicity by Schmitz [29].

CHAPTER II

REACTION SYSTEM

Introduction

Polymerization is the process by which molecular units known as monomers are combined to form aggregates known as polymers. Since the kinetic mechanism of the polymerization process is very complex, much effort in recent years has gone into the characterization of these processes so that consistent product properties might be maintained [30-39]. The example of interest in this research is the chain growth free radical polymerization in a CSTR of styrene with initiation by 2-azobisisobutyronitrile (AIBN).

In polymerization reactions, there exists an essentially infinite number of individual chemical species (free radicals and polymers of varying chain lengths). Therefore, the kinetic expressions describing the polymerization process comprise an infinite set. This number of expressions is effectively reduced to a finite set through the use of number chain length distributions for radical and polymer species. To attain these distribution descriptions, basically these methods have been employed: generating function technique, stepwise algebraic

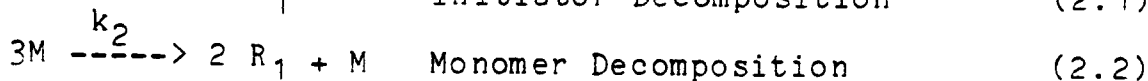
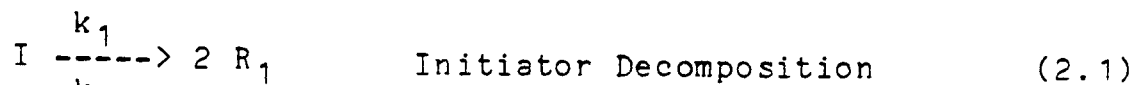
substitution technique, continuous variable technique, and discrete variable technique [40,41,42]. Perhaps the simplest method to apply is the discrete variable technique which makes use of Z-transformations [19,22,41].

Polymerization Kinetics

Free radical unipolymerization kinetics may be described by essentially five mechanisms: free radical generation, polymerization initiation, propagation, chain transfer, and termination. Each mechanism will be discussed individually before combining all the steps to yield the full polymerization reactor model used in this research. In every case, the discussion will be directed toward the free radical polymerization of styrene initiated by AIBN. The ensuing discussion is the result of modeling due to [30-50].

Free Radical Generation. Free radicals are generated when covalent bonds of monomer or free radical-producing agents are homolytically broken. The lower the energy required to break these bonds, the more stable the resulting free radical is; some free radicals may be so stable that they may not be capable of initiating polymerization. The methods of introducing this dissociation energy requirement are varied: electrochemically, chemically (redox systems), photochemically, or thermally.

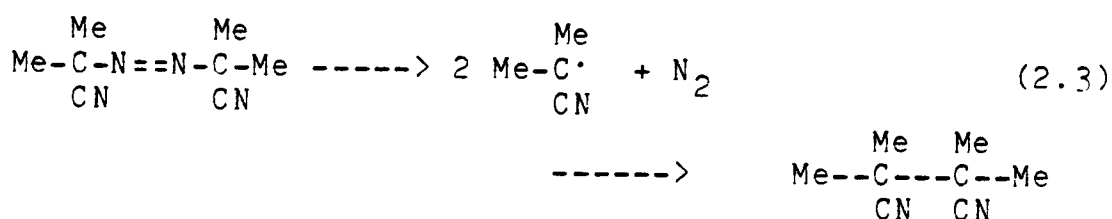
Of interest in this research is free radical generation by initiator decomposition and by thermal decomposition of the monomer:



where: I initiator
 M monomer
 R₁ single unit free radical
 k₁ rate constants
 k₂

The thermal decomposition method, naturally, is increasingly important as the reaction temperature is increased, and, in fact, becomes the predominant radical generating mechanism above 120°C [63]. These free radicals are available to initiate polymerization with monomer, polymer, or another radical.

One problem encountered with an initiator is the so-called "cage effect" that essentially eliminates available radicals through reaction with itself. Consider the case of AIBN as the initiator:



As the two radicals are formed, they may recombine as shown

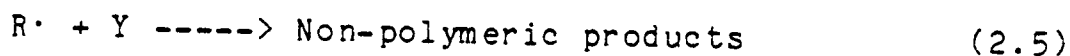
if they are not sterically blocked from doing so or if they do not have the opportunity to diffuse away from one another. To take this cage effect into account, an initiator efficiency is generally employed in the rate expressions involving initiator-initiated polymerization [43-47].

Initiation of Polymerization. Initiation occurs when a free radical reacts with another species. The most desired of these initiation reactions is that involving radical and monomer:



where: $R\cdot$ any free radical
 M monomer
 $RM\cdot$ a new free radical of
 increased length

but, as discussed earlier, undesired reactions may occur:

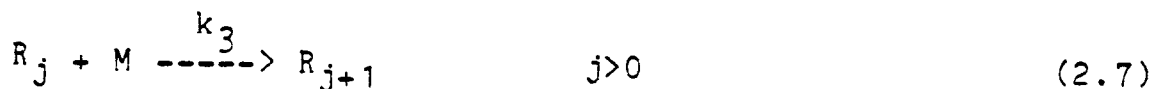


The efficiency factor, f , is used in the current study to describe that number of free radicals actually initiating polymerization. In this way both the cage effect and side reactions are accounted for with the resulting initiation rate expression is:

$$r_i = 2k_1fI + 2k_2M^3 \quad (2.6)$$

The particular correlation for the efficiency factor, f , is the same as that used by Spitz [22].

Propagation. Propagation is that step where monomer units are added to a free radical of undetermined length to form a free radical of increased chain length:



The rate of formation due to propagation for chain length growth from $j-1$ to j is given by:

$$r_p = k_3 M (R_{j-1} - R_j) \quad (2.8)$$

Transfer Reactions. A transfer reaction is one in which something is transferred from one chemical species to another. Transfer reactions may involve the transfer of a chemical site (the site of kinetic activity) or the transfer of radical activity. Dependent upon the relative activity of the resultant radical species, a transfer reaction may be viewed as a termination reaction, an acceleration reaction, an inhibition or retardation step, or a straight transfer from one polymer chain to another. Further complications are included since transfer reactions may occur with any species (monomer, polymer, solvent, etc.). Due to these properties, transfer reactions are often used to control polymer product properties, such as molecular weight.

For this particular system of interest, transfer to monomer is the predominant transfer reaction:

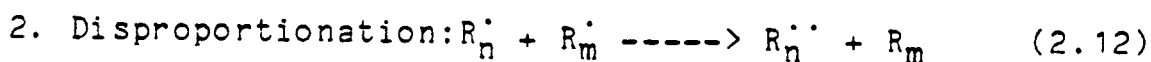
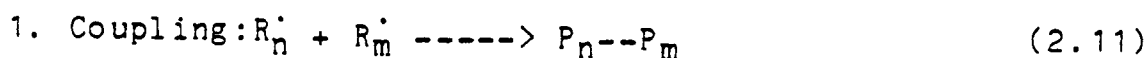


where: P_j polymer of length j
 and the rate of transfer for radicals of length j is given by:

$$r_{tr} = k_4 M (R_j - R_j \delta(j-1)) \quad (2.10)$$

where: $\delta(j-1)$ dirac delta function

Termination of Chain Growth. Termination is that step or reaction mechanism which effectively halts chain length growth through propagation. Common forms of termination are illustrated by:



Other mechanisms for termination of polymerization include termination with monomer and through transfer reactions.

Most specifically for the styrene system under study, termination is by radical recombination:



CSTR Model Development

With the kinetic expressions previously given, individual species balances may be written for the CSTR model where no polymer is fed to the reactor and constant reactor volume is assumed:

$$\text{Initiator: } \frac{dI}{dt} = \frac{(I_0 - I)}{\theta} - k_1 I \quad (2.14)$$

$$\text{Monomer: } \frac{dM}{d\tau} = \frac{(M_0 - M)}{\Theta} - 2k_2M^3 - k_3M\sum R_j - k_4M\sum R_j \quad (2.15)$$

$$\begin{aligned} \text{Radical: } \frac{dR_j}{d\tau} = & -\frac{R_j}{\Theta} + (2k_1fI + 2k_2M^3)\delta(j-1) \\ & + k_3M(R_{j-1} - R_j) \\ & + k_4M(R_j\delta(j-1) - R_j) - k_5R_j\sum R_k \end{aligned} \quad (2.16)$$

$$\text{Polymer: } \frac{dP_j}{d\tau} = -\frac{P_j}{\Theta} + k_4MR_j + \frac{k_5}{2}\sum R_j - kR_k \quad (2.17)$$

where: I_0 initiator feed concentration
 M_0 monomer feed concentration
 Θ reactor residence time

Through the use of Z-transformations, as previously described, differential equations for the moments of free radical distribution and of polymer distribution may be written [19,22,41]:

$$\frac{d\sigma_0}{d\tau} = -\frac{\sigma_0}{\Theta} + (2k_1fI + 2k_2M^3) - k_5\sigma_0^2 \quad (2.18)$$

$$\begin{aligned} \frac{d\sigma_1}{d\tau} = & -\frac{\sigma_1}{\Theta} + (2k_1fI + 2k_2M^3) + (k_3 + k_4)M\sigma_0 \\ & - k_4M\sigma_1 - k_5\sigma_0\sigma_1 \end{aligned} \quad (2.19)$$

$$\begin{aligned} \frac{d\sigma_2}{d\tau} = & -\frac{\sigma_2}{\Theta} + (2k_1fI + 2k_2M^3) + (k_3 + k_4)M\sigma_0 \\ & + 2k_3M\sigma_1 - k_4M\sigma_2 - k_5\sigma_0\sigma_2 \end{aligned} \quad (2.20)$$

$$\frac{d\mu_0}{d\tau} = -\frac{\mu_0}{\Theta} + k_4M(\sigma_0 - R_1) + k_5\sigma_0^2 \quad (2.21)$$

$$\frac{d\mu_1}{d\tau} = -\frac{\mu_1}{\Theta} + k_4M(\sigma_1 - R_1) + k_5\sigma_0\sigma_1 \quad (2.22)$$

$$\frac{d\mu_2}{d\tau} = -\frac{\mu_2}{\Theta} + k_4M(\sigma_2 - R_1) + k_5(\sigma_0\sigma_2 + \sigma_1^2) \quad (2.23)$$

where: σ_0	0th moment of radical distribution
σ_1	1st moment of radical distribution
σ_2	2nd moment of radical distribution
μ_0	0th moment of polymer distribution
μ_1	1st moment of polymer distribution
μ_2	2nd moment of polymer distribution

The moments of radical distribution are generally written to describe radicals of all chain lengths. But, in the initial development of this model, special consideration was given to the single-unit-length radical since it was involved in reactions that other radicals were not associated with (ie. thermal initiation, initiator decomposition, transfer reactions). The rate equation for this species is given by:

$$\begin{aligned} \frac{dR_1}{dt} = & \frac{-R_1}{\Theta} + (2k_1fI + 2k_2M^3) - (k_3 + k_4)MR_1 \\ & + k_4M\sigma_0 - k_5\sigma_0R_1 \end{aligned} \quad (2.24)$$

Under normal circumstances, that is, single precision reaction dynamics studies, the R_1 term is left out entirely since its effect is not noted to any significant digit. Even though the effect of this term still appears to be negligible under the current double precision considerations, an analysis discussed later in Chapter IV indicates that this term should be retained. Using the derived moment expressions, and including the consideration

of the single-unit-length radical R_1 , the monomer balance equation may be rewritten as:

$$\frac{dM}{dt} = \frac{(M_0 - M)}{\Theta} - 2k_2M^3 - (k_3 + k_4)M\sigma_0 + k_4MR_1 \quad (2.25)$$

Since this study involves the case of the nonisothermal CSTR, an energy balance must be included to describe temperature transients. In general, this balance is given by:

$$\frac{d(V\rho C_p T)}{dt} = \frac{V\rho_0 C_{p0}(T_0 - T_r)}{\Theta} - V\rho C_p(T - T_r) - UA_H(T - T_c) + V\sum(-\Delta H_i)r_i \quad (2.26)$$

where: ΔH_i heat of reaction for reaction i
 V reactor volume
 ρ density of reaction mixture
 C_p heat capacity of reaction mixture
 T_0 inlet temperature
 T_r reference temperature
 T_c coolant temperature
 U overall heat transfer coefficient
 A_H heat transfer area

Assumptions commonly made regarding this energy balance are:

1. constant volume reactor: a standard practice for liquid-phase reaction systems;

2. average coolant temperature: a standard practice described by Aris [53];
3. constant density and heat capacity: although it is known that these properties do change over the entire range of operating conditions possible, the additional complexity encountered in the inclusion of variable properties in this model would not enhance the results of this study. The common approach used has been to assume constant density and heat capacity.
4. significant heats of reaction for only thermal initiation, propagation, and transfer reactions[20-22];

yielding the following energy balance:

$$\frac{dT}{dt} = \frac{(T_o - T)}{\Theta} - \frac{UA_H(T - T_o)}{V\rho C_p} + \frac{((- \Delta H_2)k_2M^3 + (- \Delta H_3)k_3M\sigma_o + (- \Delta H_{II})k_{II}M\sigma_o)}{\rho C_p} \quad (2.27)$$

Thus, the complete model describing the system under study is given by the ten ordinary differential equations written as (2.14), (2.18)-(2.25), and (2.27).

Phenomena of High Temperature and High Conversion

In general, the total rate of propagation is expected to decrease in some closely-linear relationship to monomer conversion. However, observations indicate that this total rate of reaction frequently will increase, pass through a maximum, and then decrease. This behavior is due to diffusion-related effects and is called the gel effect or the Trommsdorf effect. The gel effect, occurring at high conversions where the monomer concentration is low and the polymer concentration is high, is exhibited as an increase in the rate of polymerization resulting from the combination of essentially immobile polymer chains and diffusion-mobile monomer units.

An additional diffusion-related effect is noted at even higher conversions due to the very high viscosities encountered. Due to the higher viscosity and even lower monomer concentration, the combination of monomer and polymer free radicals is slowed and the rate of polymerization decreases again. This phenomenon is known as the glass effect.

Gel and glass effects have been studied and modeled [43-50] with the resulting correlations showing the effects in terms of the propagation and termination reaction rate constants. The correlation of Hui and Hamielec [47] has

been included as part of the model used in this research, and is given as:

$$k_5 = k_{50}(\exp(Ax + Bx^2 + Cx^3))^{-2} \quad (2.28)$$

$$\text{where: } A = 2.57 - .00505T$$

$$B = 9.56 - .0176T$$

$$C = -3.03 + .00785T$$

$$x = (M_0 - M)/M_0$$

$$k_{50} = \text{rate constant at zero conversion}$$

$$k_5 = \text{rate constant at actual conversion.}$$

Summary of Model Parameters

It was the intention of this study to choose a process of some industrial importance. Concurrent with this thinking was the selection of parameter values such that the results of this work might have some correlation to a real situation. These model parameter values are noted in TABLE 2-1.

TABLE 2-1. MODEL PARAMETER VALUES

PARAMETER	VALUE	REFERENCE
ρ	11.5 gmol/l	81
C_p	33.5 cal/gmol	81
U	0.0005 cal/sec-cm ² -°K	82
V	1000 l	
θ	10080 sec	
I_0	0.0106 gmol/l	
M_0	4.81 gmol/l	
$-\Delta H_2$	10000.	26
$-\Delta H_3$	16680.	26
$-\Delta H_4$	16680.	26
k_1'	1.580 E 15	26
k_2'	2.190 E 5	26
k_3'	1.050 E 7	26
k_4'	2.310 E -6	26
k_5'	1.255 E 9	26
E_1	30800.	26
E_2	27441.	26
E_3	7067.	26
E_4	12671.	26
E_5	1677.	26
f	exp(-2x)	20, 22

$$j = 1 \text{ to } 5$$

$$k(I) = k(I)' \times \exp(-E_I / 1.987 / T)$$

$$h(5) = k(5) / (\exp(Ax + Bx^2 + Cx^3))^2$$

CHAPTER III

STEADY STATES AND STABILITY

This section deals with the determination of steady states for any particular set of system parameters and the analysis of the resulting steady state operating conditions as regards stability. The term stability, here and in the remainder of the thesis, will mean local asymptotic stability unless otherwise noted. The problem of control at the unstable steady state and the stability of the resulting controlled process will be addressed later.

General Introduction

In the analysis of any dynamic system, the question of stability of a steady state becomes important; this is especially the case for systems involving steady state multiplicity. The criteria for determination of stability is well established [53,55,56,57,64] and will not be elaborated here. There are many available references which present the development of these criteria for a second order system [56,57,64]. In lieu of reiterating this development, some general comments pertaining to their results and the logical extensions to higher order systems will be made.

As referenced earlier, Van Heerden [2] presented a graphical approach to stability analysis which involved separation of the energy balance into heat generation and heat removal curves. Intersections of these curves represent steady state conditions and the "slope condition" for stability was established. For the single variable problem, this slope condition is necessary and sufficient; but, for higher order systems, the slope condition is only a necessary condition for stability.

Local asymptotic stability (eg. that steady state where transients in an arbitrarily small region about the state die out as time progresses) analysis represents necessary and sufficient criteria for stability of higher order systems. Local stability is based on the linearized system about the steady state of interest, where the equations may be written as:

$$Y = AX \quad (3.1)$$

where: Y vector of derivatives of X
 X vector of perturbation variables
 A matrix containing the linearization
 coefficients evaluated at the steady
 state of interest: Jacobian matrix.

For an n^{th} order system described as above, the characteristic equation is given by:

$$\det(A - \lambda I) = 0 \quad (3.2)$$

where: I identity matrix
 λ roots of characteristic equation
or eigenvalues

Another representation of the characteristic equation is in the form of an n^{th} order polynomial:

$$b_0 \lambda^n + b_1 \lambda^{n-1} + \dots + b_{n-1} \lambda + b_n = 0. \quad (3.3)$$

In order to have local asymptotic stability, the eigenvalues of the Jacobian matrix (the roots of the characteristic equation) must have negative real parts. In the case of instability, the eigenvectors corresponding to the positive eigenvalues will indicate the source(s) of the instability.

Another way of expressing the necessary and sufficient conditions for local stability is the Routh-Hurwitz criteria. That is, the successive determinants defined by

$$\Delta_1 = b_1, \Delta_2 = \begin{vmatrix} b_1 & b_0 \\ b_3 & b_2 \end{vmatrix}, \Delta_3 = \begin{vmatrix} b_1 & b_0 & 0 \\ b_3 & b_2 & b_1 \\ b_5 & b_4 & b_3 \end{vmatrix}, \quad (3.4)$$

$$\Delta_r = \begin{vmatrix} b_1 & b_0 & 0 & 0 & 0 & 0 & 0 \\ b_3 & b_2 & b_1 & b_0 & 0 & 0 & 0 \\ b_5 & b_4 & b_3 & b_2 & b_1 & b_0 & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ b_{2n-1} & b_{2n-2} & \cdot & \cdot & \cdot & \cdot & b_n \end{vmatrix} \quad (3.5)$$

must all be positive for an n^{th} order system.

With the advent of high-speed computers and available mathematical techniques, the second method of Lyapunov and Krasovskii's theorem [5,57,65] have been applied for

stability analyses. This method of analysis acts as a sufficient, but not necessary, condition for stability of the steady state. It gives additional information as it identifies a specific region where asymptotic stability applies. This method has been found, in general, to be very conservative for the actual region of stability is usually considerably larger than that indicated by the Lyapunov function. An example of a second order system is presented by Berger and Perlmutter [66,67].

Literature: Stability of Polymerization Reactors

As noted in the literature survey, much effort has gone into investigating the dynamics of the free radical polymerization of styrene, with particular interest in the steady state multiplicity of the system. There has been some effort put forth in examining the stability of these systems. Basically, there are two types of stability problems encountered in this class of reactions. Concentration stability is due to the auto-acceleration nature of the polymerization reaction and may present itself even under isothermal conditions. Temperature or thermal stability involves both the auto-acceleration effects and the exothermic effects of the polymerization process. This review is intended only as a brief introduction to the available publications on the topic.

Warden and Amundson [35] applied the Routh-Hurwitz criteria to a monomer-terminated addition polymerization with first order initiation step in a nonisothermal CSTR. Their system was described by three ordinary differential equations. They also investigated regions of stability for various modes of linear control applied to the system. One result of their study was that the unstable steady state could always be made stable using proportional control based on the reactor temperature and several manipulated variables. Ranges of parameter values for the various modes of control were indicated for stable control of the average molecular weight and of the total polymer concentration.

Knorr and O'Driscoll [17] used a Van Heerden-type analysis using the steady state mass balance (monomer) equation to determine steady state multiplicity. They note that multiple steady states exist for the styrene polymerization CSTR for both nonisothermal and isothermal cases. Much of their work deals with the phenomena occurring at higher temperatures and higher conversions. In his dissertation, Knorr [49] gives far more detail of the stability problems with suggestions for control. Also, he examines the additional complexities associated with the copolymerization process.

Shastri and Fan [37] depart from the classical analysis techniques using linearization to apply Lyapunov's second or direct method to determine regions of stability. Their studies used simplified kinetic models to examine the temperature stability of homopolymerization in two tanks in series and of copolymerization in a single CSTR.

A study of dynamic behavior in free radical polymerization reactors, where oscillatory phenomena is possible, is presented by Jaisinghani and Ray [48]. Polymethymethacrylate and polystyrene systems were studied using simplified dimensionless equations. Lowering the order of their model to two ordinary differential equations, they used bifurcation theory to determine that unstable limit cycles are possible at the upper steady state only. More detail on the polystyrene system is available in the thesis by Jaisinghani [50]. One of the interesting results is that there was no qualitative changes in their simulations either with or without the initiator dynamics. Quantitative analyses predicting this result arrived at in their numerical study is presented later in Chapter IV.

With this basic review of stability, in general, and of some of the existing literature concerning dynamics and steady state stability of polymerization reactors, the problem of steady state multiplicity and stability analysis of the specific system of interest will be investigated.

Analysis of the Reaction System

Steady States. The search for steady state multiplicity for the reaction system under study was done through a Van Heerden-type approach of the nonisothermal system. All time-dependent derivatives (equations 2.14, 2.18-2.25, 2.27) were set equal to zero and the resulting equations solved for the steady state operating conditions:

$$I = I_0 / (1 + k_1 \Theta) \quad (3.6)$$

$$\sigma_0 = \frac{-1 + \sqrt{1 + 8k_5(k_1 f I + k_2 M^3) \Theta^2}}{2k_5 \Theta} \quad (3.7)$$

$$\sigma_1 = \frac{2(k_1 f I + k_2 M^3) + (k_3 + k_4) M \sigma_0}{1/\Theta + k_4 M + k_5 \sigma_0} \quad (3.8)$$

$$\sigma_2 = \sigma_1 \left[1 + \frac{2k_3 M}{1/\Theta + k_4 M + k_5 \sigma_0} \right] \quad (3.9)$$

$$R_1 = \frac{2(k_1 f I + k_2 M^3) + k_4 M \sigma_0}{1/\Theta + (k_3 + k_4) M \sigma_0 - k_5 \sigma_0} \quad (3.10)$$

$$\mu_0 = \Theta \left[k_4 M (\sigma_0 - R_1) + \frac{k_5 \sigma_0^2}{2} \right] \quad (3.11)$$

$$\mu_1 = \Theta \left[k_4 M (\sigma_1 - R_1) + k_5 \sigma_0 \sigma_1 \right] \quad (3.12)$$

$$\mu_2 = \Theta \left[k_4 M (\sigma_2 - R_1) + k_5 (\sigma_0 \sigma_2 + \sigma_1^2) \right] \quad (3.13)$$

$$0 = (M_0 - M) / \Theta - 2k_2 M^3 - (k_3 + k_4) M \sigma_0 + k_4 M R_1 \quad (3.14)$$

$$0 = \frac{\sum(-\Delta H_i)r_i}{f C_p} - \left[\frac{(T-T_o)}{\theta} + \frac{UA_H(T - T_o)}{V\rho C_p} \right] = Q_g - Q_r \quad (3.15)$$

By assuming temperatures, values for the remaining nine variables were determined [Program UTKVHA.FOR, Appendix A]. Monomer concentration was solved through an iterative procedure using equations (3.6), (3.7), (3.10) and (3.14), using an error specification of 10^{-14} for the monomer balance [eqn. (3.14)]. Heat generation [Q_g] and heat removal [Q_r] curves as functions of temperature were constructed as shown in FIGURE 3-1. Intersections indicate steady state conditions and the slope condition is evident as a necessary condition for stability. It is important to note the the Van Heerden Analysis is only valid at the steady states. This point is vividly demonstrated by the control studies of Chapter VI.

The heat generation curve is the sigmoidally-shaped curve shown in the figure. The auto-acceleration effect is evidenced by the very steep nature of this curve. The inclusion of the gel and glass effects for higher temperatures and conversions is noted by the sharp increase and subsequent decrease in the generation curve. From this graphical analysis, the middle steady state would be unstable based on the slope condition. Stability of the other steady states must be determined through an eigenvalue analysis.

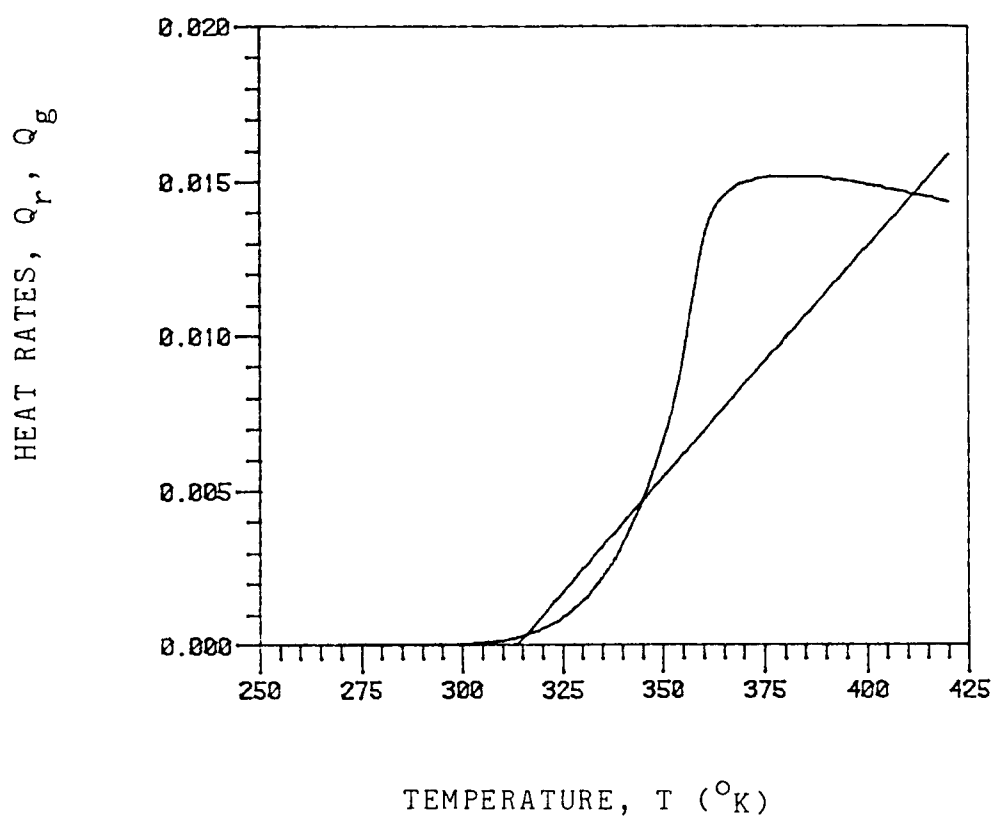


FIGURE 3-1. VAN HEERDEN DIAGRAM: STANDARD CASE

Determination of the actual steady state conditions is done, again, through the Van Heerden approach outlined above. A trial-and-error solution via subroutine of program UTKVHA.FOR is made for the temperature of the state using the five equations involved in the solution of the energy balance (T , M , I , R_1 and σ_0). When mass and energy balance error criteria [10^{-14}] are met for equations (3.14) and (3.15), all variables are then calculated. These values, as noted in TABLE 3-1 for the standard case used here, are subsequently used for further analyses. Variable numbers shown in TABLE 3-1 are consistent with the order of variables used in analyses throughout this thesis.

Eigenvalue Analysis. To determine stability of the lower and upper steady states and to verify the instability of the middle steady state, an eigenvalue analysis was done at each steady state. Thus, the local asymptotic stability of the various steady states was determined.

Using the values of the steady state conditions determined above, the coefficients of the linearized model are calculated and stored as the Jacobian matrix. These coefficients are derived by taking the partial derivatives of each nonlinear ordinary differential equation, Y_i , with respect to each state variable, X_i , such that the entries in the Jacobian matrix A are:

TABLE 3-1. STEADY STATE VALUES AND EIGENVALUES:
STANDARD CASE

		STEADY STATE		
VARIABLE		LOWER	MIDDLE	HIGH
T	1	315.9	345.1	411.6
M	2	4.721	3.598	0.4038
μ_0	3	0.9637 E-4	0.2614 E-2	0.8324 E-2
μ_1	4	0.8880 E-1	0.1217 E+1	0.4409 E+1
μ_2	5	0.1300 E+3	0.9028 E+3	0.4525 E+4
I	6	0.01052	0.007081	0.1513 E-4
σ_0	7	0.1375 E-7	0.9523 E-7	0.5837 E-6
σ_1	8	0.6938 E-5	0.2443 E-4	0.2565 E-3
σ_2	9	0.6995 E-2	0.1251 E-1	0.2252 E 0
R_1	10	0.0274 E-9	0.3738 E-9	0.1330 E-8
EIGENVALUES:				
		-0.9921 E-4	-0.9921 E-4	-0.9921 E-4
		-0.9921 E-4	-0.9921 E-4	-0.9921 E-4
		-0.9921 E-4	-0.9921 E-4	-0.9921 E-4
		-0.9345 E-4	0.2894 E-3	-0.6880 E-1
		-0.1002 E-3	-0.1108 E-3	-0.5234 E-3
			0.1681 E-4i	
		-0.1133 E-3	-0.1108 E-3	-0.2063 E-3
			-0.1681 E-4i	
		-0.1270 E+1	-0.4940 E+1	-0.1706 E+1
		-0.1270 E+1	-0.4940 E+1	-0.1706 E+1
		-0.2297 E+1	-0.8861 E+1	-0.1153 E+1
		-0.6407 E+3	-0.1267 E+4	-0.7495 E+3

$$a_{ij} = \frac{\partial Y_i}{\partial X_j} \quad (3.16)$$

This procedure was done analytically for the specific styrene polymerization system studied. Eigenvalues of this matrix are then determined by means of a package routine [Program OLDSVD.FOR, Appendix A] from the Scientific Subroutine Package (SSP). This being a very stiff system, ie. eigenvalues are very widely separated by orders of magnitude, double precision routines were employed. As a result, no eigenvectors were determined since standard routines require complex arithmetic which is unavailable on the DECsystem-10 machine used for computations.

Some of the interesting results, as noted in TABLE 3-1, from the eigenanalyses performed were:

1. verification of stiffness of the polymerization system,
2. verification of instability of the middle steady state,
3. determination of stability of upper and lower steady states, and
4. repetition of roots (eigenvalues): at each steady state investigated, there were two sets of repeated roots (two roots equal and three roots equal).

To gain some insight into the global stability of this system for the chosen set of model parameters, simulations of the nonlinear system were made around each steady state. These simulations showed that no limit cycles exist and confirmed the eigenvalue analyses. No open-loop phase plane plots or time traces are reproduced in this paper.

CHAPTER IV

SINGULAR VALUE DECOMPOSITION ANALYSES

General Background

Singular value decomposition, also referred to in this work as SVD, is a linear algebra analysis tool that is applicable to matrices describing stable linear systems. Even though singular value decomposition has been established since 1889 (by Sylvester for real square matrices), significant engineering applications have been slow to develop. In fact, there have been very few applications of singular value decomposition in the engineering area. The main interest, here, in singular value decomposition is directed toward model simplification/reduction and identification of control loops.

For very stiff systems, that is, systems with widely-separated eigenvalues, variables or combinations of variables may be seen as fast, while others are slow in the general comparison. Through a complete eigenvalue analysis, these variables or combinations may be determinable. If, for example, the macroscopic time element is of primary interest, the common procedure for handling fast variables

is to ignore their transients as noted in FIGURE 4-1 and make a quasi-steady state assumption (pseudo-steady state assumption); that is, assume that the fast variables are always in a steady state relationship with the remainder of the process variables retained as dynamic.

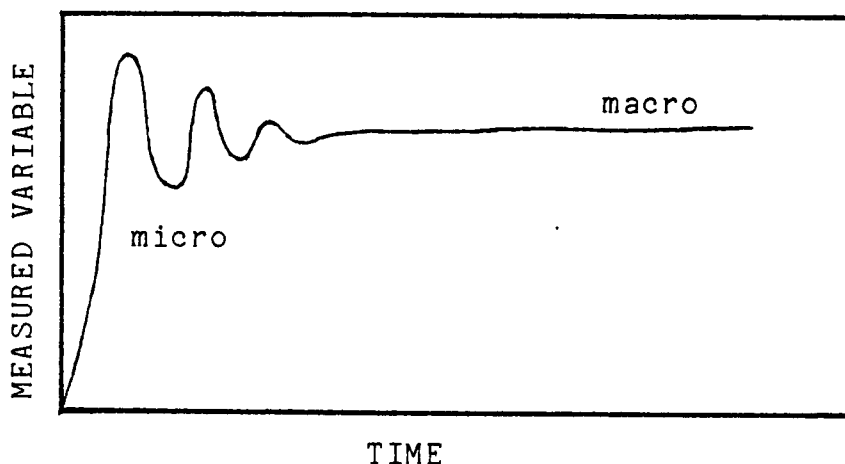


FIGURE 4-1. FAST VS. SLOW VARIABLES: TIME RELATIONSHIPS

A major stumbling block is often encountered when repeated eigenvalues exist; the interpretation of the eigenvalue analysis becomes quite difficult.

This is the basic problem associated with modal control [55], although additional transformations will often alleviate the confusion involved in modal analysis. Singular value decomposition uses a variation of eigenvalue analysis which greatly simplifies systems analysis, even in the case of repeated eigenvalues. For the particular research problem of interest, three varieties of singular

value decomposition analyses were employed to examine the steady state process, the dynamic process, and the controlled process. Before discussing each of these analyses, a brief overview of the procedure used will be presented.

Mathematical Procedure

In control theory, the linearized model of the nonlinear system is often used so that linear analysis techniques can be employed. This provides important information and insight into the dynamic behavior of the corresponding nonlinear system. The classical example is the determination of local asymptotic stability of the steady states of a nonlinear system. Thus, the linearized model of the nonlinear system is used here. This exercise results in a system described in a linear algebra form:

$$Y = AX + BP \quad (4.1)$$

where: Y vector of state variable derivatives
 X state variable vector
 P input variable vector
 A Jacobian matrix
 B matrix containing coefficients of
 model linearized with respect to P.

Now consider, for example, only an open loop system given by:

$$Y = AX. \quad (4.2)$$

Having now a simple linear algebra problem, singular value decomposition can be applied to matrix A .

In general, for any matrix D , singular value decomposition is basically an eigenvalue analysis of a transformation of the matrix D . The decomposition results in a reordered system given by:

$$D = V\Sigma U^H \quad (4.3)$$

where: Σ diagonal matrix containing singular values $\sigma_1, \sigma_2, \dots$

V matrix containing orthonormal columns (eigenvectors of DD^H)

U matrix containing orthonormal columns (eigenvectors of $D^H D$).

The values given by $\sigma_1^2, \sigma_2^2, \dots$ are the non-zero eigenvalues of $D^H D$. Columns of matrix V are known as left singular vectors of D and the columns of U are known as the right singular vectors of D . The resulting system is an orthogonal geometric representation of the original linearized model; that is, inputs and outputs are described as elliptical surfaces given by the matrices U (output) and V (input) respectively. The relative magnitudes of each vector (ie. its length) of both U and V are given by the corresponding singular values.

To digress briefly on the topic of geometric representation: the outputs of the system may be viewed as an elliptical surface where the axes of the ellipsoid are given by U . In this way, all axes are perpendicular to one another and the relative importance of each orthogonal direction (comprised of one or a combination of the original state variables) is given by the singular values corresponding to each vector. The larger the singular value is, the more significant is that particular coordinate direction. The same argument is made for the inputs of the system, with axes described by V . Moore [69] develops these concepts for a third order system, with special emphasis on the geometric analogy, and indicates the extensions to higher order problems.

The method of applying singular value decomposition is via the QR algorithm iteration scheme. Stewart [68] gives a thorough explanation of the mechanics of the QR algorithm and its use in singular value decomposition and eigenvalue analysis. The particular routine employed in this research is a Householder bidiagonalization with QR variant, a FORTRAN version of an ALGOL routine due to Golub and Reinsch [72].

This presentation is meant only as a brief introduction to singular value analysis. Stewart [68] gives a summary and additional references. Moore [69] indicates the

applications to control problems in general. He also makes some application of this analysis to the problems of controllability, observability and model reduction [70,71]. The implementation of singular value decomposition routines and the information contained in the analysis results are detailed below in terms of the styrene polymerization model.

SVD of the Jacobian Matrix

The first application of singular value decomposition to this research was directed toward the problem of model reduction/simplification. The distinction made, in this work, between model reduction and model simplification is: reduction indicates that variables are eliminated entirely, whereas simplification infers that the variables are retained, as in the case of pseudo-steady state variables. This is of particular interest since the system of equations used here are difficult and time-consuming to integrate (stiff differential equations and a 10th order model). Of initial importance is the reduction of order of the open loop system by model simplification, described as:

$$Y = AX \quad (4.2)$$

where: Y vector of state variable derivatives
 A Jacobian matrix
 X state variables vector

Singular value decomposition of the Jacobian matrix yields information about the derivatives and which internal or, in this case, state variables affect the derivatives. For example, TABLE 4-1 is a typical singular value decomposition analysis of the Jacobian matrix, this one representing the tenth order model at the unstable steady state. Each singular value is associated with its corresponding columns of matrices U and V; ie. SV(1) corresponds to the first column of both U and V. Further, each row of U represents an output variable and its contributions to the orthogonal column vectors (the first row is the contributions to the column vectors of U due to the first output variable, etc.) and, similarly, each row of V represents an input variable and its contributions to the orthogonal column vectors in V. For the analysis of the Jacobian matrix, the derivatives are the input variables and the state variables are the output variables. Thus, referring to TABLE 4-1, the first singular value SV(1), being of the largest magnitude, is indicative of the fastest derivative as given as the major component of the corresponding vector of matrix V (the seventh variable, or σ_0). In other words, for this steady state, the total number of free radicals is changing faster than any of the other state variables as the system is perturbed slightly from the steady state. This is physically consistent with the expected behavior. And, this rate of change has its

greatest effect on the fifth(μ_2) and the ninth(σ_2) state variables, as indicated by the principal components of the first column of matrix U. This analysis procedure is followed for each singular value. As an added note, should an input vector and an output vector be equivalent, it would represent an eigenvector and the corresponding singular value would also be an eigenvalue of the original matrix (for this example note SV(3) and SV(9)).

The results of singular value decomposition of the Jacobian matrix for each steady state for various order models are given in Appendix B (along with eigenvalues). These analyses indicate that, for the lower and middle steady states, there are basically four variables with significantly faster derivatives than the remaining variables, as shown by consideration of the four larger singular values. These faster variables are the four free-radical oriented terms ($\sigma_0, \sigma_1, \sigma_2$ and R_1) and are noted as the principal components of the left singular vectors (V) of the four major singular values. Those state variables affected most strongly by these fast variables are given in the right singular vectors (U) which correspond to the same singular values(T, μ_2, σ_2 and R_1). For this analysis at the upper steady state, the initiator derivative joins the other four as fast in comparison to the other state variable derivatives.

This establishes a criteria and specific numerical reasoning for determination of which variables were considered to be fast. This method of examining stiff systems is a superior approach to the intuitive "feel" used previously. Although numerically crude at this stage of development, additional research could be done to quantify the procedure further. These analyses verify the standard procedure for handling of the radical distribution moment equations, that is, quasi-steady state assumption. But, it should be noted here that, in some instances, the quasi-steady state assumption may be inappropriate, since dynamics of the fast variables may have great influence on the total system dynamics. In such cases, singular value decomposition could be used to separate fast and slow variables for integration on separate time frames.

An interesting result of this particular analysis is the changing character of the initiator derivative. In many cases, the initiator equation is handled through the quasi-steady state assumption [31]. And, in fact, one study showed no pathological differences in system dynamics when the initiator dynamics were included and when initiator dynamics were ignored [48,50]. This analysis indicates regions where the initiator dynamics should be retained for numerical reasons.

The singular value decomposition analysis of the Jacobian matrix at the steady state yielded information concerning the derivatives of the state variables. This is especially helpful in the handling of stiff problems as are often encountered in polymerization processes of this class. The option of quasi-steady state assumption is left open to the researcher, dependent upon the time frame of interest (microscopic or macroscopic) and the option of an SVD-approach to integration is also available. Next an investigation of the dynamic system is to be made.

Grammian Analyses

Generalizations. The problem of model reduction/simplification has long been studied in the field of engineering in order to obtain systems of lower order that enable analysis by simpler means. One method, continued fraction inversion, is an accepted means of handling systems described in the Laplace domain [55,73-79]. This method of model reduction is also applicable to system analysis based on time or frequency response data. The analysis procedure described here is an application of singular value decomposition for model reduction of linear systems using time domain response data.

The preceding section dealt with an analysis which yielded information concerning the open loop derivatives of the system: determination of fast and slow variables in a relative sense. But, for model reduction, the dynamic system must be investigated. This is accomplished by examining the dynamic response of the system in terms of a grammian, as defined by [69,70,71]:

$$W_{H,t_1}^2 = \int_0^{t_1} H'(t)H(t)dt \quad (4.4)$$

where: W^2 grammian
 $H(t)$ impulse response matrix
 H_{t_1} map: $R^m \rightarrow e^r[0,t_1]$

The grammian is a symmetric matrix that is positive semidefinite ($\underline{\omega}' W^2 \underline{\omega} > 0$ for all $\underline{\omega}$) and that has a unique symmetric square root $W = W'$. Since this integration could be cumbersome, and does not allow for any on-line control applications, a better method of developing the grammian is through a response matrix, comprised of response values of the output variables, at consistent time intervals, due to perturbations in each of the state variables:

$$W^2 = R'R \quad (4.5)$$

where: R $N \times n$ response matrix
 N dimension of system
 n number of samples at interval h

Using this technique, large quantities of data (accumulated on-line or through simulation) may be handled yielding the

singular value decomposition of the actual dynamic system. Additional advantages, which will not be explored in this research, for this method include the ability to examine changing singular values and vectors which would give insight into problems such as dead time.

Once the grammian is supplied, the model reduction becomes an application of decomposition to a matrix reduction problem [68-71]. Model reduction involves the elimination of those variables which do not affect the overall nature of the matrix and may be examined from a Frobenius norm approach. A major concern in a grammian analysis is the normalization of variables such that equal or appropriate weight is given each variable in the decomposition process. This aspect of singular value decomposition is not highly developed and the normalization process is, therefore, the result of experience and "feel" for the system under investigation, rather than a simple mechanical procedure. This is an area where additional theoretical results are needed. In the application of this analysis to the present problem, several normalization procedures were used to provide some insight to the effects of the normalization scheme.

Normalization. Four sets of grammian analyses were conducted on the response data collected from simulations with response values recorded as:

1. perturbation variables about the steady state of interest;
2. variables normalized with respect to the steady state of interest;
3. variables normalized with respect to the expected range of values (inlet conditions to those at the upper steady state), where conversion was taken as the normalized variable for monomer; and
4. variables normalized as in No. 3, but (M/M_0) was taken as the normalized monomer variable.

Perturbation variables proved inappropriate since the numerical magnitude of the variables was not masked, causing larger-valued variables such as temperature and the second moment of polymer distribution to appear to be of supreme importance and the remaining variables to be insignificant. This showed the need for some form of normalization. Normalization with respect to the steady state was also somewhat unsatisfactory as it tended to enhance the importance of the faster variables. Basically, this

resulted from the fast increase of the radical quantities in comparison to their steady state values. The sets of analyses conducted with the range-normalized variables seemed to give the most understandable and reliable results. These procedures allowed each variable to range from zero to unity, giving each variable an equal weight in the decomposition analysis. The latter of these tests, with monomer normalized as (M/M_0) , yielded the most reasonable information since monomer, not conversion, is taken as the state variable in this polymerization model.

Analysis and Results. Grammian analyses [Program GRAM.FOR, Appendix A] were conducted for each steady state, even though the analysis procedure has been proved for stable systems only. Response values were collected from simulations at set time intervals with initial conditions taken as perturbations of 5% away from the values for the steady state studied in all variables. These perturbations were defined in terms of the dimensional values. Various tests were made where the dynamic model was represented by five, nine and ten ordinary differential equations. The lower order models retained the remaining variables under the quasi-steady state assumption; that is, although reduced order dynamic models were used, the system grammian was still described by ten variables. Additionally, various sampling time intervals were used. A summary of runs made

is tabulated in TABLE 4-2. Singular value decomposition analyses of the grammians are located in Appendix C. In all runs given in this work, the number of samples, n , taken for the response matrix was ten.

TABLE 4-2. SUMMARY OF GRAMMIAN ANALYSIS RUNS

RUN	STEADY STATE	TIME INTERVAL	MODEL ORDER	NORMALIZATION			
				1	2	3	4
		sec.					
2	MID	0.01	10	*			
3	MID	10.0	9	*	*	*	*
5	MID	100.0	5	*	*	*	*
6	LOW	100.0	5	*	*	*	*
7	LOW	100.0	9	*	*	*	*
8	HI	100.0	5	*	*	*	*

Run No. 2 was discarded since numerical problems were encountered in simulating the single unit radical equation (instability in integration): values for R_1 began oscillating between positive and negative values. For all other runs, the quasi-steady state assumption was employed for R_1 dynamics, a seemingly reasonable assumption since this would be a fast variable of minute proportion in comparison to the other state variables. This was the only problem encountered in the simulation process. The interpretation of the analysis results is done in the same manner as was done for the analysis of the Jacobian matrix decomposition with the difference that input variables are

now state variables as well as the output variables being state variables.

The most striking element in these analyses is that only one major singular value resulted from the decompositions performed. Based on the most reasonable normalization technique (No. 4), the vector corresponding to the major singular value has significant contributions due to every variable. The radical distribution moments appear to enjoy a larger role at the upper steady state, explainable by the overproduction of free radicals at the elevated temperatures (glass effect).

Based on the grammian analyses conducted, all variables should be kept as part of the simulation model, even though decomposition of the Jacobian matrix indicates some variables are faster. This seeming contradiction can really be viewed as an explanation for the quasi-steady state assumption. One disclaimer that should be made here concerns the retention of R_1 in the full model, as indicated by the grammian analysis. It has been noted that no essential differences in analysis or simulation results can be seen for models including R_1 and for models that do not include R_1 . Although the results of these tests indicate retention in the model, it was felt that this may have stemmed from the normalization process whereby the actual magnitude of the variables is masked from the analysis

machinery. In reality, despite its importance in a reaction mechanism sense, the magnitude of R_1 makes its effect on the other variables negligible. These conflicting results cannot be justified with the numerical analysis presented here. Further investigation of this observation is beyond the scope of this work. Understanding of this apparent shortcoming would certainly provide a guide to future use of this decomposition application.

Two additional results of merit involve comparison of grammian decompositions for matrices constructed from samples of different time intervals for the same steady state. Results of grammian analyses with different time intervals were similar; further extended time frames may begin to differ as the macroscopic scale is approached. Similarly, common analysis results are given from grammians constructed from the response data of the different order dynamic models tested. This fact tends to reinforce the proposed model simplification via quasi-steady state assumption, and verifies the contention of Jaisinghani [50] that initiator dynamics do not affect system pathology (in the 5-equation model, the initiator was considered to be a pseudo-steady state variable). This theory is supported by the relatively small contributions of the initiator to the resultant vectors of the major singular value.

Through singular value decomposition of the Jacobian matrices and the grammian analyses, the complete ten-equation model describing the styrene polymerization process under investigation is not reduced. Instead, the model is simplified through the quasi-steady state assumption. The dynamics of the radical-oriented variables have been eliminated to leave a model consisting of five dynamic variables (T , M , μ_0 , μ_1 , μ_2) and five quasi-steady state variables (I , σ_0 , σ_1 , σ_2 , R_1). These results are based on analyses for the middle steady state since it represents the state around which the nonlinear control will be investigated in Chapter VI.

Input Response Analyses

An insight into the controlled process may also be gained through another application of singular value decomposition. For the controlled process described by:

$$Y = AX + BP \quad (4.1)$$

the process, at steady state, is:

$$X = -A^{-1}BP. \quad (4.6)$$

It is this new matrix defined by $(-A^{-1}B)$ that will give indications of most responsive control based on unit step changes in the control variable. Again, normalization of the control variables is of utmost importance since a step change will reflect the normalization employed.

For the styrene polymerization process examined here, the following five possible control variables were chosen as those available in an actual physical setting:

1. residence time Θ (basically an indication of flow rate);
2. inlet monomer concentration, M_0 ;
3. inlet initiator concentration, I_0 ;
4. average coolant temperature, T_c ; and
5. inlet temperature, T_0 .

These control variables were normalized with respect to the range of values to be considered as probable changes in the control parameter; the construction of the B-matrix reflected this consideration through row multiplication by the desired range for each control variable. The B-matrix was constructed from the coefficients of the linearized system of equations (linearized with respect to the control variables), evaluated at the steady state:

$$b_{ij} = \frac{\partial Y_i}{\partial P_j} \quad (4.7)$$

where: b_{ij} = i-th row, j-th column entry of B
 Y_i = i-th derivative
 P_j = j-th input variable.

Singular value decomposition analyses were conducted [Program RESVDN.FOR, Appendix A] at each steady state and normalization of control variables were such that a reasonable step change was simulated. Also, various order models were tested.

For interpretation of an input response analysis, the matrix supplied to the decomposition routine is $N \times 5$, where N is the model dimension studied and five represents the five system inputs (Θ , M_0 , I_0 , T_c , and T_0). Referring to TABLE 4-3 (Input Response Analysis of the Ninth Order Model), note there are five singular values, as indicated by the five non-zero entries, with five corresponding columns in matrices U and V . Each vector of U is comprised of nine components (dynamic state variables) and each vector of V is comprised of five components (system inputs). Scaling factors indicate the relative magnitudes of the "unit step changes" in each input to the system; for example, a unit step change in residence time Θ for this analysis is actually a change of 2000 seconds. Now, for a unit step change in all input variables, the third input (I_0) is shown as having the largest effect as given by its role as the principal component of the vector in V corresponding to the largest singular value $SV(1)$. And, as before in the other decomposition analyses, the fifth output (μ_2) is seen as the state variable most affected by the unit step inputs. This

process is carried through for each singular value. Finally, the nearly-zero singular value SV(5) indicates a repetition of input variables, as is the case for control via temperature manipulation (T_c and T_o) and can be noted also by the entries in the B-matrix.

The results of the input response decomposition analysis are given in Appendix D. For all the tests made, only four singular values are of importance, indicating a repetition of input variables. This is obviously the case for control via either T_c or T_o would yield a common control response. More importantly, though, is the indication of primary control variables (as given by the first singular value and vector). Inlet temperature (T_o), inlet initiator concentration (I_o) and residence time (θ) are shown to be primary control variables and inlet monomer concentration (M_o) is seen as the dominant secondary control variable for the case of the middle steady state. Since all of these variables play major roles in each of the singular values, it is difficult to determine precisely the single dominating control variable, if indeed one is better than the rest.

A further extension of this analysis is to examine each control variable individually to obtain a general indication as to which state variables are most affected by a step change in each control variable. Generalized results of this procedure are given in TABLE 4-4.

TABLE 4-4. INDIVIDUAL CONTROL VARIABLE TEST RESULTS

CONTROL VARIABLE	STATE VARIABLES AFFECTED		
	LOW	MID	HI
θ	μ_2	μ_2	μ_2
M_o	μ_2	μ_2	$\mu_2 - T$
I_o	μ_2	μ_2	μ_2
T_c	$\mu_2 - T$	μ_2	μ_2
T_o	$\mu_2 - T$	μ_2	μ_2

The second moment of polymer distribution is indicated as that state variable most affected by step changes in control parameters, but this quantity is hardly measurable (although it may yet be attainable through the use of a filter). Dependent upon the region of interest, inlet monomer concentration or one of the temperature parameters may prove to be adequate as manipulated variables since reactor temperature, an easily measured quantity, is seen to have strong, desirable dependence, as indicated by its role as the second most affected variable in these analyses.

Conclusions

Through various applications of singular value decomposition, the model for the styrene polymerization process has been simplified to five dynamic equations (T , M , μ , μ_1 , μ_2) and five variables resulting from pseudo-steady state assumptions (I , σ_0 , σ_1 , σ_2 , R_1). The application of

these linear algebra techniques has taken some of the guess-work out of model simplification/reduction and given some insight into the differences between these two results. Although theoretically limited to stable, linear systems, the techniques employed here, when applied to the unstable regions, yielded similar and anticipated results. The required theoretical extensions would be a fruitful area for continued research.

Some of the important uses of singular value decomposition are listed here:

1. Jacobian matrix analysis yields information of system derivatives and the state variables affected by changes in those derivatives;
2. grammian analysis highlights dynamic situations by giving information on the relative importance of the dynamic variables for the time frames desired; and
3. input response analysis indicates possible control strategies based on the relative response values and vectors resultant from step changes in the control parameters.

As a result, singular value decomposition is an area of analysis relatively new in the field of engineering and

offers interesting possibilities for new applications:

1. new technique for handling of stiff differential equations;
2. improvement and advantage over modal control analysis;
3. on-line analysis directed toward multivariable control problems; and
4. decoupling in multivariable control problems.

CHAPTER V

STYRENE POLYMERIZATION MODELS

Introduction and Generalizations

In the development of the reaction system model used in this research, it became evident that the free-radical polymerization of styrene had been the subject of much published research. Consequently, many approaches to the modeling of the process have been used, often tailoring the modeling efforts to suit the specific needs and goals of the study undertaken. Studies of reaction dynamics would required a more simplified model than those studies concerned with the resultant polymer properties, since polymer distribution moments have no dynamic effect on the polymerization process.

Similarly, mathematical studies have oftentimes been conducted in terms of dimensionless variables to obtain more generalized solutions, as compared to those conducted in association with experimental results, where the modeling has been left in dimensioned form as a point of correlation. Other differences in modeling include: isothermal vs. nonisothermal studies, bulk vs. solution polymerization, compensation for volumetric changes, and correlations for

properties (density, heat capacity, gel effect and glass effect).

This chapter is meant to direct attention to a few of the other modeling efforts found in the literature and to point out some of the similarities and differences encountered.

Comparison of Modeling

The standard approach to modeling is by writing species material balances and an energy balance (if dealing with a nonisothermal case). In the case of a polymerization process, this procedure results in an infinite series of equations for free radical and polymer species of varying chain length. Application of moments of distributions of free radical and polymer reduce this infinite series of equations to a finite set, generally given by three moments of distribution of free radical and three moments of distribution of polymer.

Laurence and Vasudevan [19] conducted a study on the time-averaged effects on molecular weight distributions of very slow oscillations of the feed concentrations of monomer and initiator. Their model was that of an isothermal CSTR described by eight equations (moment equations, monomer and initiator equations). The variables were normalized with respect to their steady state values and dimensionless

equations were subsequently derived. The system under study was the solution polymerization (benzene as solvent) of styrene, as described kinetically by initiator decomposition, propagation and termination mechanisms.

Hamielec, et al., [43-46] presented a series of articles on polymer properties and molecular weight distributions concerning free-radical polymerization in batch reactors, CSTRs, and various configurations of CSTRs. Again, solution polymerization (benzene as solvent) of styrene was studied, but a correction for solvent effects was included for the transfer and termination reactions. No correction, however, was made for thermally-induced polymerization, and, although viscosity effects were evident in their experimental work, they were not accounted for in the model. Pseudo-steady state assumptions were made for handling radical distribution moments.

In a later paper, Hui and Hamielec [47] explored the problems of gel and glass effects for thermally-induced bulk polymerization of styrene. Their model, for this study, ignored initiation and transfer reactions, employed the method of moments to reduce the number of equations involved, and was simplified through quasi-steady state assumptions applied to free radical moments of distribution. Also included in this model were compensations for volumetric changes. The result of their work was a

correlation involving the propagation and termination reaction rate constants to compensate for gel and glass effects encountered at high temperatures and conversions.

In an earlier study of control of addition polymerization reactors, Warden and Amundson [35] developed a model for a nonisothermal CSTR. Their model was simplified to only three equations since their major concern was the reaction dynamics and control of these dynamics. Reduction to only three equations maintained the desired integrity of the model while allowing them to apply more easily the Routh-Hurwitz criteria for stability to their control study.

Spitz, et al., [20] investigated the bulk free radical polymerization of styrene initiated by AIBN in an experimental study. Their modeling efforts were focused on the comparison of theoretical prediction and experimental results of open loop on-off periodic control of inlet initiator concentration. Their model [20,21,22] consisted of nine equations written in dimensioned form, where the following applied:

1. pseudo-steady state assumption for moments of radical distribution;

2. compensation for initiator cage effect; and
3. gel and glass effects through correlations due to [47].

For the nonisothermal portion of their study, variation of heat capacity was considered as a function of polymer chain length.

In a more recent paper by Jaisinghani and Ray [48], reactor dynamics of free radical polymerization were studied. Their model, since polymer properties were inconsequential, consisted only of four equations (initiator, monomer, temperature and zeroeth moment of radical distribution). Further simplification resulted from the quasi-steady state assumption applied to the radical moment equation. In order to examine the process more generally, the remaining equations were made dimensionless. Other features of their model include a constant heat capacity and a heat of reaction for only the propagation reaction. Thermally-initiated polymerization was ignored.

Probably the most significant difference in this model is the change in the correlation for the gel and glass effects. Since their study employed the use of bifurcation theory to test for limit cycles, the data used by Hui and Hamielec [47] was refit to another mathematical correlation

to simplify the differentiation demanded by the analysis technique. Although the correlation is intended to yield a similar compensatory effect, for the polystyrene system examined, this did not seem to be the case as noted in FIGURE 5-1.

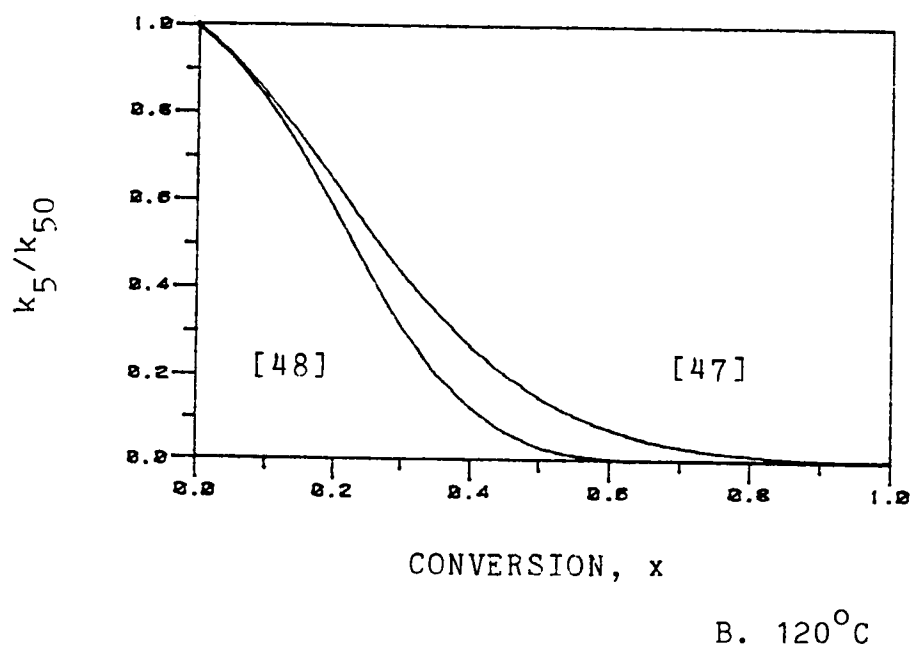
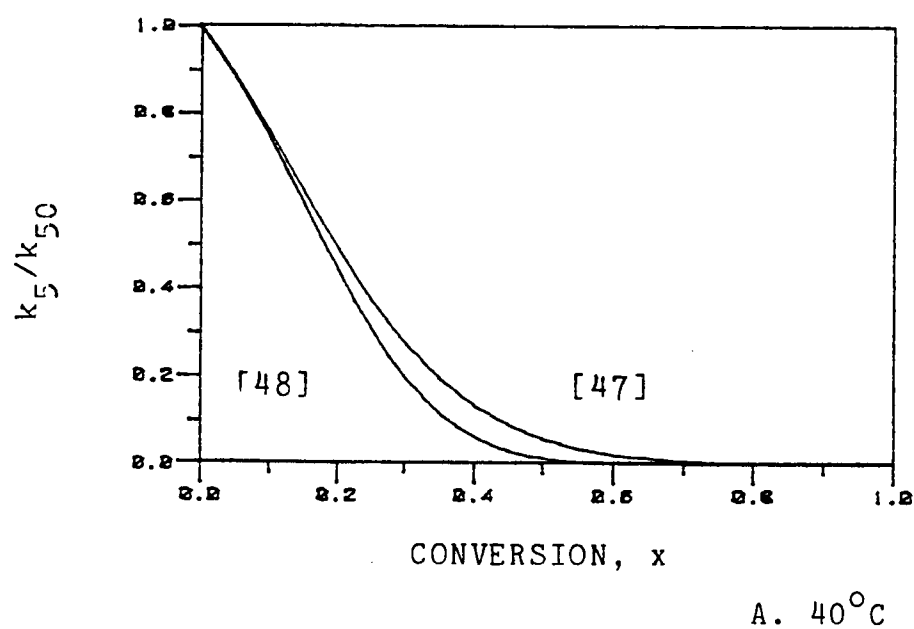


FIGURE 5-1. COMPARISON OF CORRELATIONS

Understandably, variations are noted in the simulation results, as seen by the temperature-time traces of FIGURE 5-2.

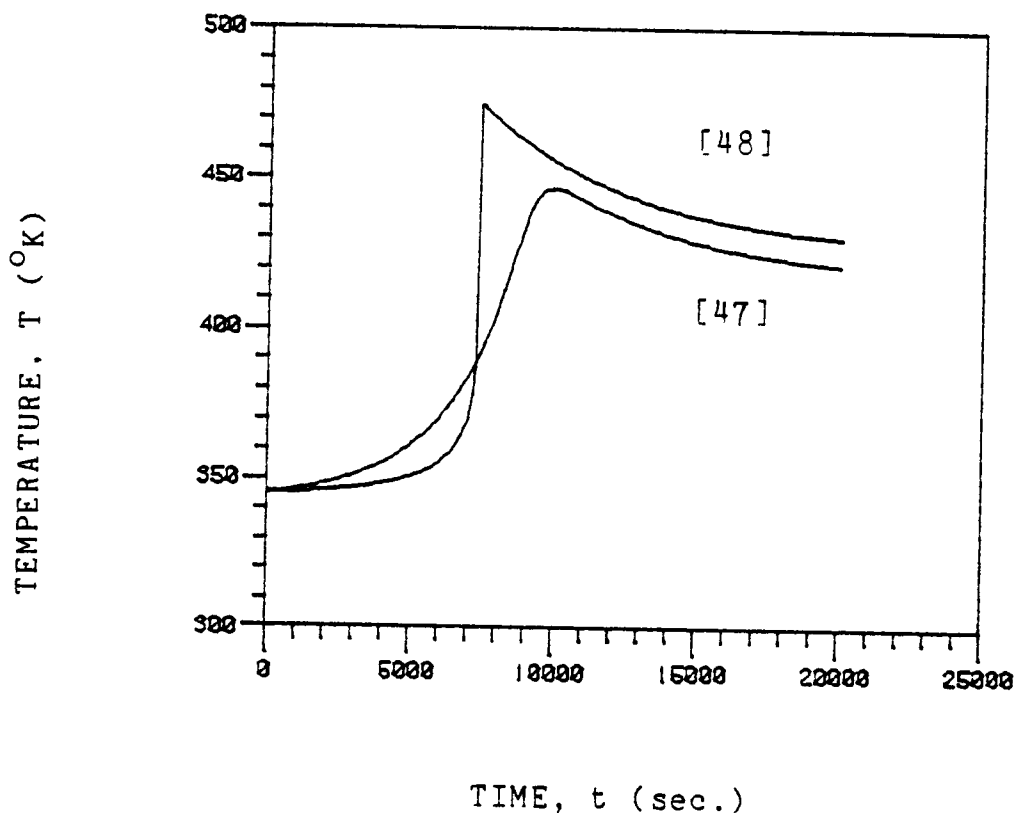


FIGURE 5-2. COMPARISON OF MODELS: SIMULATION

Even with these differences, however, the same reactor pathology is maintained for both correlations. Since reactor dynamics only were of interest, their work included some interesting studies of the influence of initiator dynamics. Again, they saw no pathological changes in the overall reactor dynamics due to initiator dynamics (included

or ignored).

Summary

All models investigated were developed in similar manners, but some of the major differences have been outlined. A greater majority of differences in models results from the intent of the specific research. All models applied the pseudo-steady state assumption to some extent (depending upon the study) for simplification, although none had concrete reasoning for this assumption. Prior studies have relied on intuitive reasoning for this simplification, whereas this work has presented a quantitative approach through singular value decomposition. No other models included a single unit free radical equation or variable although many used it as a starting point in their model development. Retention of the R_1 equation for this study has been explained earlier.

Other features included and neglected in this model are:

1. no compensation for solvent as in solution polymerization;
2. consideration of thermal initiation (monomer decomposition) to free radicals;

3. constant heat capacity and density;
4. consideration of heats of reaction for thermal initiation, propagation and transfer reactions;
5. compensation for gel and glass effects through the correlation due to Hui and Hamielec [47]; and
6. compensation for the cage effect of the initiator, as given by Spitz, et al., [20,22].

CHAPTER VI

THE CONTROL PROBLEM

General Introduction

The desirability of process operation at or near an unstable steady state has given way to designs of control systems to meet this need. Conventional linear feedback control systems are directed toward maintaining the unstable steady state conditions. In some cases, this conventional approach may prove difficult to implement or, for other reasons, an alternative concept may be desired. One such approach [23-25,27,28,62] will be examined here as it is applied to the styrene polymerization CSTR under investigation.

A thorough and rigorous development of the design procedures will not be presented as these may be found elsewhere [23,28,65]. Instead, an intuitive description of the nonlinear feedback control strategy will be given along with an "applied" approach to the nonlinear control element (relay) design. To initiate the study of the relay control scheme for a specified control loop (having chosen the measured and manipulated variables), the effects of the change in the manipulated variable on the process steady

state behavior was studied through Van Heerden diagrams. This showed how the generation and removal characteristics were modified due to changes in the manipulated input. It also provided some "feel" for the suitability of the linearization of the process as required by the current analysis and design procedures, especially in terms of the manipulated variable.

Then the nonlinear control element for the nonlinear system is formally analyzed by applying Tsytkin's method to the linearized model. This design method yields both amplitude and period of the resultant cyclic solution of the controlled process.

The control objective of this section is the illustration that a nonlinear feedback control element (relay) may be applied successfully to the AIBN-initiated styrene polymerization carried out in a CSTR. In order to force this part of the research to remain within reasonable bounds for this thesis, the following constraints were placed on the study:

1. Of the many new and intriguing results and characteristics in behavior not reported in other studies of nonlinear control for unstable reactor operation, only a selected few were investigated in detail.

2. Stability analysis of the predicted periodic solutions was not carried out.
3. No attempts were made to examine the effects of the implemented control strategy on the various properties of the polymer product.

Many of the details leading to the results, trends, and conclusions reported in this portion of the thesis are given in Applied Control Laboratories Report Number 7903 [85].

Tsyarkin's Analysis

When the nonlinear feedback control element under consideration is a relay, an analysis procedure set forth by Tsyarkin allows treatment of the control element exactly [23,65,83]. Basically there are two sets of conditions which must be satisfied in this procedure:

1. the switching conditions, which yield the predicted frequency Ω_0 of the periodic solution, and
2. the continuity condition, which requires checking the waveform, and thus, gives the anticipated amplitude of the resulting oscillation.

The switching conditions are necessary conditions for an oscillation, while the switching conditions and the

continuity conditions taken together constitute necessary and sufficient conditions for an oscillation.

Bruns [23] presents the switching and continuity conditions for a symmetric relay with hysteresis (memory), as shown in FIGURE 6-1, for the case where the relay is in a negative feedback loop. These conditions are rewritten here for the same relay considered in a positive feedback loop, where time zero is taken as a time when the relay changes to a positive drive level. The switching conditions are:

$$\text{Passive: } x(n\tau_0^-) = -\delta \quad \dot{x}(n\tau_0^-) < 0 \quad (6.1a)$$

$$x((n+1)\tau_0^-) = \delta \quad \dot{x}((n+1)\tau_0^-) > 0$$

$$\text{Active: } x(n\tau_0^-) = \delta \quad \dot{x}(n\tau_0^-) > 0 \quad (6.1b)$$

$$x((n+1)\tau_0^-) = -\delta \quad \dot{x}((n+1)\tau_0^-) < 0$$

and the continuity conditions are:

$$\text{Passive: } x(t) < \delta \quad n\tau_0 \leq t < (n+1)\tau_0 \quad (6.2a)$$

$$x(t) > -\delta \quad n\tau_0 \leq t < (n+1)\tau_0$$

$$\text{Active: } x(t) > -\delta \quad n\tau_0 \leq t < (n+1)\tau_0 \quad (6.2b)$$

$$x(t) < \delta \quad n\tau_0 \leq t < (n+1)\tau_0$$

where: $\tau_0^- = \lim_{\epsilon \rightarrow 0} (\tau_0 - \epsilon)$ = time of switch to D^+

δ = half-bandwidth, deviation from reference

x = independent controlled variable

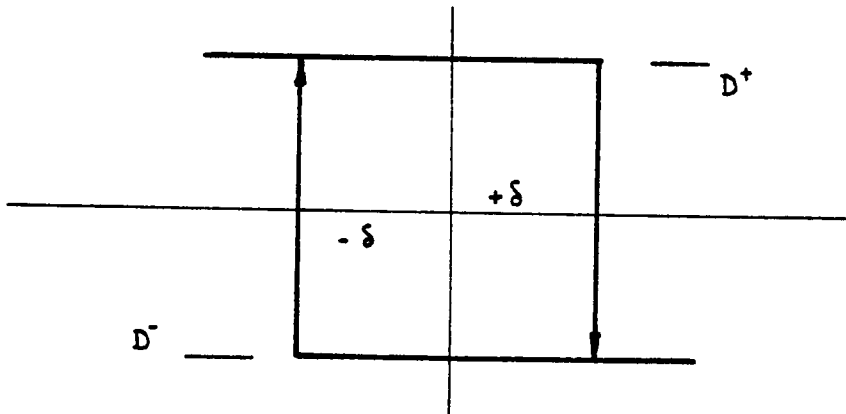


FIGURE 6-1. ACTIVE RELAY WITH HYSTERESIS.

To analyze the switching conditions, a Tsytkin's locus $T(j\Omega_0)$ is constructed in the complex plane by considering all values of Ω_0 for the Tsytkin function according to:

$$T(j\Omega_0) = \frac{-1}{\Omega_0} \dot{x} \left[\frac{\pi^-}{\Omega_0} \right] - jx \left[\frac{\pi^-}{\Omega_0} \right] \quad (6.3)$$

$$\text{or: } T(j\Omega_0) = \frac{4D}{\pi} \sum \left[\text{Re } G_1(jk\Omega_0) + j \frac{1}{k} \text{Im } G_1(jk\Omega_0) \right] \quad (6.4)$$

Thus the switching conditions may be rewritten to yield the following form for a relay considered in a positive feedback sense:

$$\text{Passive: } \text{Im}[T(j\Omega_0)] = \sum_k \frac{1}{k} \text{Im}[G_1(jk\Omega_0)] = \frac{\pi}{4} [G_S(\infty) + \frac{\delta}{D}] \quad (6.5)$$

$$\text{Re}[T(j\Omega_0)] = \sum_k \text{Re}[G_1(jk\Omega_0)] > \frac{\pi}{4\Omega_0} \lim_{s \rightarrow \infty} sG_1(s) \quad (6.6)$$

$$\text{Active: } \text{Im}[T(j\Omega_0)] = \sum_k \frac{1}{k} \text{Im}[G_1(jk\Omega_0)] = \frac{\pi}{4} [G_S(\infty) - \frac{\delta}{D}] \quad (6.7)$$

$$\text{Re}[T(j\Omega_0)] = \sum_k \text{Re}[G_1(jk\Omega_0)] < \frac{\pi}{4\Omega_0} \lim_{s \rightarrow \infty} sG_1(s) \quad (6.8)$$

To simplify handling of these series summations, some closed forms have been provided by Gelb and VanderVelde [83]. Armed with these closed forms of summations, Tsypkin's analysis becomes a cookbook procedure that can be applied to any linear process described as a partial fraction expansion in the Laplace domain. For a given bandwidth 2δ and drive level D , a frequency of oscillation Ω_0 is sought using the switching condition on the variable (eqn. 6.5 or eqn. 6.7). All real positive solutions that are found are candidate solutions. Any candidate frequency Ω_0 is then tested for the switching condition of the derivative (eqn. 6.6 or eqn. 6.8).

Finally, for the solution to satisfy necessary and sufficient conditions and, thus, be a valid solution, the continuity conditions must be met. Again, the expressions for the waveform are written in terms of infinite series involving the process transfer function, with Gelb and VanderVelde providing the required closed forms to reduce the generation of the waveform to a numerical procedure.

Polymerization Process

Since this direct approach to Tsypkin's analysis was taken, it became necessary to examine the problem of obtaining transfer functions for the various control strategies under investigation, as well as allowing the

flexibility of examining different order models of the process. Due to the multiple input-multiple output nature of the system, the solution was approached by developing a generalized numerical package. Note that, for the tenth order model with five possible manipulated variables, fifty transfer functions would be needed to describe the reactor fully. Further, such a package would facilitate analysis of simplified models as well as being a general tool in the analysis of other systems.

A subroutine package due to Melsa and Jones [80] was revised by Stelling [84] to allow for the construction of the resolvent matrix Φ , based on the input Jacobian matrix A , where:

$$\Phi = \text{adj}(sI - A) \quad (6.9)$$

and each element ϕ_{ij} of Φ is a polynomial which represents the numerator of the open loop transfer function. Cross-multiplication of the resolvent matrix with the input coefficient matrix B , as given by (4.7), yields the numerator of the closed loop transfer function for each of the fifty possible control strategies.

The denominator of the transfer function is given as the product of the eigenvalue terms, given by $(s-\lambda_1)(s-\lambda_2)\cdots$; thus, the partial fraction expansion of the desired loop transfer function is derived through another subroutine package from Melsa and Jones [80], as

modified for this work by Stelling [84]. Again, since this is all done numerically, it becomes a simple process to examine any of the feasible control schemes for the considered process.

Applied Tsyarkin's Analysis

For the purpose of this initial study, five control loops were surveyed with regard to Tsyarkin's design procedure:

1. second moment of polymer distribution controlled by flow rate manipulation (residence time), $D=2000$ seconds;
2. second moment of polymer distribution controlled by manipulation of average coolant temperature, $D=20^{\circ}\text{K}$;
3. second moment of polymer distribution controlled by manipulation of inlet initiator concentration, $D=0.01$ and $.004$ moles/liter;
4. reactor temperature maintained through inlet monomer concentration manipulation, $D=1.5$ moles/liter; and

5. monomer concentration controlled by manipulation of inlet monomer concentration, $D=1.5$ moles/liter.

Singular value decomposition involved in input response analyses indicated control of the second moment of polymer distribution and of reactor temperature. Control of monomer concentration was also indicated as the most probable secondary control variable. These particular control strategies and drive levels were chosen due to the seeming linearity of the system with regard to the control variables as given by the Van Heerden analysis. Tsyppkin's analysis was conducted for these loops using the fifth order model and simulation verification was also done using the fifth order model.

Based on the results of the input response analyses conducted using singular value decomposition, control of the second moment of polymer distribution was tested (cases 1, 2, and 3). Only Tsyppkin's analysis was performed on these loops with some interesting results. For Case 1, the acceptable ranges for half-bandwidths given by the switching conditions was $10 \leq \delta \leq 125$, with corresponding oscillation periods of 1164-32442 seconds. The lower frequency oscillations exhibited increasingly nonlinear behavior.

For Case 3, where average coolant temperature with a drive level of 20°K was used to control the second moment of polymer distribution, Tsypkin's analysis indicated that the desired relay should be a passive relay (positive feedback sense); this is contrary to that which would be anticipated from the Van Heerden diagram. An important concept is emphasized by this revelation; that is, for higher order systems (strictly for any system other than first order [25]), the Van Heerden approach will only yield information about the steady states and not give reliable insight into the dynamics involved. This same phenomenon would be expected in the use of phase plane analysis where dynamics up to only second order are correctly represented [24]. Thus the approach using Tsypkin's analysis is the appropriate analysis to implement in predicting the system's dynamic response and relay design. Here it should be pointed out that the limiting factor is the use of the linearized model.

Case 3 provided further unexpected results as Tsypkin's analysis predicted that, for the chosen drive levels, there were no relay designs, active or passive, which lead to oscillatory behavior. Solutions were found for Ω_0 according to the switching condition of the variable, but these solutions failed the derivative test.

The specific control loop indicated by the input response analyses discussed in Chapter IV was control of the second moment of polymer distribution by inlet initiator concentration. For inlet initiator drive levels that would provide multiple steady states, no solutions corresponding to realistic bandwidths solutions were determined that would provide a stable periodic solution. But, as the drive level was increased to the point that only a unique steady state existed for at least one drive level, some rather interesting results were found: for a small region of narrow half-bandwidths ($0 < \delta < 8$), two solutions for the frequency of oscillation were found. This phenomenon has not been reported in previous applications of this kind and immediately raises the intriguing question of stability of oscillation for the two cases. Further investigation into the control problem exhibited here is obviously indicated, and could be aided somewhat by results given by Spitz, et al., [20,22] in their studies involving forced periodic control. Since this interesting phenomenon falls outside the central scope of this thesis, the suggested studies will be left for future research.

Controlling reactor temperature by manipulating inlet monomer concentration at a drive level of $D=1.5$ moles/liter proved to give stable control for $\delta_{\max} = 12^\circ\text{K}$ using an active relay element (positive feedback loop). For this

Case 4, simulation of the nonlinear equations was also implemented. This procedure would normally be the final step in all detailed designs. This simulation showed the bandwidth was further restricted when applying the relay control to the nonlinear system; $\delta_{\max}$ was reduced to a value of about 9°K . It should be noted that the resulting stable oscillation for the nonlinear system for $\delta=5$, as shown by the simulation in FIGURE 6-2, is very much first order in character; this phenomenon can be explained by:

1. five variables are taken as pseudo-steady state variables;
2. moments of polymer distribution do not enter into monomer or temperature dynamics; and
3. monomer concentration for stable oscillations is, in essence, at steady state.

Period and total amplitude of the resulting oscillations as predicted by Tsytkin's analysis were verified by the simulation results as being quite good and are indicated in TABLE 6-1.

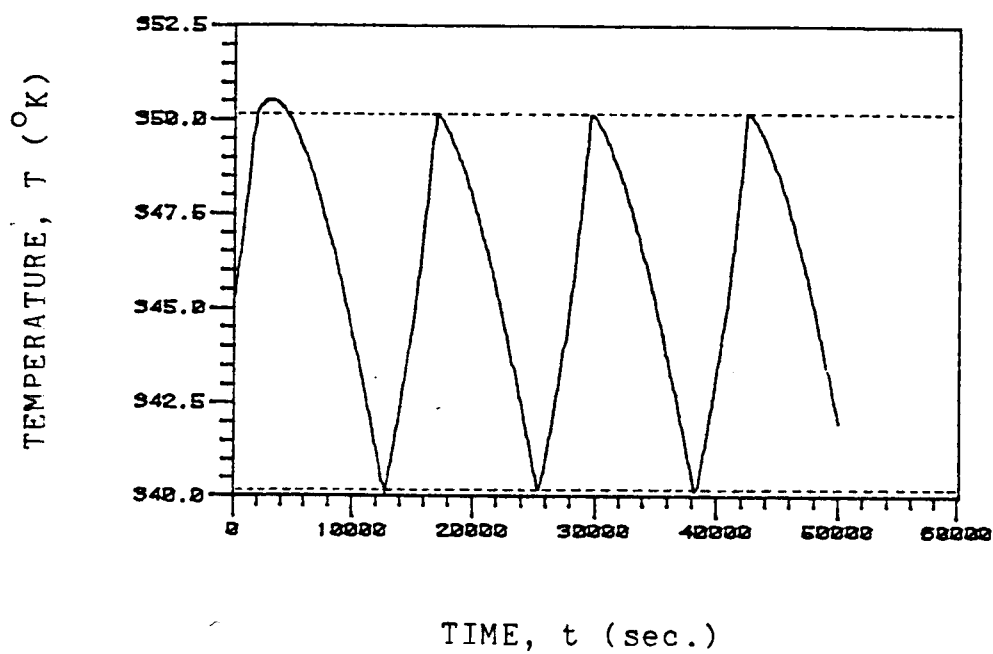


FIGURE 6-2. ACTIVE RELAY CONTROL: CASE 4 ($D = 1.5$, $\delta = 5.$)

TABLE 6-1. COMPARISON OF SIMULATION AND TSYPKIN RESULTS
FOR CASE 4: $D = 1.5$

	BANDWIDTH	TSYPKIN	SIMULATION
PERIOD, sec.	5	13004	12803
	9	29970	35570
AMPLITUDE	5	10	10
	9	18	20.9

As the bandwidth was increased to its maximum value of 18°C , the character of the resulting oscillation drifted from that of first order exhibited for a bandwidth of 10°C ($\delta=5.$). An overshoot of almost 3°C occurred at the upper switching level with none seen at the lower switching level for this maximum bandwidth.

One of the more interesting cases examined was Case 5, control of monomer concentration by inlet monomer concentration. A passive relay (positive feedback loop) was indicated for implementation through the Van Heerden approach; this is reversed from control relays for the other state variables since monomer is the one function that decreases with increasing temperature. When applied in the Tsytkin analysis design, the passive relay surprisingly would not satisfy any of the switching conditions. This

again illustrates the absence of dynamic information in the Van Heerden diagram. Normally, the limiting case for relay design is $\delta = 0$, or the case of the "ideal" relay. This case also failed to meet the switching criteria.

Upon closer examination of this unique problem, it was noticed that, beginning at the unstable steady state, if a step increase of inlet monomer concentration was made, the reactor monomer concentration would initially increase, then decrease as the reactor temperature would rise rapidly. Conversely, if a step decrease in inlet monomer concentration was made, reactor monomer concentration would initially decrease. This phenomenon is sometimes called wrong way behavior and has been noted in other processes. Wrong way behavior presents special problems in the design of process control systems. This situation of wrong way behavior is dramatically illustrated in FIGURE 6-3.

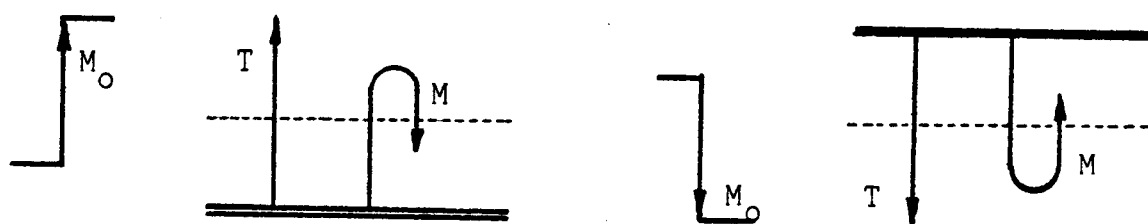


FIGURE 6-3. RESPONSE TO STEP CHANGES IN INLET MONOMER

The linearized system used for Tsympkin's design also demonstrated the wrong way behavior seen in the nonlinear simulations, reinforcing the contention that control design for higher order systems cannot be done through the Van

Heerden diagram. Thus, based on Tsytkin results, an active relay (positive feedback loop) was employed for Case 5. This turnabout from the design implied by the Van Heerden approach to the design given by Tsytkin's analysis can be noted by studying the changing character of the relay from passive to active as shown in FIGURE 6-4.

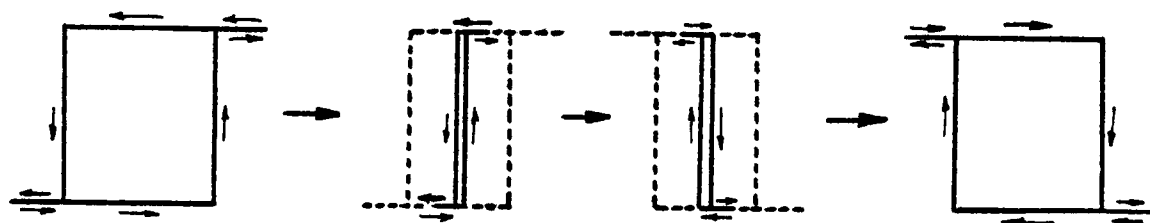


FIGURE 6-4. PASSIVE TO ACTIVE CHARACTER OF RELAY

Basing a Tsytkin design on controlling monomer concentration using inlet monomer concentration with the active relay gave still further interesting results. Solutions were found for frequency of oscillation, based on the switching condition on the variable, that did not satisfy the switching condition on the derivative. This case is an example of the problems arising when discontinuities in the derivative are encountered, and can be noted mathematically by the finite value taken by $\lim_{s \rightarrow \infty} sG_1(s)$. It is more easily recognised intuitively from FIGURE 6-3:

1. values falling within the indicated gap would satisfy the switching condition of the variable;
and

2. of each pair of values within the gap, only one value has the proper sign on the derivative to satisfy that switching condition.

So, under "normal" conditions, the frequency of oscillation given by Tsytkin's analysis is expected to be greater than that attainable through simulation due to nonlinearities. But, in this case, before simulation is attempted, the range of allowable frequencies is reduced due to the switching criteria on the derivative. This range is noted in TABLE 6-2.

TABLE 6-2. ILLUSTRATION OF FREQUENCY LIMITATION DUE TO SWITCHING CRITERIA OF TSYTKIN'S ANALYSIS FOR CASE 5: $D = 1.5$

BANDWIDTH	PERIOD	$\text{RE}[T(j\omega_0)]$	$\frac{\pi}{4\omega_0} \lim_{s \rightarrow \infty} sG_1(s)$	CHECKS
0.10	1200	0.0054	< 0.033	*
0.25	3030	0.0333	< 0.084	*
0.50	6333	0.1308	< 0.176	*
1.00	20667	0.7545	> 0.574	
1.06	36370	1.3984	> 1.016	

The nonlinear simulation of Case 5, as shown in FIGURE 6-5, indicates that control is lost for this strategy due to the

extreme asymmetry of the system. The process is far more temperature-dependent than it is dependent upon monomer concentration. As seen in FIGURE 6-5, temperature increased with time, finally reacting monomer at a rate fast enough to force loss of control based on the monomer concentration. The stable oscillations indicated by Knorr [49] for the open loop forced oscillation situation are for the isothermal CSTR. Based on these discoveries, control of the reactor temperature yielded the better control (Case 4).

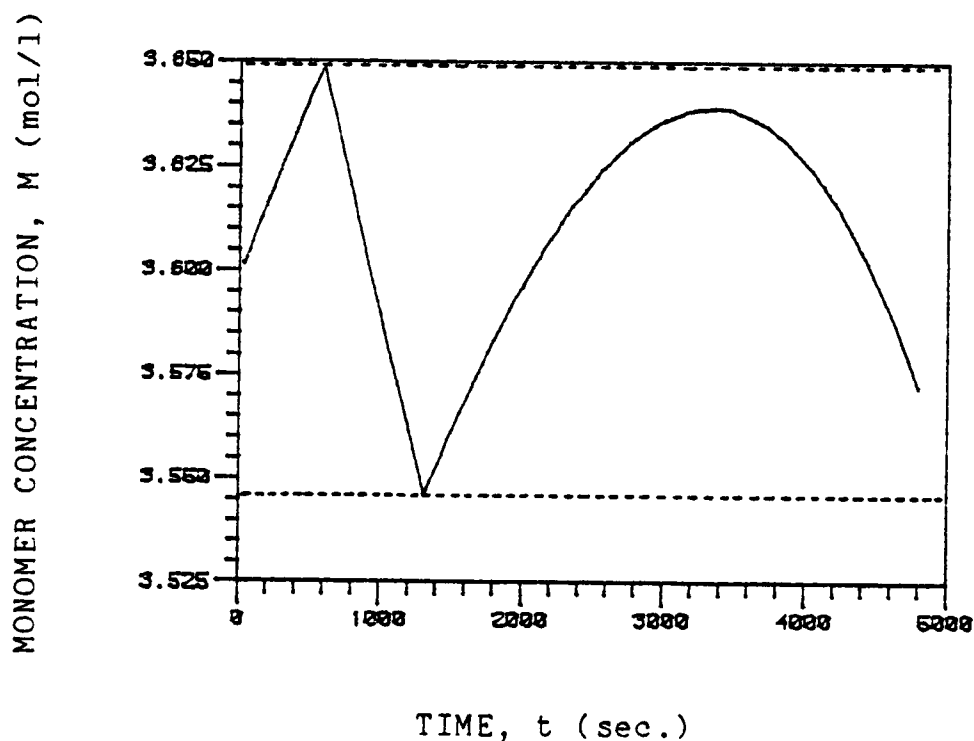


FIGURE 6-5. ILLUSTRATION OF CASE 5 CONTROL
USING AN ACTIVE RELAY: $D=1.5$, $\delta=0.05$

Conclusions

Based on these initial investigations, the following important conclusions were drawn.

1. Relay control is applicable to the AIBN-initiated styrene polymerization process modeled.
2. Relay design for higher order systems must be done using Tsytkin's analysis since the Van Heerden and phase plane approaches do not give any indication of the actual dynamic behavior.
3. Longer period-borderline case studies (such as Case 4, $D=1.5$, $\delta=9$.) showed an overshoot at the upper switching level, resulting from the combination of the longer period of oscillation, wider bandwidth, and the highly exothermic nature of the polymerization process.
4. Although Tsytkin's analysis may indicate a reasonable stable oscillation the nonlinear simulations could well prove that the actual stable oscillations possible are for unrealistic bandwidths.
5. For the nonisothermal CSTR under control of monomer concentration by inlet monomer concentration manipulation, the stability of the oscillations

predicted by Tsypkin's analysis was not tested, but, based on the nonlinear simulations attempted, these oscillations were unstable.

Out of this survey there are indicated other avenues that should be investigated:

1. control based on inlet initiator concentration;
2. control of various polymer properties, either as state variables or calculated variables; and
3. time-averaged effects of relay control on the various polymer properties.

CHAPTER VII

RECOMMENDATIONS FOR FUTURE STUDY

There are many areas that could be explored using this present work as a base. Quite a large number of difficulties were encountered due to the ill-conditioning of the system, that is, due to the widely spread range in magnitudes of values for all the variables used. This problem is particularly evident from the condition numbers for the various order models, as given in TABLE 7-1. The condition number of a matrix is merely the largest singular value divided by the smallest singular value, with a condition number of unity representative of a singular matrix. To further investigate this styrene polymerization model, as a complete model of ten dynamic equations, normalization of state variables to dimensionless form is indicated.

TABLE 7-1. CONDITION NUMBERS FOR MODELS

MODEL ORDER	CONDITION NUMBER
2	1.886 E02
5	3.851 E04
6	4.762 E08
7	1.805 E14
9	1.666 E11
10	1.113 E15

Further refinements to the styrene polymerization model employed in this study could be made to better represent the process over a large region of operating conditions. More specifically, correlations for the changing nature of the density and the heat capacity could be included, as well as adding the influence of the solvent in the solution polymerization process. Also much remains to be done in the way of examining the various models presented in the literature; simulations could indicate differences not readily detected in the survey approach used in this thesis.

A large amount of research is open to investigation in the engineering applications area of singular value decomposition. For the system investigated, the conflicting

results concerning the use of the single unit radical in the model should be studied further. This could, perhaps, best be accomplished through the normalization techniques employed. Following this line of study, a quantitative guideline for normalization could well be developed, possibly involving time scaling employed in the grammian analyses. The same techniques applied in this study could be applied to other systems of interest. In order to apply these techniques to unstable processes, the required theory needs to be formalized. The analysis tool could be modified to allow an effective method of integrating the stiff differential equations used here, or for any system of stiff equations. And, singular value decomposition could easily be applied in other process control areas, such as decoupling problems and on-line analysis directed toward multivariable control.

Some of the unexpected, and previously unreported, results found in this research deserve further investigation:

1. multiple solutions for the pushing control example of polymer properties controlled by inlet initiator concentration;

2. asymmetry of resultant oscillations and comparison to predictions by Tsytkin's analysis; and
3. wrong way behavior noted in the case of monomer controlled through inlet monomer concentration manipulation.

Specific to the nonlinear control problem addressed in this research, the most promising new area of investigation would be in the application of nonsymmetric relays (unequal bandwidths, unequal drive levels, or a combination of these features) to the feedback control system. Since there are many severe nonlinearities encountered in this system, especially near the unstable steady state, nonsymmetric relays could provide some compensation for these effects and allow better control. This idea should be included in the analysis of the effects of relay control on the time-averaged polymer properties. Finally, since this research represents merely a mathematical study, the ideas investigated should be experimentally verified.

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LIST OF REFERENCES

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APPENDICES

APPENDIX A

FORTRAN PROGRAMMING

FORTRAN compiler listings for the following programs are given in this appendix:

1. UTKVHA.FOR - Van Heerden analysis and steady state solutions;
2. OLDSVD.FOR - eigenvalue analysis and SVD of the Jacobian matrix;
3. GRAM.FOR - grammian analysis of the dynamic system by SVD; and
4. RESVDN.FOR - analysis of input responses for full and simplified models.

Eigenvalues found using OLDSVD.FOR were determined by means of matrix routines from the Scientific Subroutine Package (SSP) supplied by the International Business Machines Corporation. Singular value decomposition was done using the FORTRAN version of an ALGOL routine by Golub and Reinsch [72].

Simulations of the nonlinear system of equations were done using a variable step size, variable order Adams-Moulton predictor-corrector routine. Also tested was a Gear method, specifically applicable to systems of stiff ordinary differential equations. The routine used was subroutine DVOGER from the International Mathematical and Statistical Libraries, Inc.

```

MAIN.      UTKVMA-FOU      FORTRAN V.5A(621) /KI      19-SEP-79      10100      PAGE 1

00001      C      PROGRAM FOR STEADY STATE VALUES VS TEMPERATURE
00002      C      TO EXAMINE THE EFFECTS OF VARIOUS 'CONTROLLABLE'
00003      C      PARAMETERS ON THE 'STABILITY' OF THE SYSTEM...
00004      C
00005      C      PGM BY JOHN STELLING III.....REV./06.04.79
00006      C
00007      C.....
00008      C      IMPLICIT REAL*8 (A-H,O-Z)
00009      C.....
00010      REAL*8 H,M1,M10,MOLD,MBAL,MPRE
00011      REAL TI,OGI,GRI,M1,P2
00012      REAL*8 IFILE,JFILE,SFILE
00013      COMMON/AREA1/R,CAGE,M10,RKO(S),RK(S),EN(S),CONV
00014      COMMON/AREA2/DH(S),DHO(S),RI,TREF,TI
00015      COMMON/AREAS/DHO,IT,TC,GV,UAV,RHOCP,V2,CP,CI,ERROR
00016      C.....
00017      WRITE(5,10001)
00018      1000  FORMAT( 3X,'VAN HEERDEN DATA OUTPUT FILE NAME: ',S)
00019      READ(5,1500)IFILE
00020      1500  FORMAT( A10)
00021      WRITE(5,16001)
00022      1600  FORMAT( 3X,'STEADY STATE RESULTS TO LINE PRINTER: ',S)
00023      READ(5,1500)SFILE
00024      2000  WRITE(5,20001)
00025      2000  FORMAT( 3X,'PLOTTER DATA FILE NAME: ',S)
00026      READ(5,1500)JFILE
00027      C.....
00028      OPEN(UNIT=23,ACCESS='SEQUENT',FILE=JFILE)
00029      OPEN(UNIT=20,ACCESS='SEQUENT',FILE=IFILE)
00030      OPEN(UNIT=25,ACCESS='SEQUENT',FILE=SFILE)
00031      OPEN(UNIT=21,ACCESS='SEQUENT',FILE='SSPIN.DAT')
00032      C      INITIALIZATION OF VALUES
00033      DELOP=.1.
00034      ISOI=0
00035      R=1.987
00036      IT=2000
00037      EWROR=1.0-14
00038      TST=270.15
00039      TC=310.15
00040      TI=315.15
00041      TREF=298.15
00042      M10=4.81
00043      GV=10000.
00044      C.
00045      C.
00046      BI=4.45
00047      CI=.0106
00048      U=.0005
00049      AREA=30383.
00050      V=1000.
00051      CALL INPUT(TC,TI,M10,CI,GV)
00052      CP=33.5
00053      RH0=11.5
00054      UAV=U*AREA/V
00055      RHOCP=RH0*CP
00056      V2=UAV/RHOCP

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MAIN.      UTKVHA.FON      FORTRAN V.5A(621) /KI      19-SEP-79      10:08      PAGE 1-1

00057      D=0+.05
00058      READ IN BASE VALUES
00059      READ(21,*) (RKO(1),I=1,5)
00060      READ(21,*) (EN(1),I=1,5)
00061      READ(21,*) (DMO(1),I=1,5)
00062      C
00063      WRITE(25,3000)SFILF
00064      FURMAT(1),5X,VAN HEERDEN STEADY STATE TEST: 'A10'
00065      WRITE(25,3001)GV,MIO,CI,I,TC
00066      FURMAT(1),5X,CONTROL PARAMETERS: '11X,RESIDENCE TIME: ',
00067      1 3A,F/11X,INLET MONOMER: 4X,F/11X,INLET INITIATOR: 2X,F/11X,
00068      2 1-INLET: 10X,F/11X,1-COOLANT: 8X,F)
00069      C STEP TEMPERATURES
00070      DO 20 J=1,150
00071      T=TST+1.*FLOAT(J)
00072      C*****HEATS OF REACTION*****
00073      CPDELT=CP*(1-TREF)
00074      DO 22 IRXN=2,4
00075      D= (IRXN)*DMO(1)*XN)-CPDELT
00076      C*****
00077      D=DMO
00078      DO 30 K=1,5
00079      RK(K)=RKO(K)*EXP(-EN(K)/R/T)
00080      RKZ5=RK(5)
00081      C=CI/(1.+RK(1))*GV)
00082      A1=2.57-.00505*T
00083      A2=9.56-.0176*T
00084      A3=-3.03+.00785*T
00085      M=MIO*DMO
00086      MPRE=0.
00087      DO 135 I=1,11
00088      M=M-DM
00089      IF (M)531,531,541
00090      FLAG=1.0
00091      M=MIO
00092      CONTINUE
00093      CUNV=(MIO-M)/MIO
00094      CAGE=2.
00095      EFF=EXP(1-CAGE*CONV)
00096      RK(5)=RKZ5/EXP(1+(A1*(A2+A3*CONV)*CONV)*CONV))*2
00097      F=1.+8.*RK(5)*(RK(1)*EFF+C*RK(2)*M+3)*GV*GV
00098      G=2.*GV*RK(5)
00099      RU=1-1.*SORT(F)/6
00100      C*****
00101      RAD=2*(RK(1)*EFF+C*RK(2)*M+3)*RK(4)*M+R0
00102      RAD=RAD/(1/GV*M*(RK(3)*RK(4))-RK(5)*R0)
00103      C*****
00104      MVAL=(MIO-M)/GV-2.*RK(2)*M+3-(RK(3)*RK(4)*M+R0
00105      *WK(4)*M+RAD
00106      C=11*MBAL*MPRE
00107      MPRE=MBAL
00108      IF (FLAG.EQ.1.0)GO TO 33
00109      IF (CMT) 115,125,125
00110      DM=-.1*DM
00111      GO TO 135
00112      IF (ABS(MBAL).LE.ERROR) GO TO 33

```

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MAIN.      UTKVMA-FOM      FORTRAN V.5A(621) /KI      19-SEP-79      10100      PAGE 1-2

00113      135      CONTINUE
00114      WRITE(20,900)
00115      900      FORMAT ( 3X,'MONOMER BALANCE ITERATION WENT 2000.....')
00116      33      CONTINUE
00117      FLAG=0.
00118      Z=2.*EFF*RK(1)*C*2.*RK(2)*M**3*(RK(3)*RK(4))*M*R0
00119      RI=Z/(1./GV*RK(5)*R0*RK(4)*M)
00120      PU=(RK(4)*M*(R0-RAD)*RK(5)/2.*R0**2)*GV
00121      PI=(RK(4)*M*(RI-RAD)*RK(5)*R0*RI)*GV
00122      C      HEAT GENERATION AND REMOVAL CALCULATIONS
00123      C.
00124      QH=(T-T1)/GV-V2*(TC-T)
00125      C.
00126      QU=(DH(2)*RK(2)*M*M*R0*(DH(3)*RK(3)+DH(4)*RK(4))*M/RHOC*P
00127      D=LO-QG-QR
00128      TEST=DELO*DELOP
00129      IF (TEST)9011,9012,9013
00130      9011      CALL UTKSS(T,DELO,ISOL)
00131      9012      GOTO 9013
00132      9012      ISOL=ISOL+1
00133      WRITE(25,8000)DELO,MBAL,QG,QR
00134      WRITE(25,8001)T,M,C
00135      WRITE(25,8002)PO,PI,P2
00136      WRITE(25,8003)R0,RI,R2
00137      WRITE(5,8004)ISOL,T,M,P2
00138      8000      FORMAT('-.5X,DELO= ',D14.8,2X,MBAL= ',D14.8/8X,
00139      1      'QG= ',D14.8,2X,UR= ',D14.8)
00140      8001      FORMAT('-.5X,STEADY STATE PROPERTIES: /8X,T= ',D14.8,3X,
00141      1      'M= ',D14.8,3X,I= ',D14.8)
00142      8002      FORMAT('-.6X,PO= ',D14.8,2X,PI= ',D14.8,2X,P2= ',D14.8)
00143      8003      FORMAT('-.6X,R0= ',D14.8,2X,RI= ',D14.8,2X,R2= ',D14.8)
00144      8004      FORMAT( 3X,STEADY STATE '12/6X,T= ',D/6X,M= ',D/5X,P2= ',D)
00145      DELOP=-DELOP
00146      GOTO 9014
00147      9013      DELOP=DELO
00148      9014      CONTINUE
00149      R2=R1*12.*RK(3)*M*R1/(1./GV*RK(4)*M*RK(5)*R0)
00150      P2=IRK(4)*M*(R2-RAD)*RK(5)*(R0*R2*RI**2))*GV
00151      CALL RESULT(C,M,R0,RI,R2,PO,PI,P2,T,20)
00152      WRITE(20,100) MBAL,QR,QG,DELO
00153      WRITE(20,200) RAD
00154      200      FORMAT('-.10X,RADICAL CONCEN IS: ',D20.14)
00155      100      FORMAT ('-.6X,MBAL= ',E12.6,2X,QR= ',E12.6,2X,QG= ',E12.6,
00156      1      2X,DELO= ',E12.6)
00157      C*****
00158      TI=T
00159      MI=M
00160      P21=P2
00161      QR1=QR
00162      QG1=QG
00163      C*****
00164      WRITE(23) T1,QR1,QG1,M1,P21
00165      20      CONTINUE
00166      CLOSE (UNIT=23,ACCESS='SEQUENT',FILE='JFILE')
00167      CLOSE (UNIT=21,ACCESS='SEQUENT',FILE='SSPIN.DAT')
00168      CLOSE (UNIT=20,ACCESS='SEQUENT',FILE='IFILE')

```

MAIN. UTKVHA.FOW FORTRAN V.5A(621) /KI 19-SEP-79 10108 PAGE 1-3

00169 CLOSE(UNIT=25,ACCESS='SEQUOUT',FILE=SFILF)
00170 STOP
00171 END

COMMON BLOCKS

/AREAL(1+46)
R +0 CAGE +2 MIO +4 RKO +6 RK +20
EN +32 CUNV +44

/AREAZ(1+32)
DH +0 DHO +12 BI +24 TREF +26 TI +30

/AREASS(1+23)
DMO +0 I1 +2 TC +3 GV +5 UAV +7
RHOCF +11 V2 +13 CP +15 CI +17 ERROR +21

SURPROGRAMS CALLED

UTKSS INPUT FLOAT. DEFP. RESULT DABS.
DSORT.

SCALARS AND ARRAYS "##" NO EXPLICIT DEFINITION - "##" NOT REFERENCED

*P21 1 *AREA 3 *Z 5 *EFF 7 T1 11
*T 12 *LPDEL 14 *RKZ5 16 *K 20 *Q0 21
*A3 23 *ISOL 25 *MI 35 *OR 26 P2 30
*PRE 31 *LAG 33 *A2 35 *V 37 SFILF 41
*P1 43 *M1 45 *JFILE 46 *M 50 *J 52
*G 53 *IST 55 *S0006 57 *CRIT 60 *S0005 62
*A1 63 *S0004 65 *R2 66 *DM 70 *S0003 72
*IRXN 73 *S0002 74 *S0001 75 *P0 76 *S0000 100
*DELOP 101 *U 103 *R1 105 *RHO 107 *DELO 111
*IFILE 113 *TEST 115 *I 117 *F 120 *C 122
*R0 124 *G1 126 *SMOLD
ORI 133 *RAD 127 MBAL 131

TEMPORARIES

.00000 401 .00001 402

MAIN. NO ERRORS DETECTED

PAGE 1

10:08

19-SEP-79

FORTRAN V.5A(621) /KI

UTKVMA.FOR

UTKSS

```

00001 SUBROUTINE UTKSS(ITEM,DELOI,ISOL)
00002 PROGRAM FOR STEADY STATE VALUES VS TEMPERATURE
00003 C.....
00004 IMPLICIT REAL*8 (A-H,O-Z)
00005 C.....
00006 R=AL*8 M=MI*MIO*MOLD,MBAL,MPRE
00007 COMMON/AREA1/R,CAGE,MIO,RKO(5),RK(5),EN(5),CONV
00008 COMMON/AREA2/DH(5),DH0(5),RI,TREF,TI
00009 COMMON/AREAS/DH0,IT,TC,GV,UAV,RHOC,P,V2,CP,C1,ERROR
00010 ISOL=ISOL+1
00011 DT=-.5
00012 D=LOP=DELOI
00013 T=TEM*DT
00014 DU 201 J=1,500
00015 DM=DH0
00016 DU 30 K=1,5
00017 RK(K)=RKO(K)*EXP(-EN(K)/R/T)
00018 RK25=RK(5)
00019 C=CI/(1.+RK(1)*GV)
00020 A1=2.57-.00505*T
00021 A2=9.56-.0176*T
00022 A3=-3.03+.00785*T
00023 M=MIO*DM0
00024 MPRE=0.
00025 DU 135 I=1,IT
00026 M=M-DM
00027 IF (M)531,531,541
00028 FLAG=1.0
00029 M=MIO
00030 CONTINUE
00031 CONV=(MIO-M)/MIO
00032 CAGE=2.
00033 EF=EXP(-CAGE*CONV)
00034 RK(5)=RK25/EXP((A1+(A2+A3*CONV)*CONV)*CONV)**2
00035 F=1.+8.*RK(5)*(RK(1)*EFF+C*RK(2)*M**3)*GV*GV
00036 G=2.*GV*RK(5)
00037 RJ=(1.+SQRT(F))/G
00038 C.....
00039 RD=2*(RK(1)*EFF+C*RK(2)*M**3)*RK(4)*M*RO
00040 RD=RD/11/GV*M*(RK(3)*RK(4))-RK(5)*RO)
00041 C.....
00042 MDAL=(MIO-M)/GV-2.*RK(2)*M**3-(RK(3)*RK(4))*M*RO
00043 +RK(4)*M*RD
00044 C=CI*(MDAL*MPRE
00045 MPRE=MBAL
00046 IF (FLAG.EQ.1.0)60 TO 33
00047 IF (CRIT) 115,125,125
00048 DM=-.1*DM
00049 GU TO 135
00050 IF (ABS(MBAL).LE.ERROR) 60 TO 33
00051 CONTINUE
00052 WHITE(20,1001)
00053 FURMAT (3X,'MONOMER BALANCE ITERATION WENT 750.....')
00054 CONTINUE
00055 FLAG=0.
00056 Z=2.*EFF*RK(1)*C+2.*RK(2)*M**3*(RK(3)*RK(4))*M*RO

```

UTKSS UTKVHA.FOM FORTRAN V.5A(621) /KI 19-SEP-79 10:08 PAGE 1-1

```

00057 R1=Z/(1./GV*RK(5)*R0*RK(4)*M)
00058 P1=(RK(4)*M*(R0-RAD)*RK(5)/Z.*R0**2)*GV
00059 P1=(RK(4)*M*(R1-RAD)*RK(5)*R0*R1)*GV
00060 C*****HEATS OF REACTION*****
00061 CPDELT=CP*(1-TREF)
00062 DO 22 IRXN=2,4
00063 22 Dn(IRXN)=DHO(IRXN)-CPDELT
00064 C*****
00065 C*****TEMPERATURE BALANCE CALCULATIONS*****
00066 Qn=(1-T1)/GV*V2*(TC-T)
00067 Qn=(DH(2)*RK(2)*M*M*H0*(DH(3)*RK(3)*DH(4)*RK(4)))*M/RHOC
00068 C*****
00069 DnLO=Qn-QR
00070 C
00071 C TEMPERATURE ITERATION LOGIC
00072 TEST=DELO*DELO
00073 DnLO=DELO
00074 IF (ABS(DELO).LE.ERROR)GO TO 301
00075 IF (ISOL.EQ.1)GO TO 9040
00076 IF (ISOL.EQ.3)GO TO 9040
00077 IF (TEST)GO TO 301,9033
00078 D1=-.5*DT
00079 T=T+DT
00080 9031 GOTO 201
00081 9033 T=1.0T
00082 Y=(Qn-T1/GV*TC*V2)/(1./GV*V2)
00083 C*****
00084 C*****
00085 C*****
00086 C*****
00087 C*****
00088 C*****
00089 C*****
00090 C*****
00091 C*****
00092 C*****
00093 C*****
00094 C*****
00095 C*****
00096 C*****
00097 C*****
00098 C*****
00099 C*****

```

COMMON BLOCKS

```

/AREA1/(+46)
R +0
EN +32
CAGE +2 MIO +4 RKO +6 RK +20
CUNV +44
DHO +12 BI +24 TREF +26 TI +30
D1 +0
/AREA2/(+32)
D1 +0
/AREAS/(+23)
DHO +0
II +2 TC +3 QV +5 UAV +7

```


UTKSS UTKVHA-FOM FORTMAN V.5A(621) /KI 19-SEP-79 10:08 PAGE 1-2

RHOCP *11 VZ *13 CP *15 CI *17 ERROR *21

SUBPROGRAMS CALLED

DEP. DABS. DSORT.

SCALARS AND ARRAYS "S" NO EXPLICIT DEFINITION - "S" NOT REFERENCED

*Z	1	*EFF	3	*TEM	5	*T	7	*CPOELY	11
*RKZ5	13	*K	15	*QG	16	*A3	20	*MI	
*ISOL	22	*JR	23	*P2	25	*PRE	27	*FLAG	31
*DT	33	*2	35	*P1	37	*M	41	*J	43
*G	44	*CRIT	46	*A1	50	*R2	52	*S0003	54
*DM	55	*JELQ1	57	*IRXN	61	*S0002	62	*S0001	63
*P0	64	*S0000	66	*DELOP	67	*R1	71	*DELO	73
*TEST	75	*I	77	*F	100	*C	102	*R0	104
*MOLD		*AD	106	*BAL	110				

TEMPORARIES

.A0016 224 .00000 225 .00001 226

UTKSS NO ERRORS DETECTED

PAGE 1

```

INPUT  UTKVMA,+Om      FORTRAN V.5A1621) /KI  19-SEP-79  10:08
00001
00002      C
00003      SUBROUTINE INPUT(TC,TI,MIO,CI,6V,RHOIN,CPIN)
00004      IMPLICIT REAL*8 (A-H,O-Z)
00005      REAL*8 MIO
00006      WRITE(5,3000)TC,TI,MIO,CI,6V
00007      FORMAT( 3X,'CURRENT INLET CONDITIONS: ',10X,'1-TC= ',F/
00008      1 10X,'2-TI= ',F/10X,'3-MO= ',F/10X,'4-IO= ',F/10X,
00009      2 5-THETA= ',F/4X,'WHICH VARIABLE TO BE CHANGED?-- ',S)
00010      READ(5,*)IND
00011      IF (IND.EQ.1)GOTO 3001
00012      IF (IND.EQ.2)GOTO 3004
00013      IF (IND.EQ.3)GOTO 3006
00014      IF (IND.EQ.4)GOTO 3008
00015      IF (IND.EQ.5)GOTO 3010
00016      GOTO 3003
00017      3001  WRITE(5,3002)TC
00018      3002  FORMAT( 3X,'CURRENT TC= ',F,2X,'NEW TC= ',S)
00019      READ(5,*)TC
00020      GOTO 3003
00021      3004  WRITE(5,3005)TI
00022      3005  FORMAT( 3X,'CURRENT TI= ',F,2X,'NEW TI= ',S)
00023      READ(5,*)TI
00024      GOTO 3003
00025      3006  WRITE(5,3007)MIO
00026      3007  FORMAT( 3X,'CURRENT MO= ',F,2X,'NEW MO= ',S)
00027      READ(5,*)MIO
00028      GOTO 3003
00029      3008  WRITE(5,3009)CI
00030      3009  FORMAT( 3X,'CURRENT IO= ',F,2X,'NEW IO= ',S)
00031      READ(5,*)CI
00032      GOTO 3003
00033      3010  WRITE(5,3011)6V
00034      3011  FORMAT( 3X,'CURRENT THETA= ',F,2X,'NEW THETA= ',S)
00035      READ(5,*)6V
00036      CONTINUE
00037      RETURN
00038      END

```

SUBPROGRAMS CALLED

SCALARS AND ARRAYS "==" NO EXPLICIT DEFINITION - "==" NOT REFERENCED

	MIO	1	6	TC	3	10	6V	5	RHOIN	12	CPIN
*TI											

TEMPORARIES

.A0016 123

INPUT NO ERRORS DETECTED

RESULT UTKVHA-FOM FORTRAN V-5A(621) /KI 19-SEP-79 10100 PAGE 1

```

00001 C.
00002 C.
00003 C.
00004 C.
00005 C.
00006 C.
00007 C.
00008 C.
00009 C.
00010 C.
00011 C.
00012 C.
00013 C.
00014 C.
00015 C.
00016 C.
00017 C.
00018 C.
00019 C.
00020 C.
00021 C.
00022 C.
00023 C.
00024 C.
00025 C.
00026 C.
00027 C.
00028 C.
00029 C.

SUBROUTINE RESULT(IN,M,R0,R1,R2,P0,P1,P2,Y,KP)
THIS ROUTINE ALLOWS DATA TO BE WRITTEN THAT IS COMMON TO
MANY OF THE PROGRAMS USED IN THIS POLYSTYRENE SIMULATION
STUDY..
POM BY JS3.....1/01-25-79

IMPLICIT REAL*8 (A-H,O-Z)
COMMON/AREAL/R,CAGE,MIO,RKO(S),RK(S),EN(S),CONV
REAL*8 IN,M,MIO
DYN=P1/P0
DPM=PZ/P1
ZM=OPW/DPN
VIS=DEXP(-1.06-8.348*DLOG(1.-CONV)*.565*DLOG(DPM))
WRITE(KP,100)T,IN,M,DPN,OPW,VIS,ZP
FORMAT ('0',A,A,T=' ',D12.6,2X,'IN=',D12.6,3X,'M=',D12.6,
2 F3.3)
WRITE(KP,110)CONV,R0,R1,R2,P0,P1,P2
FORMAT (' ',A,'CONV=',D12.6,2X,'R0=',D12.6,2X,'R1=',D12.6,2X,
'Z2=',D12.6,3X,'P0=',D12.6,3X,'P1=',D12.6,2X,'P2=',D12.6)
RETURN
END

```

COMMON BLOCKS

```

/AREAL/(+46)
R      0      CAGE  +2      MIO  +4      RKO   +6      RK    +20
EN     +32     CONV  +44

```

SUBPROGRAMS CALLED

DLOG. DEXP.

SCALARS AND ARRAYS *** NO EXPLICIT DEFINITION - "N" NOT REFERENCED

	*T	*M	*IN	*P2	*P	*N1	*VIS	*R2	*DPN	*OPW	*P1	*KP
	1	13	24	3	15	26	5	17	30	7	21	11
												23

TEMPORARIES

```

.A0016 111    .00000 112    .00001 113    .00002 114    .00003 115

```

RESULT NO ERRORS DETECTED

```

MAIN.      OLDSVD.F04      FORTRAN V.5A(621) /KI 19-SEP-79      10107      PAGE 1

00001      C.      PROGRAM IS FOR THE SOLUTION OF THE EIGENVALUES AND EIGENVECTORS
00002      C.      OF POLYSTYRENE SYSTEM BY USING:
00003      C.      DATINT---->DATA INTERFACE ROUTINE
00004      C.      RRC----->REACTION RATE CONSTANT ROUTINE
00005      C.      HCDEN----->CP,RHO,DELTA H ROUTINE
00006      C.      DJAKE----->JACOBIAN MATRIX ROUTINE
00007      C.      HSBG----->SSP TRIANGULATE ROUTINE
00008      C.      ATEIG----->SSP EIGENVALUE ROUTINE
00009      C.      OUTTA----->DATA OUTPUT ROUTINE
00010      C.      SVD----->SINGLE VALUE DECOMPOSITION ROUTINE
00011      C.      UTTA----->DATA OUTPUT ROUTINE
00012      C.
00013      C.      PGM BY JS3.....1/01-25-79
00014      C.      .....2/03-10-79
00015      C.      .....3/05-04-79
00016      C.
00017      C.      IMPLICIT REAL*8 (A-H,O-Z)
00018      C.      REAL*8 WK(20),DW(10,10),PW(10,10),Y(1,10)
00019      C.      REAL*8 DR(10),DI(10),IN,YI(1,10)
00020      C.      .....
00021      C.      REAL*8 SW(10,10),U(10,10),V(10,10),Q(10),WKAREA(10)
00022      C.      .....
00023      C.      DIMENSION IANA(10)
00024      C.      COMPLEX IFILE,JFILE
00025      C.      COMMON/AREA2/DH(5),DHO(5),BI,TREF,TI
00026      C.      COMMON/AREAL/IY,IM
00027      C.      COMMON/AREAD/KOAT
00028      C.      COMMON/OUTP/IFILE,JFILE
00029      C.      .....
00030      C.      WRITE(5,1000)
00031      C.      1000  FORMAT( 3X,'EIGENVALUE ANALYSIS RUN NAME: ',S)
00032      C.      READ(5,1500)IFILE
00033      C.      1500  FORMAT( 2A5)
00034      C.      WRITE(5,2000)
00035      C.      2000  FORMAT( 3X,'INPUT DATA FROM FILE NAME: ',S)
00036      C.      READ(5,1500)JFILE
00037      C.      .....
00038      C.      OPEN(UNIT=20,FILE=IFILE,ACCESS='SEQUENT')
00039      C.      .....
00040      C.
00041      C.      KOAT=1
00042      C.      IY=1
00043      C.
00044      C.      CALL DATINT(1,YI)
00045      C.
00046      C.      KOAT=2
00047      C.
00048      C.      Y(1,1)=YI(1,9)
00049      C.      Y(1,2)=YI(1,2)
00050      C.      Y(1,3)=YI(1,6)
00051      C.      Y(1,4)=YI(1,7)
00052      C.      Y(1,5)=YI(1,8)
00053      C.      Y(1,6)=YI(1,1)
00054      C.      Y(1,7)=YI(1,3)
00055      C.      Y(1,8)=YI(1,4)
00056      C.

```

```

MAIN.      OLDSVD.FOR      FORTRAN V.5A(621) /K1  19-SEP-79      10:07      PAGE 1-1

00057      Y(I,9)=YI(I,5)
00058      Y(I,10)=YI(I,10)
00059      C.
00060      N=IM
00061      IZ=IM
00062      C.
00063      CALL ARC(YI(I,2),YI(I,9),EFF)
00064      C*****HEAT OF REACTION CALCULATIONS*****
00065      CP=33.5
00066      RHO=11.5
00067      CPDELT=CP*(YI(I,9)-TREF)
00068      DO 22 IJXN=2,4
00069      22 DH(IJXN)=DHO(IJXN)-CPDELT
00070      C*****
00071      C
00072      VALUEI=RHO*CP
00073      C
00074      CALL DJAKE(Y,PW,VALUEI,EFF)
00075      C.
00076      CALL MODRED(PW,IM)
00077      CONTINUE
00078      DO 10 I=1,IM
00079      DO 20 J=1,IM
00080      C*****
00081      SW(I,J)=PW(I,J)
00082      C*****
00083      20 DW(I,J)=PW(I,J)
00084      10 CONTINUE
00085      C.
00086      CALL HSBG(IZ,DW,10)
00087      CALL ATEIG(IZ,DW,DR,DI,IANA,10)
00088      .
00089      5050 WRITE(21,*)DR(IOT),DI(IOT)
00090      C*****
00091      C>>>>
00092      CALL LSVLR(SW,10,10,10,10,1,WKAREA,Q,U,V)
00093      CALL SVD(10,IM,IM,SW,Q,TRUE,0,TRUE,0,0,IERR,WKAREA)
00094      C.
00095      C.
00096      C.
00097      TYPE OUT DATA * *GO TO LPT ?*
00098      WRITE(5,100)
00099      FURMAT( 3X,'EIGENVALUES & SINGULAR VALUES:')
00100      DO 30 I=1,IM
00101      WRITE(5,110) I,DR(I),DI(I),I,Q(I)
00102      FURMAT( 9X,0('I2,')=.012,6,2X,012.6,3X,0('I2,')=.012,6)
00103      30 CONTINUE
00104      C
00105      WRITE(5,9999) IERR,IERR
00106      FURMAT( 3X,'ERROR MESSAGE #,I2,--HALT ON SV#,.I2)
00107      C.
00108      WRITE(5,120)
00109      FURMAT( 3X,'DO YOU WANT TO GO TO THE PRINTER ? - NO(0)YES(1)')
00110      READ(5,*)IND
00111      IF (IND.EQ.0) GO TO 40
00112      CALL OUTTA(PW,DR,DI,YI,U,V,Q)

```

```
00113 C.
00114 40 CONTINUE
00115 C.
00116 50 CONTINUE
00117 C.....
00118 CLOSE(UNIT=20,FILE=IFILE,ACCESS='SEQUENT')
00119 C.....
00120 STOP
00121 END
```

COMMON BLOCKS

```
/AREA2/(+32)
DH +0 D+0 +12 B1 +24 TREF +26 T1 +30
/AREA1/(+2)
IV +0 IM +1
/AREAD/(+1)
KDAT +0
/OUTP/(+4)
IFILE +0 JFILE +2
```

SUBPROGRAMS CALLED

```
MODRED ATEIG RMC H586 OUTTA DJAKE
SVD DATINT
```

SCALARS AND ARRAYS "NO" NO EXPLICIT DEFINITION - "N" NOT REFERENCED

*IOT	1	*EFF	2	*CPDELT	4	0	6	Y1	32
*N	56	UI	57	Y	103	*CP	127	V	131
*KAREA	441	*K		*J	465	-S0004	466	*I2	467
-S0003	470	-S0002	471	*IRXN	472	-S0001	473	*IERR	474
-S0000	475	SW	476	*IN		DR	1006	PW	1032
*IND	1342	U	1343	*RHO	1653	TANA	1655	DW	1667
*I	2177	*VALUE1	2200						

TEMPORARIES

MAIN. NO ERRORS DETECTED

```

OUTTA      OLDSDV.FOM      FORTRAN V.5A(621) /K1  19-SEP-79      10107      PAGE 1

00001      SUBROUTINE OUTTA(PW,ZR,ZI,Y,U,V,Q)
00002
00003      ROUTINE WRITES OUT RESULTS OF EIGENVALUE PROGRAM
00004
00005      PGM BY JS3.....1/01-25-79
00006      .....2/03-10-79
00007      .....3/06-06-79
00008
00009      IMPLICIT REAL*8 (A-H,O-Z)
00010      COMPLEX IFILE,JFILE
00011      REAL*8 PW(10,10),Y(1,10),ZR(10),ZI(10)
00012      REAL*8 U(10,10),V(10,10),Q(10)
00013      REAL DAY(2),HR,SEC
00014      COMMON/AREAT/1Y,1M
00015      COMMON/OUTP/IFILE,JFILE
00016
00017      WRITE(20,100)
00018      100  FORMAT(1,'4X',RESULTS OF SVD AND EIGENVALUE ANALYSES,'5X,
00019      1  '---SVD OF JACOBIAN MATRIX---')
00020      CALL DATE(DAY)
00021      CALL TIME(HR,SEC)
00022
00023      C.....
00024      WRITE(20,150)IFILE
00025      WRITE(20,160)JFILE,Y(1,9),Y(1,3),Y(1,6)
00026      1500  FORMAT(1,'4X',EIGENVALUE ANALYSIS RUN NAME: ',2A5,10X,
00027      1  'INPUT STEADY STATE VALUES-----')
00028      1600  FORMAT(1,'4X',INPUT DATA FOR ANALYSIS FROM: ',2A5,10X,
00029      1  'I=',D12,6,4X,'RO=',D12,6,4X,'PO=',D12,6)
00030      C.....
00031      WRITE(20,130)Y(1,1),Y(1,4),Y(1,7),DAY,Y(1,2),Y(1,5)
00032      1  Y(1,8),HR,SEC,Y(1,10)
00033      130  FORMAT(1,'5X',I=',D12,6,4X,'RI=',D12,6,4X,'PI=',D12,6/
00034      1  SA,DATE: ',2A5,34X,'M=',D12,6,4X,'R2=',D12,6,4X,'P2=',D12,6/
00035      2  SA,TIME: ',2A5,32X,'RAD=',D12,6)
00036      C.....
00037      WRITE(20,120)
00038      120  FORMAT(1,'4X',JACOBIAN MATRIX VALUES----->')
00039      DO 10 I=1,1M
00040      WRITE(20,140) (PW(I,J),J=1,1M)
00041      140  FORMAT(1,'6X,10(D10,4,2X))
00042      10  CONTINUE
00043      C.....
00044      WRITE(20,150)
00045      150  FORMAT(1,'4X',EIGENVALUES & SINGLE VALUES----->'/24X,'REAL',
00046      1  'UX,'IMAG')
00047      DO 20 I=1,1M
00048      WRITE(20,160)I,ZR(I),ZI(I),Q(I)
00049      160  FORMAT(1,'8X,'LAMBDA(12,1)=',2X,D12,6,2X,D12,6,10X,'Q(1,
00050      1  12,1)=',2X,D12,6)
00051      20  CONTINUE
00052      C.....
00053      WRITE(20,1209)
00054      1209  FORMAT(1,'4X',MATRIX U - ORTHONORMALIZED COLUMNS')
00055      DO 109 I=1,1M
00056      WRITE(20,140) (U(I,J),J=1,1M)

```

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19-SEP-79

/KI

OUTTA OLDSVD.FOM

FORTRAN V.5A(621)

10107

```

00057      109      CONTINUE
00058      C
00059      WRITE(20,1509)
00060      FURNAT('0'.4X,'MATRIX V - ORTHOGONAL MATRIX')
00061      DO 209 I=1,IM
00062      WRITE(20,140)(V(I,J),J=1,IM)
00063      C.
00064      RETURN
00065      END

```

COMMON BLOCKS

```

/AREAT(1:2)
IV      .0      IM      .1
/OUTP(1:4)
IFILE   .0      JFILE  .2

```

SUBPROGRAMS CALLED

DATE TIME

SCALARS AND ARRAYS "##" NO EXPLICIT DEFINITION - "##" NOT REFERENCED

Q	1	ZR	2	HR	3	Y	4	V	5
.J	6	.S0006 7	.S0005 10	.S0004 11	.S0003 12				
OAY	13	.S0002 15	.S0001 16	.S0000 17	SEC	20			
PN	21	J	ZI	23	.I	24			

TEMPORARIES

.A0016 240

OUTTA NO ERRORS DETECTED

MODRED OLDSVD.F0M FORTRAN V.5A(621) /KI 19-SEP-79 10:07 PAGE 1

```

00001                    SUBROUTINE MODRED(A,IM)
00002                    C
00003                    C    REDUCTION OF JACOBIAN MATRIX BASED ON JACOBIAN MATRIX
00004                    C
00005                    REAL*8 A(10,10),ROWCON
00006                    IMI=IM
00007                    WRITE(5,5000)
00008                    5000    FORMAT( 3X,'MODEL REDUCTION INFORMATION'/5X,
00009                    1    'MAT ORDER MODEL DO YOU WANT TO EXAMINE? - ',5)
00010                    READ(5,*)NELIM
00011                    IF (NELIM.EQ.1)GOTO 5001
00012                    NELIM=IMI-NELIM
00013                    DO 30 ICT=1,NELIM
00014                       DO 10 I=1,IM
00015                       DO 10 J=1,IM
00016                       ROWCON=A(I,IELIM)/A(IELIM,IELIM)
00017                       DO 10 J=1,IM
00018                       A(I,J)=A(I,J)-ROWCON*A(IELIM,J)
00019                       IM=IM-1
00020                    30    CONTINUE
00021                    GOTO 5002
00022                    5001    WRITE(5,5003)
00023                    5003    FORMAT( 5X,'YOU WANTED THE WHOLE MODEL 1')
00024                    RETURN
00025                    END

```

SUBPROGRAMS CALLED

SCALARS AND ARRAYS ** NO EXPLICIT DEFINITION - "*" NOT REFERENCED

*NELIM	1	ROWCON	2	*ICT	4	*IMI	5	*J	6
A	7	.S0002	10	.S0001	11	.S0000	12	*IELIM	13
*I	14	*IM	15						

TEMPORARIES

.A0016 46

MODRED NO ERRORS DETECTED

10107 PAGE 1-1

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FORTRAN V.5A(621) /KI

GRAM.FOR

```

00057 C.
00058 CALL OUTTA(PW,U,V,Q)
00059 C.
00060 C. 40 CONTINUE
00061 C.
00062 STOP
00063 END

```

COMMON BLOCKS

```

/AREAL(1+2)
1Y .0 IM .1

```

SUBPROGRAMS CALLED

GRAMMY OUTTA SVD

SCALARS AND ARRAYS ** NO EXPLICIT DEFINITION - "*" NOT REFERENCED

Q	1	*M	25	V	26	WKAREA	336	*J	362
.S0002	363	.S0001	364	*IERR	365	.S0000	366	SW	367
PW	677	*IND	1207	U	1210	*I	1520		

TEMPORARIES

MAIN. NO ERRORS DETECTED

```

OUTTA  GRAM.FOM      FORTRAN V.5A(621) /KI  19-SEP-79      10107      PAGE 1

00001      SUBROUTINE OUTTA(PW,U,V,Q)
00002      C.
00003      RQUTINE WRITES OUT RESULTS OF EIGENVALUE PROGRAM
00004      C.
00005      PGM BY JS3.....1/01-25-79
00006      .....2/03-10-79
00007      .....3/06-06-79
00008      C.
00009      IMPLICIT REAL*8 (A-H,O-Z)
00010      COMMON/AREA1/IY,IM
00011      REAL*8 U(1M,1M),V(1M,1M),Q(1M),PW(1M,1M)
00012      C.
00013      WRITE(3,120)
00014      FORMAT('0',4X,'GRAMMIAN MATRIX VALUES----->')
00015      DO 10 I=1,1M
00016      WRITE(3,140) (PW(I,J),J=1,1M)
00017      FORMAT('0',6X,10(D10.4,2X))
00018      10 CONTINUE
00019      C.
00020      WRITE(3,150)
00021      FORMAT('0',4X,'SINGULAR VALUES FROM GRAMMIAN DECOMPOSITION')
00022      DO 20 I=1,1M
00023      WRITE(3,160)(Q(I))
00024      FORMAT('0',10X,'SV(',12,')= ',2X,0)
00025      20 CONTINUE
00026      C.
00027      WRITE(3,1209)
00028      FORMAT('0',4X,'MATRIX U - ORTHONORMALIZED COLUMNS')
00029      DO 109 I=1,1M
00030      WRITE(3,140) (U(I,J),J=1,1M)
00031      109 CONTINUE
00032      C.
00033      WRITE(3,1509)
00034      FORMAT('0',4X,'MATRIX V - ORTHOGONAL MATRIX')
00035      DO 209 I=1,1M
00036      WRITE(3,140)(V(I,J),J=1,1M)
00037      209 CONTINUE
00038      RETURN
00039      END

COMMON BLOCKS
/AREA1/(+2)
IY      +0      IM      +1

SUBPROGRAMS CALLED

SCALARS AND ARRAYS      *** NO EXPLICIT DEFINITION - "X" NOT REFERENCED
.I0010 1      U      2      V      3      *J      4      .S0006 5
.S0005 6      .S0004 7      .S0003 10      .S0002 11      .S0001 12

```

OUTTA GRAM.FON FORTRAN V.5A(621) /KI 19-SEP-79 10107 PAGE 1-1

.50000 13	PM	14	U	15	.10007 16	.10006 17
.10005 20		.10004 21		.10003 22	.10002 23	.10001 24
*1 25		.10000 26				

TEMPORARIES

.A0016 110

OUTTA NO ERRORS DETECTED

```

GRAMMY      GRAM.F04      FORTRAN V.5A(621) /KI      19-SEP-79      10107      PAGE 1

00001      SUBROUTINE GRAMMY(GH,IM)
00002      C
00003      C ROUTINE CALLS IN RESPONSE DATA FILE AND RETURNS TO
00004      C MAIN PROGRAM THE GRAMMIAN MATRIX FOR THE DYNAMIC MODEL.
00005      C
00006      C PGMD JOHN STELLING III.....16.JUN.79
00007      C
00008      IMPLICIT REAL*8 (A-H,O-Z)
00009      REAL*8 GH(IM,IM),A(10,100),RFILE
00010      REAL DAY(2),HR,SEC
00011      C
00012      C*****READ IN DATA FILE INFORMATION*****
00013      WRITE(5,1000)
00014      1000 FORMAT( 3X,'DATA FILE CONTAINING THE RESPONSE MATRIX: ',S)
00015      READ(5,1500)RFILE
00016      1500 FORMAT( A10)
00017      OPEN(UNIT=1,FILE=RFILE,ACCESS='SEQUENTIAL')
00018      C*****
00019      C
00020      IRV=0
00021      C
00022      C*****READ IN RESPONSE DATA FROM RFILE*****
00023      DO 10 I=1,400
00024      READ(1,END=20)T,(A(J,I),J=1,10)
00025      IMV=IRV+1
00026      10 CONTINUE
00027      20 CONTINUE
00028      C*****
00029      C
00030      IRV=IRV/10
00031      C
00032      WRITE(5,2000)IRV
00033      2000 FORMAT( 3X,'NUMBER OF RESPONSE VALUES: ',I3)
00034      C
00035      WRITE(3,3000)RFILE,IRV
00036      3000 FORMAT(1,'10X','SVD ANALYSIS OF THE DYNAMIC MODEL','16X',
00037      1 'DATA FILE CONTAINING THE RESPONSE MATRIX: ',A10/16X,
00038      2 'NUMBER OF RESPONSE VALUES: ',I3)
00039      C
00040      CALL DATE(DAY)
00041      CALL TIME(HR,SEC)
00042      WRITE(3,3299)DAY,HR,SEC
00043      3299 FORMAT('0','15X','DATE & TIME OF ANALYSIS: ',2A5,5X,2A5)
00044      C
00045      IRV=IRV*IM
00046      C
00047      C*****GRAMMIAN BY CROSS-MULTIPLICATION*****
00048      DO 30 I=1,IM
00049      DO 40 J=1,IM
00050      SUM=0.
00051      DO 50 II=1,IRV
00052      DO 60 JI=1,IRV
00053      SUM=SUM+A(II,1)*A(JI,J)
00054      60 CONTINUE
00055      50 CONTINUE
00056      GH(I,J)=SUM

```

GRAMMY GRAM.FOH FORTRAN V.5A16211 /KI 19-SEP-79 10:07 PAGE 1-1

```

00057      40      CONTINUE
00058      30      CONTINUE
00059      C*****
00060      C*****
00061      C*****
00062      C*****
          RETURN
          END

```

SUBPROGRAMS CALLED

DATE
TIME

SCALARS AND ARRAYS "" NO EXPLICIT DEFINITION - "" NOT REFERENCED

```

*IRV  1      *I  2      HR  4      *J1  5      *J  6
.S0005 7      *M  10     .S0004 11     *SUM 12     .S0003 14
DAY  15      A  17     .S0002 3737     .S0001 3740     .S0000 3741
SEC   3742    *FILE 3743     .I0002 3745     *I1  3746     .I0001 3747
*I    3750    .I0000 3751     *IM  3752

```

TEMPORARIES

.A0016 4044

GRAMMY NO ERRORS DETECTED

```

MAIN.      RESVN.FOR      FORTRAN V.5A1621) /KI      19-SEP-79      13:14      PAGE 1

C.
00001      PROGRAM IS FOR THE SOLUTION OF THE EIGENVALUES AND EIGENVECTORS
00002      OF POLYSTYRENE SYSTEM BY USING:
00003      DATINT---->DATA INTERFACE ROUTINE
00004      RRC----->REACTION RATE CONSTANT ROUTINE
00005      DJAKE----->JACOBIAN MATRIX ROUTINE
00006      HSBG----->SSP TRIANGULATE ROUTINE
00007      ATEIG----->SSP EIGENVALUE ROUTINE
00008      OUTTA----->DATA OUTPUT ROUTINE
00009      SVD----->SINGLE VALUE DECOMPOSITION ROUTINE
00010      UTTA----->DATA OUTPUT ROUTINE
00011
00012      PGM BY JS3.....1/01-25-79
00013      .....2/03-10-79
00014      .....3/05.04.79
00015
00016      IMPLICIT REAL*8 (A-H,O-Z)
00017      REAL*8 WK(20),DM(10),PM(10),Y(1,10)
00018      REAL*8 IN,YI(1,10),WAREA(10),BU(10),B(10,10),BSV(10,10)
00019      C.....
00020      REAL*8 SW(10,10),U(10,10),V(10,10),Q(10),WKAREA(10)
00021      C.....
00022      DIMENSION IANA(10) ,
00023      COMPLEX IFILE,JFILE
00024      COMMON/AREA2/DH(5),DHO(5),BI,TREF,II
00025      COMMON/AREA1/IY,IM
00026      COMMON/AHEAD/KDAT
00027      COMMON/OUTP/IFILE,JFILE
00028      C.....
00029      WRITE(5,1000)
00030      FORMAT( 3X,'INPUT RESPONSE ANALYSIS RUN NAME: ',S)
00031      READ(5,1500)IFILE
00032      1500      FORMAT( 2A5)
00033      WRITE(5,2000)
00034      2000      FORMAT( 3X,'INPUT DATA FROM FILE NAME: ',S)
00035      READ(5,1500)JFILE
00036      C.....
00037      OPEN(UNIT=20,FILE=IFILE,ACCESS='SEQUENT')
00038      C.....
00039      C.
00040      KDAT=1
00041      IY=1
00042      C.
00043      CALL DATINT(1,YI)
00044      C
00045      KDAT=2
00046      C
00047      C
00048      Y(1,1)=YI(1,9)
00049      Y(1,2)=YI(1,2)
00050      Y(1,3)=YI(1,6)
00051      Y(1,4)=YI(1,7)
00052      Y(1,5)=YI(1,8)
00053      Y(1,6)=YI(1,1)
00054      Y(1,7)=YI(1,3)
00055      Y(1,8)=YI(1,4)
00056      Y(1,9)=YI(1,5)

```



```

MAIN-      RESVDN.FOR      FORTRAN V.5A(621) /KI      19-SEP-79      13114      PAGE 1-1

00057      C.
00058      Y(1,10)=YI(1,10)
00059      N=IM
00060      IZ=IM
00061      C.
00062      CALL RRC(YI(1,2),YI(1,9),EFF)
00063      C*****HEAT OF REACTION CALCULATIONS*****
00064      CP=33.5
00065      RHO=11.5
00066      CPDELTA=CP*(YI(1,9)-TREF)
00067      DO 22 I=1,9
00068      22 DM(IRAN)=DMO(IRAN)-CPDELTA
00069      C*****
00070      C
00071      VALUE1=RHO*CP
00072      C
00073      CALL DJAKE(Y,PW,VALUE1,EFF)
00074      C.
00075      CALL HSHG(IZ,DW,10)
00076      CALL ATEIG(IZ,DW,DR,DI,IANA,10)
00077      C*****
00078      CALL RUMAT(Y,WAREA,EFF,8)
00079      CALL MODRED(PW,IM,10,8,5)
00080      C.
00081      DO 10 I=1,IM
00082      DO 20 J=1,IM
00083      C*****
00084      S(I,J)=-PW(I,J)
00085      C*****
00086      20 D(I,J)=PW(I,J)
00087      10 CONTINUE
00088      C*****
00089      CALL MINV(SW,10,IM,DETERM,WAREA)
00090      WAREA(I)=1.
00091      CALL MINV(SW,10,IM,DETERM,WAREA)
00092      C*****CROSS-MULTIPLICATION FOR A*XB MATRIX*****
00093      DO 60 I=1,IM
00094      DO 62 J=1,5
00095      SUM=0.
00096      DO 64 I1=1,IM
00097      64 SUM=SUM+SW(I,I1)*D(I1,J)
00098      62 BSW(I,J)=SUM
00099      60 CONTINUE
00100      C*****
00101      C>>>> CALL LSVLR(SW,10,10,10,10,10,WKAREA,Q,U,V)
00102      CALL SVD(10,IM,5,BSW,Q,TRUE,U,TRUE,V,IERR,WKAREA)
00103      C*****
00104      C.
00105      C.
00106      C.
00107      WRITE(5,100)
00108      100 FORMAT('3X,EQUIVALENT INPUT VECTOR & SINGULAR VALUES:')
00109      DO 30 I=1,IM
00110      WRITE(5,110) I,BUI(I),I,Q(I)
00111      110 FORMAT('9X,8XU(1,12,')=,D20.14,10X,SV(1,12,')=,D20.14)
00112      30 CONTINUE

```

MAIN. RESVON.FOM FORTRAN V.5A(621) /KI 19-SEP-79 13:14 PAGE 1-2

```

00113 C
00114 WRITE(5,9999)IERR,IERR
00115 9999 FORMAT( 3X,'ERROR MESSAGE #',I2,'-HALT ON SV#',I2)
00116 C.
00117 WRITE(5,120)
00118 120 FORMAT( 3X,'DO YOU WANT THIS PRINTED?-NO/0/YES/1 ',S)
00119 READ(5,*)IND
00120 READ(5,*)IND
00121 IF (IND.EQ.0)GOTO 40
00122 C.
00123 CALL OUTTA(PW,B,YI,U,V,Q)
00124 C.
00125 40 CONTINUE
00126 C.
00127 50 CONTINUE
00128 C.....
00129 CLOSE(UNIT=20,FILE=IFILE,ACCESS='SEQUENT')
00130 C.....
00131 STOP
00132 END

```

COMMON BLOCKS

```

/AREA2/(+32)
DH +0 +12 01 +24 TREF +26 11 +30
/AREA1/(+2)
1Y +0 1M +1
/AREAD/(+1)
KDAT +0
/OUTP/(+4)
IFILE +0 JFILE +2

```

SUBPROGRAMS CALLED

```

MODRED BUMAT RWC OUTTA DJAKE MINV
SVD DATINT

```

SCALARS AND ARRAYS *N=NO EXPLICIT DEFINITION - *N=NOT REFERENCED

```

*EFF 1 *LPDELT 3 0 5 31 *N 55
8 56 *AREA 366 Y 412 *CP 436 V 440
WKAREA 750 *K *J 774 BSW 775 *S0007 1305
*S0006 1306 *S0005 1307 *SUM 1310 *S0004 1312 *I2 1313
*S0003 1314 *S0002 1315 *IRRM 1316 *S0001 1317 *IERR 1320
*S0000 1321 SW 1322 *IN *PW 1632 *IND 2142
U 2143 *MHO 2453 *IANA *DW 2455 *I1 2765
*I 2766 *U 2767 *DETERM 3013 *VALUE1 3015

```

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19-SEP-79

FORTRAN V.5A(621) /KI

MAIN. RESVDN.FOM

TEMPORARIES

MAIN. NO ERRORS DETECTED

```

OUTTA RESVDN.F04      FORTRAN V.5A(621) /KI  19-SEP-79      13114      PAGE 1

00001      SUBROUTINE OUTTA(PW*8,Y*U,V*Q)
00002      C.
00003      ROUTINE WRITES OUT RESULTS OF EIGENVALUE PROGRAM
00004      C.
00005      PGM BY JS3.....1/01-25-79
00006      C. ....2/03-10-79
00007      C. ....3/06.06.79
00008      C.
00009      IMPLICIT REAL*8 (A-H,O-Z)
00010      COMPLEX IFILE,JFILE
00011      REAL*8 PW(10,10),Y(1,10),B(10,10)
00012      REAL*8 U(10,10),V(10,10),Q(10)
00013      REAL DAY(2),HR,SEC
00014      COMMON/AREA1/IY,IM
00015      COMMON/OUTP/IFILE,JFILE
00016      COMMON/NEW1/UFAC(5)
00017      C.
00018      CALL DATE(DAY)
00019      CALL TIME(HR,SEC)
00020      C
00021      WRITE(20,100)
00022      100  FORMAT('1.4X,RESULTS OF SVD OF INPUT RESPONSE ANALYSIS')
00023      C.....
00024      WRITE(20,1500)IFILE
00025      WRITE(20,1600)JFILE,Y(1,9),Y(1,3),Y(1,6)
00026      1500  FORMAT('0.4X,INPUT RESPONSE ANALYSIS RUN NAME: ',ZAS,10X,
00027      1  'INPUT STEADY STATE VALUES-----')
00028      1600  FORMAT('...X,INPUT DATA FOR ANALYSIS FROM: ',ZAS,10X,
00029      1  ', ',D12.6,X,'R0=',D12.6,X,'P0=',D12.6)
00030      C.....
00031      WRITE(20,130)Y(1,1),Y(1,4),Y(1,7),DAY,Y(1,2),Y(1,5)
00032      1  Y(1,9),HR,SEC,Y(1,10)
00033      130  FORMAT('...X,I=',D12.6,X,'R1=',D12.6,X,'P1=',D12.6/
00034      1  SA,DATE: ',ZAS,34X,'M=',D12.6,X,'R2=',D12.6,X,'P2=',D12.6/
00035      2  SA,TIME: ',ZAS,32X,'RAD=',D12.6)
00036      C.
00037      WRITE(20,120)
00038      120  FORMAT('0.4X,JACOBIAN MATRIX VALUES----->')
00039      DO 10 I=1,IM
00040      WRITE(20,140) (PW(I,J),J=1,IM)
00041      140  FORMAT(' ',6X,10(D10.4,2X))
00042      10  CONTINUE
00043      C.
00044      WRITE(20,150)
00045      150  FORMAT('0.4X,INPUT MATRIX B & SINGULAR VALUES----->')
00046      DO 20 I=1,IM
00047      WRITE(20,160) (B(I,J),J=1,5),I,0(I)
00048      160  FORMAT(' ',6X,5(D10.4,2X),4X,'SV(I,2,')= ',D)
00049      20  CONTINUE
00050      C.
00051      WRITE(20,1209)
00052      1209  FORMAT('0.4X,MATRIX U - ORTHONORMALIZED COLUMNS/')
00053      DO 109 I=1,IM
00054      WRITE(20,140) (U(I,J),J=1,IM)
00055      109  CONTINUE
00056      C

```

OUTTA RESVDN.FOM FORTRAN V.5A(621) /KI 19-SEP-79 13114 PAGE 1-1

```

00057 WRITE(20,1509)
00058 FORMAT(0,'.4X,MATRIX V - ORTHOGONAL MATRIX/')
00059 DO 209 I=1,IM
00060 WRITE(20,140)(V(I,J),J=1,IM)
00061 C.
00062 WRITE(20,189)(UFACT(I),I=1,5)
00063 FORMAT(0,'.4X,SCALING FACTORS: THETA/,F8.3,2X,MO/,F7.3,
00064 1 2X,IO/,F7.3,2X,TC/,F7.3,2X,TO/,F7.3)
00065 RETURN
00066 END

```

COMMON BLOCKS

```

/AREAL(1:2) IM +1
IV +0
/OUTP(1:4) J+ILE +2
IFILE +0
/NEW1(1:12)
UFACT +0

```

SUBPROGRAMS CALLED

DATE TIME

SCALARS AND ARRAYS *** NO EXPLICIT DEFINITION - "*" NOT REFERENCED

Q	1	2	3	4	5
J	6	7	10	11	12
SEC	13	14	16	17	20
	21	22	23	24	25

TEMPORARIES

.A0016 246

OUTTA NO ERRORS DETECTED

```

DJAKE      RESVDN.FOM      FORTRAN V.SA(621) /K1  19-SEP-79      13:14      PAGE 1

00001      SUBROUTINE DJAKE(YP,PW,VALUE1,EFF)
00002      C
00003      C THIS SUBROUTINE IS TO BE USED TO 'CHECK' UVA AND THE
00004      C WAY THEY CALCULATE THEIR EIGENVALUES FOR THE PSSA MODEL.
00005      C
00006      C PROGRAM BY JS3.....1/05.01.79
00007      C .....2/05.04.79
00008      C
00009      IMPLICIT REAL*8 (A-H,O-Z)
00010      C
00011      M2AL=0 YP(IY,IM),IN,IO,MIO,M,PM(IM,IM)
00012      C
00013      COMMON/AREAL/R,CAGE,MIO,RK0(5),RK(5),EN(5),CONV
00014      COMMON/AREA2/DH(5),DH0(5),BI,TREF,TI
00015      COMMON/AREA3/TC,THETA,U,AREA,V,UAV,RCPIN,CP
00016      COMMON/AREAL/IY,IM
00017      COMMON/AREARK/A1,A2,A3
00018      COMMON/AREAR5/RK5M
00019      C
00020      T=YP(1,1)
00021      M2YP(1,2)
00022      P2=YP(1,3)
00023      P1=YP(1,4)
00024      P2=YP(1,5)
00025      IN=YP(1,6)
00026      R0=YP(1,7)
00027      R1=YP(1,8)
00028      R2=YP(1,9)
00029      R4D=YP(1,10)
00030      C
00031      T*IN=-1./THETA
00032      R5M=2.*RK(5)*(A1+2.*A2*CONV+3.*A3*CONV**2)/MIO
00033      R12=R*RT**2
00034      R45T=RK(5)*EN(5)/RT2+2.*RK(5)*(1.00505*(1.0176-.00785*CONV)
00035      1 *(CONV)*CONV
00036      C.
00037      R41T=RK(1)*EN(1)/RT2
00038      R42T=RK(2)*EN(2)/RT2
00039      R43T=RK(3)*EN(3)/RT2
00040      R44T=RK(4)*EN(4)/RT2
00041      C
00042      DM1=-CP
00043      C.
00044      D1F1=T-TC
00045      D1F2=T-TREF
00046      VAL=UAV/VALUE1
00047      FM=EFF/MIO*CAGE
00048      C.....
00049      QPOL1=RK(3)*DH(3)+RK(4)*DH(4)
00050      QINT0=2*(EFF*IN+RK1T*M*M*M*HK2T)
00051      QINT1=M*RO*(RK3T*HK4T)
00052      QINT2=M*HK4T+R0*HK5T
00053      QINM0=2*(RK(1)*T*IN*FM+3*(RK(2)*M*M*H)
00054      QINM1=R0*(RK(3)+RK(4))
00055      QINM2=RK(4)*R0*HK5M
00056      QRI0=M*(RK(3)+RK(4))

```

```

DJAKE RESVDN.FOM      FORTRAN V.5A(621) /K1  19-SEP-79      13114  PAGE 1-1

00057 C.....
00058 C.
00059 C.      NUM. THE PARTIAL DERIVATIVES, LINE BY LINE.....
00060 C.
00061 C.      INITIALIZE MATRIX TO ZERO
00062 C.
00063 C.      DO 10 I=1,IM
00064 C.      DO 20 J=1,JM
00065 C.      P=(I,J)=0.
00066 C.      20 CONTINUE
00067 C.      10 CONTINUE
00068 C.
00069 C.....D*ENDT
00070 C
00071 C      P=(1,1)=THIN*(M*R0*(DH(3)*RK3T*DH(4)*RK4T*RK(3)*DHT)+
00072 C      1 2*M*3*HK2T*DH(2)-UAV)/VALUE1
00073 C      P=(1,2)=(R0*QPOLT+6*M*M*RK(2))/VALUE1
00074 C      P=(1,7)=M*QPOLT/VALUE1
00075 C.....D*DOT
00076 C
00077 C      P=(2,1)=M*(RAD*HK4T-2*M*M*RK2T)-QINT1
00078 C      P=(2,2)=THIN-6*HK(2)*M*M-QINM1*RK(4)*RAD
00079 C      P=(2,7)=-QR10
00080 C      P=(2,10)=RK(4)*M
00081 C.....D*QNT
00082 C
00083 C      P=(3,1)=R0*(M*HK4T-R0/2*HK5T)-M*RAD*RK4T
00084 C      P=(3,2)=R0*(RK(4)*R0/2*HK5M)-RK(4)*RAD
00085 C      P=(3,3)=THIN
00086 C      P=(3,7)=RK(4)*M*RK(5)*R0
00087 C      P=(3,10)=-HK(4)*M
00088 C.....D*IDT
00089 C
00090 C      P=(4,1)=R1*(M*HK4T-R0*RK5T)-M*RAD*RK4T
00091 C      P=(4,2)=R1*(RK(4)*R0*RK5M)-RK(4)*RAD
00092 C      P=(4,4)=THIN
00093 C      P=(4,7)=RK(5)*R1
00094 C      P=(4,8)=PW(3,7)
00095 C      P=(4,10)=PW(3,10)
00096 C.....D*ZDT
00097 C
00098 C      P=(5,1)=R2*(M*HK4T-R0*RK5T)*R1*R1*RK5T-M*RAD*RK4T
00099 C      P=(5,2)=R2*(M*HK4T-R0*RK5M)*R1*R1*RK5M-RK(4)*RAD
00100 C      P=(5,5)=THIN
00101 C      P=(5,7)=RK(5)*R2
00102 C      P=(5,8)=2*PW(4,7)
00103 C      P=(5,9)=PW(3,7)
00104 C      P=(5,10)=PW(3,10)
00105 C.....D*NDT
00106 C
00107 C      P=(6,1)=-IN*RK1T
00108 C      P=(6,6)=THIN-RK(1)
00109 C
00110 C
00111 C
00112 C

```

```

00113 C
00114 C.....DmDDT
00115 C
00116 P=(7.1)=QINT0-RK5T*R0*R0
00117 P=(7.2)=QINM0-RK5M*R0*R0
00118 P=(7.6)=2*RK(1)*EFF
00119 P=(7.7)=THIN-2*RK(5)*R0
00120 C
00121 C.....DmDDT
00122 C
00123 P=(8.1)=QINT0-QINT1-R1*QINT2
00124 P=(8.2)=QINM0-QINM1-R1*QINM2
00125 P=(8.6)=PW(7.6)
00126 P=(8.7)=QR10-R1*RK(5)
00127 P=(8.8)=THIN-PW(3.7)
00128 C
00129 C.....DmDDT
00130 C
00131 P=(9.1)=QINT0-QINT1-R2*QINT2-2*M*R1*RK3T
00132 P=(9.2)=QINM0-QINM1-R2*QINM2-2*R1*RK(3)
00133 P=(9.6)=PW(7.6)
00134 P=(9.7)=QR10-RK(5)*R2
00135 P=(9.8)=2*RK(3)*M
00136 P=(9.9)=PW(8.8)
00137 C
00138 C.....DmDDT
00139 C
00140 P=(10.1)=QINT0-QINT1-RAD*(QINT2*M*RK3T)
00141 P=(10.2)=QINM0-QINM1-RAD*(QINM2*RK(3))
00142 P=(10.6)=PW(7.6)
00143 P=(10.7)=RK(4)*M-RK(5)*RAD
00144 P=(10.10)=PW(8.8)-RK(3)*M
00145 C
00146 R=TURN
00147 E=0

```

COMMON BLOCKS

/AREA1/(+46)									
R	+0								
EN	+32	CAGE	+2	MIO	+4	RKO	+6	RK	+20
		CUNV	+44						
/AREA2/(+32)									
DH	+0	DH0	+12	BI	+24	TREF	+26	TI	+30
/AREA3/(+20)									
TC	+0	TETA	+2	U	+4	AREA	+6	V	+10
UAV	+12	RCPIN	+14	CP	+16				
/AREA1/(+2)									
IY	+0	IM	+1						
/AREARK/(+6)									
AI	+0	AL	+2	A3	+4				

DJAKE RESVDN.FOM

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/AREARS/(1+2)
RKSM +0

SUBPROGRAMS CALLED

SCALARS AND ARRAYS "==" NO EXPLICIT DEFINITION - "s" NOT REFERENCED

*EFF	1	*T	3	*RKST	5	*QPOLT	7	*DIF2	11
*RK2T	13	*P2	15	*DIF1	17	*QINT2	21	*QINM2	23
*THIN	25	*P1	27	M	31	*J	33	%IO	
*QINT1	34	*RK3T	36	*ORIO	40	*RT2	42	*R2	44
*QINH1	46	*S0001	50	*S0000	51	*P0	52	IN	54
P4	56	*QINT0	57	*R1	61	*QINM0	63	*I0005	65
*I0004	66	*VAL	67	*I0003	71	*HK4T	72	*I0002	74
*I0001	75	*I	76	*I0000	77	YP	100	*FM	101
*R0	103	*UHT	105	*RAD	107	*VALUE1	111	*RKIT	113

TEMPORARIES

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DJAKE NO ERRORS DETECTED

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BUMAT RESVDN.FOM FORTRAN V.5A(621) /KI 19-SEP-79 13:14 PAGE 1

00001 SUBROUTINE BUMAT(Y,8U,EFF,8)
00002 C
00003 C SUBROUTINE BUMAT(Y,8U,EFF,8)
00004 C
00005 C SUBROUTINE SUPPLIES THE CROSS-PRODUCT VECTOR OF THE 8 MATRIX
00006 C AND THE PROCESS INPUT VECTOR U (DEVIATION VARIABLES).....
00007 C
00008 C PLMD BY JOHN STELLING III.....1/06.29.79
00009 C
00010 C
00011 C IMPLICIT REAL*8 (A-H,O-Z)
00012 REAL*8 MIO,IO,Y(1,10),BU(10),B(10,10),U(5)
00013 REAL*8 MIO1,IO1
00014 C
00015 C COMMON/AREAL/R,CAGE,MIO,RKO(5),RK(5),EN(5),CONV
00016 C COMMON/AREA2/DH(5),DHO(5),BI,TREF,TI
00017 C COMMON/AREA3/TC,THETA,UCAP,AREA,V,UAV,RCPIN,CP
00018 C COMMON/AREA5/IO
00019 C COMMON/AREAS/RKSH
00020 C COMMON/NEW1/UFACT(5)
00021 C
00022 C DATA UFACT/2000.,1.,.04,20.,25./
00023 C
00024 C
00025 8888 FURMAT( 3X,'SCALING FACTORS FOR INPUTS: ',5(2X,'UFACT(',
00026 1 I,')= ',F/))
00027 DO 8886 I=1,5
00028 WRITE(5,8885)
00029 FURMAT( 3X,'CHANGE WHICH VARIABLE7(0 FOR NO CHANGE)- ',5)
00030 READ(5,*)IINPUT
00031 IF(IINPUT.EQ.0)GOTO 8887
00032 WRITE(5,8889)IINPUT
00033 FURMAT( 3X,'UFACT(',I,')= ',5)
00034 READ(5,*)UFACT(IINPUT)
00035 CONTINUE
00036 CONTINUE
00037 C
00038 C*****B-MATRIX FORMULATION*****
00039 THIN=1/THETA
00040 THIN2=THIN*THIN
00041 C
00042 DO 10 I=1,10
00043 DO 20 J=1,5
00044 B(I,J)=0.
00045 CONTINUE
00046 C
00047 DO 30 I=1,10
00048 B(I,1)=Y(I,1)*THIN2
00049 C
00050 B(1,1)=B(1,1)-THIN2
00051 B(2,1)=B(2,1)-MIO*THIN2
00052 B(6,1)=B(6,1)-IO*THIN2
00053 C
00054 B(1,4)=UAV/RCPIN
00055 B(1,5)=THIN
00056 B(2,2)=THIN

```

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BUMAT RESVDN.FOM FORTRAN V.5A(621) /KI 19-SEP-79 13:14 PAGE 1-1

00057 C B(6,3)=THIN
00058
00059 FVAL=-2.*RK(1)*Y(1,6)*Y(1,2)*EFF*CAGE/MIO/MIO
00060 RKSMIO=-RKSM*Y(1,2)/MIO
00061 C
00062 B(3,2)=RKSMIO*Y(1,7)*Y(1,7)/2.
00063 B(4,2)=RKSMIO*Y(1,7)*Y(1,8)
00064 B(5,2)=RKSMIO*Y(1,7)*Y(1,9)*Y(1,8)*Y(1,8))
00065 B(7,2)=FVAL-2.*B(3,2)
00066 B(8,2)=FVAL-B(4,2)
00067 B(9,2)=FVAL-RKSMIO*Y(1,7)*Y(1,9)
00068 B(10,2)=FVAL-RKSMIO*Y(1,7)*Y(1,10)
00069 C*****SCALING OF THE B-MATRIX*****
00070 C*****
00071 DO 70 J=1,5
00072 D) 80 I=1,10
00073 80 B(I,J)=B(I,J)*UFAC(J)
00074 70 CONTINUE
00075 C*****
00076 C*****WRITE OUT THE B-MATRIX*****
00077 C*****
00078 NPASS=NPASS+1
00079 C**
00080 1000 FURMAT(1,0,4,*,B-MATRIX FOR STEADY STATE NO. *,12)
00081 DO 35 I=1,10
00082 35 WRITE(21)(B(I,J),J=1,5)
00083 1001 FURMAT(1,*,5(3X,010.4))
00084 C**
00085 C*****U-VECTOR FORMULATION*****
00086 C*****
00087 DO 40 I=1,5
00088 40 U(I)=0.
00089 GOTO 8989
00090 WRITE(5,3000)THETA,MIO,IO,TC,TI
00091 3000 FURMAT(1,3X,CURRENT INLET CONDITIONS:*/10X,*,1-THETA= *,F/
00092 1 10X,*,2-MO= *,F/10X,*,3-IO= *,F/10X,*,4-TC= *,F/10X,
00093 2 *,5-IO= *,F/10X,*,WHICH VARIABLE TO BE CHANGED?-- *,S)
00094 READ(5,*)IND
00095 IF(IND.EQ.1)GOTO 3010
00096 IF(IND.EQ.2)GOTO 3006
00097 IF(IND.EQ.3)GOTO 3008
00098 IF(IND.EQ.4)GOTO 3001
00099 IF(IND.EQ.5)GOTO 3004
00100 GOTO 3003
00101 3001 WRITE(5,3002)TC
00102 3002 FURMAT(1,3X,CURRENT TC= *,F,2X,*,NEW TC= *,S)
00103 READ(5,*)TC1
00104 U(IND)=TC-TC1
00105 GOTO 3003
00106 3004 WRITE(5,3005)TI
00107 3005 FURMAT(1,3X,CURRENT TI= *,F,2X,*,NEW TI= *,S)
00108 READ(5,*)TI1
00109 U(IND)=TI-TI1
00110 GOTO 3003
00111 3006 WRITE(5,3007)MIO
00112 3007 FURMAT(1,3X,CURRENT MIO= *,F,2X,*,NEW MIO= *,S)

```

BUMAT RESVDN.FOM FORTAN V.5A(621) /K1 19-SEP-79 13114 PAGE 1-2

```

00113 READ(5,*)M101
00114 U(IND)=M10-M101
00115 GO TO 3003
00116 WRITE(5,3009)IO
00117 FURMAT( 3X,'CURRENT IO= ',F.2X,'NEW IO= ',S)
00118 READ(5,*)I01
00119 U(IND)=I0-I01
00120 GO TO 3003
00121 WRITE(5,3011)THETA
00122 FURMAT( 3X,'CURRENT THETA= ',F.2X,'NEW THETA= ',S)
00123 READ(5,*)THETA1
00124 U(IND)=THETA-THETA1
00125 CONTINUE
00126 C
00127 WRITE(5,1002)IND,U(IND)
00128 FURMAT( 3X,'U( ',I2,')= ',F.2X,'READY,SET,GO.....')
00129 C.....CROSS-MULTIPLICATION FOR VECTOR.....
00130 DO 50 I=1,I0
00131 SUM=0.
00132 DO 60 J=1,I5
00133 SUM=SUM+U(I,J)*U(J)*SUM
00134 BU(I)=SUM
00135 C
00136 C
00137 6989 CONTINUE
00138 RTURN
00139 END

```

COMMON BLOCKS

```

/AREA1/(+46)
R      +0
EN     +32
CAGE   +2
CONV   +44
M10    +4
RKO    +6
RK      +20
/AREA2/(+32)
DH      +0
Dn0    +12
BI      +24
TREF   +26
TI      +30
/AREA3/(+20)
TC      +0
TETA    +2
UAV     +12
RCPIN   +14
UCAP    +4
CP      +16
V        +10
/AREA5/(+2)
IO      +0
/AREAR5/(+2)
RKSN    +0
/NEW1/(+12)
UFACT   +0

```

SUBPROGRAMS CALLED

BUMAT RESVDN.FOM FORTRAN V.5A(621) /KI 19-SEP-79 13:14 PAGE 1-3

SCALARS AND ARRAYS "==" NO EXPLICIT DEFINITION - "==" NOT REFERENCED

*THIN2 1	*CFF 3	B 5	101 6	*THEIA1 10
Y 12	*WPASS 13	*THIN 14	*J 16	*S0007 17
*S0006 20	*I11 21	*S0005 23	*SUM 24	*S0004 26
*S0003 27	*S0002 30	*S0001 31	*TCL 32	*S0000 34
*IINPUT 35	*IND 36	M101 37	U 41	*S0013 53
*S0012 54	*S0011 55	*S0010 56	*FVAL 57	*I 61
HU 62	*KSM10 63			

TEMPORARIES

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BUMAT NO ERRORS DETECTED

```

00001 SUBROUTINE MODRED(A,IM,IC,B,ID)
00002 C
00003 C REDUCTION OF JACOBIAN MATRIX BASED ON JACOBIAN MATRIX
00004 C
00005 REAL*8 A(10,10),ROWCON,B(10,10)
00006 IM=IM
00007 WRITE(5,5000)
00008 5000 FORMAT(3X,'MODEL REDUCTION INFORMATION'/5X,
00009 1 'WHAT ORDER MODEL DO YOU WANT TO EXAMINE? - ',3)
00010 READ(5,*)NELIM
00011 IF (NELIM.EQ.IM)GOTO 5001
00012 NELIM=IM-NELIM
00013 DO 30 ICT=1,NELIM
00014 IELIM=IM-ICT
00015 DO 50 J=1,IM
00016 ROWCON=A(I,IELIM)/A(IELIM,IELIM)
00017 DO 10 J=1,IC
00018 A(I,J)=A(I,J)-ROWCON*A(IELIM,J)
00019 DO 40 J=1,10
00020 B(I,J)=B(I,J)-B(IELIM,J)*ROWCON
00021 50 CONTINUE
00022 IM=IM-1
00023 30 CONTINUE
00024 GOTO 5002
00025 5001 WRITE(5,5003)
00026 5003 FORMAT(5X,'YOU WANTED THE WHOLE MODEL 1')
00027 RETURN
00028 END

```

SUBPROGRAMS CALLED

SCALARS AND ARRAYS "N" NO EXPLICIT DEFINITION - "N" NOT REFERENCED

NAME	TYPE	DEFINITION	REFERENCED
NELIM	1	ROWCON 2	ICT 4
ID	7	J 10	B 5
S0001 14	14	S0003 11	A 12
IM	21	S0000 15	IC 16
			IELIM 17
			I 20

TEMPORARIES

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MODRED NO ERRORS DETECTED

APPENDIX B

ANALYSES:

EIGENVALUES AND SVD OF THE JACOBIAN MATRIX

The twelve sets of results given in this appendix represent the examination of the three steady states for tenth, ninth, sixth, and fifth order models. The model and steady state focused in each test is indicated in the EIGENVALUE ANALYSIS RUN NAME:

1. the first four characters represent the model tested, and
2. the fifth character (L,M,H) represents the low, middle or high steady state.

TABLE B-1 gives the cross reference between state variables discussed in the text of the thesis and the INPUT STEADY STATE VALUES variables indicated on each analysis sheet.

TABLE B-1. CROSS REFERENCE OF VARIABLES

INPUT VARIABLE	VARIABLE NUMBER	STATE VARIABLE
T	1	T
M	2	M
P0	3	μ_0
P1	4	μ_1
P2	5	μ_2
I	6	I
R0	7	σ_0
R1	8	σ_1
R2	9	σ_2
RAD	10	R ₁

RESULTS OF SVD AND EIGENVALUE ANALYSES

---SVD OF JACOBIAN MATRIX---

---SVD OF JACOBIAN MATRIX---

EIGENVALUE ANALYSIS RUN NAME: TENNL2.DAT
INPUT DATA FOR ANALYSIS FROM: SSIN02.DAT

EIGENVALUE ANALYSIS RUN NAME: TENNL2.DAT
INPUT DATA FOR ANALYSIS FROM: SSIN02.DAT

DATE: 15-SEP-79

DATE: 10-31-77
TIME: 10:21 15.3

JACOBIAN MATRIX VALUES

[illegible]

EIGENVALUES & SINGLE VALUES

	REAL	IMAG
LAMBDA(1) =	-.992663D-04	.000000D+00
LAMBDA(2) =	-.992663D-04	.000000D+00
LAMBDA(3) =	-.126974D+01	.000000D+00
LAMBDA(4) =	-.126974D+01	.000000D+00
LAMBDA(5) =	-.992663D-04	.000000D+00
LAMBDA(6) =	-.640712D+03	.000000D+00
LAMBDA(7) =	-.229656D+03	.000000D+00
LAMBDA(8) =	-.934526D-04	.000000D+00
LAMBDA(9) =	-.11321D-03	.000000D+00
LAMBDA(10) =	-.100183D-03	.000000D+00

MATRIX U - UNTHONORMALIZED COLUMNS

-32320-01	-15740-02	-45910-05	.99900+00	.23350-02	-53500-04	-32270-01	-86660-03	-80590-04	.37130-04
.77420-03	.37710-04	-18940-03	.23920-01	.29940-02	.11460-03	-72250+00	-69100+00	-35110-02	-21080-03
-15370-05	.78920-07	-18950-03	.7500-04	.46790-06	-10320-06	-32160-03	-33840-04	.17730-03	-10000+01
-70140-03	.77070-03	.18930-03	.21660-01	.20430-03	.59060+00	.62900-05	-72290+00	.13500-02	.24790-03
-70710+01	.70670+00	-15500-04	-.24000-01	-.52090-03	.68300-05	-36080-03	.37530-03	.85310-05	.13100-06
-15550-21	.35800-16	.36550-15	-.10130-08	.14820-01	.15200-01	-35030-02	-14840-02	.99980+00	.17620-03
.27800-05	.13540-06	.39480-09	-.85920-04	.13340-01	.99980+00	-16520-05	.27010-04	.15010-01	-.25560-05
.72850-04	.73310-04	.10430-06	.22660-02	.99980+00	-13110-01	-20450-02	-21970-02	.15030-01	.36070-05
.70630+00	.70750+00	.15120-04	.21730-01	.52090+03	.68290-05	-36770-03	.37540-03	.85290+05	.13100-06
-14430-06	-21500-04	.10000-01	-.40990-05	.627300-06	.23220-07	-26800-03	.59900-05	.95330-06	.18940+03

MATRIX V - ORTHOGONAL MATRIX

34430-19	-14400-06	-48400-09	-23450-02	-99620-00	-73860-01	-46230-01	-38140-02	-50780-04	-51830-04
-56600-08	-14870-05	-28330-08	-17290-02	-36000-01	-26710-02	-72310-00	-68970-00	-35370-02	-21170-03
-18460-15	-45420-14	-29350-10	-81150-07	-66430-04	-49250-05	-32090-03	-33890-04	-17590-03	-10000-01
-84230-13	-44360-10	-29310-10	-37010-04	-26910-01	-26730-02	-68910-00	-72400-00	-13390-02	-24790-03
-84920-19	-40670-07	-23920-11	-41010-04	-73950-01	-99730-00	-36010-03	-37590-03	-84620-05	-13100-06
-12830-11	-61540-09	-23420-08	-61790-06	-11620-03	-83600-06	-34830-02	-14760-02	-10000-01	-17480-03
-10000-01	-10160-03	-11020-06	-21720-05	-52050-08	-38590-09	-19900-08	-19930-08	-10340-10	-74480-12
-10160-03	-10000-01	-57830-01	-66190-06	-9420-07	-33810-07	-10430-05	-10270-05	-46560-08	-30750-09
-221730-05	-66460-06	-73740-09	-10000-03	-22780-02	-12780-02	-13330-02	-12290-02	-68030-05	-31670-06
-10430-00	-57830-04	-10000-01	-76940-09	-38660-09	-28690-10	-21630-08	-19980-08	-23320-08	-29160-10

RESULTS OF SVD AND EIGENVALUE ANALYSES

---SVD OF JACOBIAN MATRIX---

---SVD OF JACOBIAN MATRIX---

EIGENVALUE ANALYSIS RUN NAME: TENNM2.DAT
INPUT DATA FOR ANALYSIS FROM: SSIN02.DAT

EIGENVALUE ANALYSIS RUN NAME: TENNM2.DAT
INPUT DATA FOR ANALYSIS FROM: SSIN02.DAT

DATE: 15-SEP-79
TIME: 10:22 02.3

DATE: 15-SEP-79
TIME: 10:22 02.3

JACOBIAN MATRIX VALUES

-186600-04	-1311D-02	-00000-00	-00000-00	-0000D-00	-0000D-05	-0000D-00	-0000D-00	-0000D-00	-0000D-00
-35930-05	-1326D-03	-00000-00	-00000-00	-00000-00	-1263D-04	-0000D-00	-0000D-00	-0000D-00	-0000D-00
-50400-08	-3248D-06	-5921D-04	-00000-00	-00000-00	-0000D-00	-0000D-00	-0000D-00	-0000D-00	-5090D-00
-1924D-05	-1770D-03	-00000-00	-5921D-04	-00000-00	-0000D-01	-0000D-00	-0000D-00	-0000D-00	-5090D-00
-1380D-04	-8716D-01	-00000-00	-00000-00	-00000-00	-1136D-04	-0000D-00	-0000D-00	-0000D-00	-5090D-00
-4540D-07	-6179D-06	-00000-00	-00000-00	-9921D-04	-2273D-04	-0000D-00	-0000D-00	-0000D-00	-5090D-00
-5000D-07	-6179D-06	-00000-00	-00000-00	-00000-00	-0000D-00	-0000D-00	-0000D-00	-0000D-00	-0000D-00
-1723D-05	-9375D-04	-00000-00	-00000-00	-00000-00	-8661D-01	-0000D-00	-0000D-00	-0000D-00	-0000D-00
-8603D-03	-8274D-01	-00000-00	-00000-00	-00000-00	-4940D-01	-0000D-00	-0000D-00	-0000D-00	-0000D-00
-3633D-05	-3312D-04	-00000-00	-00000-00	-00000-00	-2525D-04	-0000D-00	-0000D-00	-0000D-00	-0000D-00
		-00000-00	-00000-00	-00000-00	-4925D-04	-0000D-00	-0000D-00	-0000D-00	-1267D-04

EIGENVALUES & SINGLE VALUES

[illegible]

9920630-04 .000000

SV(1) =	.823598D+06
SV(2) =	.339271D+04
SV(3) =	.126731D+04
SV(4) =	.420314D+00
SV(5) =	.171922D+03
SV(6) =	.124738D+03
SV(7) =	.839815D+04
SV(8) =	.494396D+05
SV(9) =	.992063D+04
SV(10) =	.740037D+09

MATRIX U - ORTHONORMALIZED COLUMNS

60130-01	-30840-02	-18220-04	99760+00	26720-02	32290-01	55800-03	-11440-01	-50700-04	-16960-03
-15330-02	78670-04	40120-03	55440-01	90240-01	64250+00	67040+00	-35900-02	41000-05	-60260-03
59980+05	32630-06	40230-06	59510-04	-32930-03	15150-02	15050-02	-17740-05	10000-01	-23450-11
13860-02	-15270-02	40140-03	22860-01	-56250-01	71630+00	65520+00	41550-03	21520-02	55710-08
70660+04	70620-00	-33540-04	42760-01	49410-03	93810-03	47820-03	69990-03	22930-05	-74560-05
-91790-20	-55090-14	-55090-14	-21270-08	-65270+00	17490+00	11000+00	35300+00	18250-03	36880+00
-10160-04	55190-06	-32600-08	-17850-01	39240+00	-61670-01	-11940-01	-11490+00	73220-04	92910-02
15350-03	14440-02	43550-06	25780-02	37980+00	19460+00	23070+00	8740+00	73980-04	72430-02
-70510-00	70800+00	-32650-04	-40290-01	44900-01	93780-03	-47830-03	89990-03	22920-05	-74560-05
59870-06	-46220-04	10000+01	-14520-05	55890-04	54690-03	10370-04	-14500-03	01500-03	-23500-06

MATRIX V - ORTHOGONAL MATRIX

38410-04	28120-08	-110070-03	69930-02	-15450-01	-20580-01	99950-00	55510-04	18050-01
-45170-06	-93190-05	-10310-01	-15660-00	80850-00	-56680-00	-23060-01	33180-05	-74000-03
-93190-05	-31500-10	-25390-07	19000-03	12050-02	-17780-02	36220-04	-10000-01	31430-06
95400-14	-44650-10	-31430-10	32460-01	56970-00	-82120-00	83280-02	21520-02	74900-03
-16620-12	-26250-07	-10570-04	-25910-03	74610-03	58490-03	-18060-01	-22930-05	99800-00
-85110-10	-20650-11	60500-05	98710-00	-14690-00	-62760-01	-10470-01	12190-03	-73660-05
-50980-10	47010-07	-46300-06	84680-05	41560-08	21480-07	98470-09	26370-10	26370-10
10000-01	-21130-03	-12360-03	-25480-05	11480-05	75650-05	-53070-05	57540-18	19430-07
-21130-03	-10000-01	-12360-03	-25480-05	11480-05	75650-05	-53070-05	57540-18	19430-07
84670-05	-26420-05	-34580-04	-59990-08	16190-02	83310-02	58490-02	13680-04	16380-04
-44820-05	-12360-03	-10000-01	35030-08	42330-07	-28120-07	17720-08	37400-10	32090-10

RESULTS OF SVD AND EIGENVALUE ANALYSES

---SVD OF JACOBIAN MATRIX---

EIGENVALUE ANALYSIS RUN NAME: NINEL2.DAT
INPUT DATA FOR ANALYSIS FROM: SSIN02.DAT

DATE: 20-AUG-79
TIME: 17:58 14.3

JACOBIAN MATRIX VALUES

-13670-03	.77770-04	.00000-00	.00000-00	.00000-00	.00000-00	.26700-05	.00000-00	.00000-00	.00000-00
-31360-06	-10110-03	.00000-00	.00000-00	.00000-00	.00000-00	-28440-09	.00000-00	.00000-00	.00000-00
-11500-09	.36830-08	-99210-04	.00000-00	.00000-00	.00000-00	-28440-09	.00000-00	.00000-00	.00000-00
-12270-06	.36930-05	.00000-00	-99210-04	.00000-00	.00000-00	.57940-03	.12700-01	.00000-00	.00000-00
-15860-03	.56740-02	.00000-00	.00000-00	.00000-00	.00000-00	.58410-06	.11590-04	.00000-00	.00000-00
-12720-08	.00000-00	.00000-00	.00000-00	.00000-00	.00000-00	.00000-00	.00000-00	.00000-00	.00000-00
-23150-06	-13920-07	.00000-00	.00000-00	.00000-00	.00000-00	-22970-01	.00000-00	.00000-00	.00000-00
-19310-06	-20370-05	.00000-00	.00000-00	.00000-00	.00000-00	.15010-05	.00000-00	.00000-00	.00000-00
-19270-03	-20440-02	.00000-00	.00000-00	.00000-00	.00000-00	.60180-02	.12700-01	.00000-00	.00000-00
						.15010-05	.12790-04	.12700-01	.12700-01

INPUT STEADY STATE VALUES

I= .3159420-03 R0= .1375050-07 P0= .9637150-04
I= .1051750-01 R1= .6938490-05 P1= .6879890-01
M= .4721350-01 R2= .6995380-02 P2= .1300490-03
RAD= .2734830-10

EIGENVALUES & SINGLE VALUES

	REAL	IMAG
LAMBUA(1)=	-.9920630-04	.0000000-00
LAMBUA(2)=	-.9920630-04	.0000000-00
LAMBUA(3)=	-.9920630-04	.0000000-00
LAMBUA(4)=	-.2296560-01	.0000000-00
LAMBUA(5)=	-.1269740-01	.0000000-00
LAMBUA(6)=	-.1269740-01	.0000000-00
LAMBUA(7)=	-.1133210-03	.0000000-00
LAMBUA(8)=	-.9345260-04	.0000000-00
LAMBUA(9)=	-.1001830-03	.0000000-00

MATRIX U - ORTHONORMALIZED COLUMNS

-32320-01	-15740-02	-.99900-00	-.23350-02	.53500-04	.32270-01	.86580-03	.80590-04	.36750-04
-77420-03	.37700-04	.23920-01	-.29940-02	-.11540-03	.72250-00	.69090-00	.35110-02	-.21960-03
-15370-05	-.74940-07	-.47500-04	-.46790-06	.10000-06	-.33350-03	.33470-04	-.17740-03	-.10000-01
-70140-03	-.77070-03	-.21660-01	-.20430-03	.18560-06	-.69060-00	.72290-00	-.13500-02	-.25580-03
-70710-06	-.70670-00	.24000-01	.52090-03	.68300-05	.36080-03	-.37530-03	.85310-05	-.13510-06
-15630-21	.35800-16	.10130-08	.14820-01	.15210-01	.35030-02	.14840-02	-.99980-00	.17620-03
-27800-05	.13540-06	.85920-04	-.13340-01	.99980-00	.16530-05	.28150-04	.15010-01	-.25600-05
-72850-04	.73310-03	-.22660-02	.99980-00	.13110-01	.20450-02	.21970-02	.15030-01	-.36330-05
.70630-00	-.70750-00	-.21730-01	.52090-03	.68290-05	.36070-03	-.37540-03	.85290-05	-.13510-06

MATRIX V - ORTHOGONAL MATRIX

-34430-14	-.14400-06	.23450-02	.99620-00	-.73860-01	-.46230-01	-.38120-02	-.50780-04	-.51280-04
-60070-08	-.14870-05	.17290-02	-.36000-01	.26710-02	-.72320-00	-.68970-00	-.35370-02	.22060-03
-18460-15	.43080-14	.81150-07	.66430-04	-.49250-05	.33280-03	-.33530-04	.17590-03	.10000-01
-84230-13	.44360-10	.37010-04	.29010-01	-.26730-02	.68910-00	-.72410-00	.13390-02	-.25580-03
-84920-14	.40670-07	-.41010-04	-.73950-01	.99730-00	-.36010-03	.37590-03	-.84620-05	.13510-06
-12830-11	-.61530-09	-.61790-06	-.11620-03	.83600-06	-.34830-02	-.14760-02	.10000-01	.17480-03
-10000-01	-.10160-03	-.21720-05	.52050-08	-.38590-09	.19900-08	.19920-08	.10340-10	-.76830-12
-10160-03	-.10000-01	.66190-06	-.94420-07	.33810-07	.10830-05	.10270-05	.46570-08	-.32080-09
-.21730-05	.66460-06	.10000-01	-.22780-02	.12780-03	.13330-02	.12290-02	.68030-05	-.33290-06

RESULTS OF SVD AND EIGENVALUE ANALYSES

---SVD OF JACOBIAN MATRIX---

EIGENVALUE ANALYSIS RUN NAME: NINEMZ-DAT
INPUT DATA FOR ANALYSIS FROM: SSIN02.DAT

DATE: 20-AUG-79
TIME: 17:55 51.2

INPUT STEADY STATE VALUES
I= .3451240-03 R0= .9523240-07 P0= .2613930-02
I= .7080520-02 R1= .2443000-04 P1= .1216520-01
M= .3597710-01 R2= .1250960-01 P2= .9027970-03
RAD= .3738470-09

JACOBIAN MATRIX VALUES

-.18600-04	.13110-02	.00000-00	.00000-00	.00000-00	.49520-05	.00000-00	.00000-00	.00000-00
-.35910-05	-.13260-03	.00000-00	.00000-00	.00000-00	-.12630-04	.00000-00	.00000-00	.00000-00
.35780-08	.22140-06	.00000-00	.00000-00	.00000-00	.23970-07	.00000-00	.00000-00	.00000-00
.19230-05	.11700-03	.00000-00	.00000-00	.00000-00	-.23970-07	.00000-00	.00000-00	.00000-00
.13080-02	.87610-01	.00000-00	.00000-00	.00000-00	.11360-04	.49400-01	.00000-00	.00000-00
-.45440-07	.00000-00	.00000-00	.00000-00	.00000-00	-.93210-04	.23970-07	.22730-04	.49400-01
.50000-07	.61790-06	.00000-00	.00000-00	.00000-00	-.14850-03	.00000-00	.00000-00	.00000-00
.17230-05	-.83750-04	.00000-00	.00000-00	.00000-00	.59580-04	.00000-00	.00000-00	.00000-00
.86030-03	-.42740-01	.00000-00	.00000-00	.00000-00	.59580-04	.12640-03	.00000-00	.00000-00
					.59580-04	.59580-04	.25250-04	-.49400-01

EIGENVALUES & SINGLE VALUES

	REAL	IMAG	SV(1)=
LAMBDA(1)=	-.9920630-04	.0000000-00	.8235980-06
LAMBDA(2)=	-.9920630-04	.0000000-00	SV(2)=
LAMBDA(3)=	-.9920630-04	.0000000-00	SV(3)=
LAMBDA(4)=	-.8860900-01	.0000000-00	SV(4)=
LAMBDA(5)=	-.4940210-01	.0000000-00	SV(5)=
LAMBDA(6)=	-.4940210-01	.0000000-00	SV(6)=
LAMBDA(7)=	.2233010-03	.0000000-00	SV(7)=
LAMBDA(8)=	-.1106300-03	.0000000-00	SV(8)=
LAMBDA(9)=	-.4488390-04	.0000000-00	SV(9)=

MATRIX U - UNNORMALIZED COLUMNS

.60130-01	-.30840-02	-.99760-00	.26720-02	.32290-01	-.55800-03	.11440-01	.16960-03	-.50690-04
-.15330-02	.78650-04	.25440-01	.98240-01	.64250-00	-.87040-00	.35900-00	-.60260-03	-.38720-05
.59980-05	-.30770-06	-.99510-04	-.32940-03	-.15150-02	-.15050-02	.18050-05	-.23980-11	.10000-01
.13600-02	-.15270-02	-.22860-01	-.56250-01	.71630-00	-.69520-00	-.41550-03	-.55710-08	-.21530-02
.70660-09	-.70620-00	.44790-01	.44910-03	.93810-03	.47820-03	.89990-03	-.74580-05	.22930-05
.91790-24	.54900-15	.21270-08	-.85270-00	.17490-00	-.11100-00	-.30530-00	.36980-00	-.18240-03
-.16760-04	.55190-06	.17850-03	.34240-00	-.87670-01	.41940-01	.11490-00	.92910-00	.73180-04
.15350-03	.14480-02	-.25780-02	.37980-00	.19460-00	-.23070-00	.87440-00	-.72430-02	.74140-04
-.70510-00	-.70800-00	-.40290-01	.44900-03	.93780-03	.47830-03	-.89990-03	-.74580-05	.22930-05

MATRIX V - ORTHOGONAL MATRIX

.38410-09	-.45170-06	.10070-03	.69930-02	-.15450-01	.20580-01	-.99950-00	.18050-01	.55510-04
-.93190-05	.10310-01	-.15660-00	-.15660-00	-.80850-00	.56680-00	.23060-01	-.74000-03	.29280-05
-.72250-15	.89960-14	.23490-07	.19010-03	.12050-02	.17780-02	-.36230-04	.31430-06	-.10000-01
.16620-12	.44650-10	.53960-05	.32460-01	.56970-00	.82120-00	.83380-02	.74690-03	.21530-02
-.51010-10	.20650-07	-.10570-04	-.25910-03	-.74610-03	.56490-03	.18080-01	.99980-00	-.22930-05
-.12400-07	-.60500-05	.98710-00	.98710-00	-.14690-00	.62760-01	.10470-01	-.73660-05	.12180-03
.10000-01	-.21130-03	-.84680-05	.41560-08	.21480-07	-.15000-07	-.98470-09	.26370-10	-.15800-12
-.21130-03	-.10000-01	.25480-05	.14480-05	.75650-05	-.53070-05	.23650-06	.19430-07	-.53820-10
.84670-05	.26420-05	.99990-00	.16190-02	.83310-02	-.58490-02	-.13680-03	.16380-04	-.23110-07

RESULTS OF SVD AND EIGENVALUE ANALYSES ---SVD OF JACOBIAN MATRIX---

EIGENVALUE ANALYSIS RUN NAME: SIXXL2.DAT
INPUT DATA FOR ANALYSIS FROM: SSIN02.DAT

DATE: 20-AUG-79
TIME: 10:02 08.7

INPUT STEADY STATE VALUES

T= .315942D+03 RO= .137505D-07 PO= .963715D-04
I= .105175D-01 R1= .693849D-05 P1= .687989D-01
M= .472135D+01 R2= .699538D-02 P2= .130049D+03
RAD= .273483D-10

JACOBIAN MATRIX VALUES

-.1098D-03	-.8410D-04	.0000D+00	.0000D+00	.0000D+00	.1745D-01
-.9582D-06	-.9719D-04	.0000D+00	.0000D+00	.0000D+00	-.4180D-03
.1395D-04	-.4014D-08	-.9921D-04	.0000D+00	.0000D+00	.8294D-06
.9606D-06	-.2621D-05	.0000D+00	-.9921D-04	.0000D+00	.4195D-03
.8392D-03	-.9846D-03	.0000D+00	.0000D+00	-.9921D-04	.7883D-01
-.1272D-08	.0000D+00	.0000D+00	.0000D+00	.0000D+00	-.9998D-04

EIGENVALUES & SINGLE VALUES

	REAL	IMAG	
LAMBDA1 1)	-.992063D-04	.000000D+00	SV(1)= .807475D-01
LAMBDA1 2)	-.992063D-04	.000000D+00	SV(2)= .320468D-03
LAMBDA1 3)	-.992063D-04	.000000D+00	SV(3)= .44684D-07
LAMBDA1 4)	-.113322D-03	.000000D+00	SV(4)= .908456D-04
LAMBDA1 5)	-.934533D-04	.000000D+00	SV(5)= .992480D-04
LAMBDA1 6)	-.100183D-03	.000000D+00	SV(6)= .992063D-04

MATRIX U - ORTHONORMALIZED COLUMNS

.2161D+00	.9646D+00	-.3518D-02	.1486D+00	-.2624D-01	-.6227D-05
-.5161D-02	-.1526D+00	-.7597D-02	.9857D+00	-.7063D-01	-.4492D-05
.1027D-04	.3040D-04	.2189D-08	.1320D-03	.1712D-02	.1000D+01
.5195D-02	.1463D-01	.1192D-05	.7373D-01	.9972D+00	-.1717D-02
.9763D+00	-.2144D+00	.4492D-03	-.2805D-01	.1278D-03	-.2852D-07
-.1238D-02	-.4457D-02	.1000D+01	.6978D-02	-.4455D-03	-.1235D-07

MATRIX V - ORTHOGONAL MATRIX

-.9853D-02	-.8899D+00	-.7291D-01	-.4483D+00	.4044D-01	.4125D-05
-.1212D-01	.4510D+00	.2640D-02	-.8897D+00	.6982D-01	.4492D-05
-.1262D-07	-.9395D-05	-.4861D-05	-.1441D-03	-.1711D-02	-.1000D+01
-.6382D-05	-.4514D-02	-.2646D-02	-.8052D-01	-.9967D+00	.1717D-02
-.1200D-02	.6626D-01	-.9973D+00	.3064D-01	-.1278D-03	.2652D-07
.9999D+00	.1432D-01	-.4460D-03	-.6335D-02	.4417D-03	.1220D-07

RESULTS OF SVD AND EIGENVALUE ANALYSES

---SVD OF JACOBIAN MATRIX---

EIGENVALUE ANALYSIS RUN NAME: SIXM2.DAT
INPUT DATA FOR ANALYSIS FROM: SSIN02.DAT

INPUT DATA FOR ANALYSIS FROM: SSIN02.DAT

DATE: 20-AUG-19

DATE: 20-AUG-73
TIME: 18:03 24.1

INPUT STEADY STATE VALUES

	H0= .9523240-07	P0= .2613930-02
--	-----------------	-----------------

I= .7080520-02 RI= .244300D-04 PI= .1216520+01

$R1 = .1250960-01$
 $R2 = .1250960-01$
 $P1 = .9027970+03$
 $P2 = .9027970+03$

RAD= .3738470-09

PO# .261393D-02

PI= .1216520.01

P1= .1210320+01
P2= .9027970+03

JACOBIAN MATRIX VALUES

26090-03	-21430-02	.00000-00	.00000-00	.00000-00	.33300+00
-101720-04	-244550-04	.00000-00	.00000-00	.00000-00	-84910-02
31460-07	-12310-06	.00000-00	.00000-00	.00000-00	.33190-04
10770-05	-56830-04	.00000-00	.00000-00	.00000-00	.85510-02
-5420-02	-45110-01	.00000-00	.00000-00	.00000-00	.89180-00
-5460-07	.00000-00	.00000-00	.00000-00	.00000-00	-14850-03

EIGENVALUES & SINGLE VALUES

	REAL	IMAG
LAMHDA(1) =	- .992063D-04	.000000D+00
LAMHDA(2) =	- .992063D-04	.000000D+00
LAMHDA(3) =	.289434D+03	SFV(3) =
LAMHDA(4) =	- .992063D-04	SFV(4) =
LAMHDA(5) =	- .110818D+03	SFV(5) =
LAMHDA(6) =	- .110818D+03	- .168101D-04
		SFV(6) =
		- .992063D-04
		SFV(7) =
		- .932012D+00
		SFV(8) =
		- .138329D+01
		SFV(9) =
		- .136659D+00
		SFV(10) =
		- .126524D+08
		SFV(11) =
		- .992584D+00
		SFV(12) =
		- .932063D-04

MATRIX U - ORTHONORMALIZED COLUMNS

36910-00	93620-00	32000-01	5850-03	25820-01	23390-04
88990-02	30980-01	99950-00	6300-02	49180-02	14260-05
34800-04	97970-04	20050-04	1640-11	30920-02	10000-01
89660-02	24030-01	57440-02	15030-07	99960-00	30940-02
93700-00	48930-00	22480-02	20170-04	76040-02	22830-05
15570-01	86860-03	16140-02	10000-01	38380-05	97800-08

MATRIX V - ORTHOGONAL MATRIX

-4,561D-02	.3700D-01	-.9942D+00	.1818D-01	-.4152D-01	.1843D-04
-.454D-01	-.9942D+00	-.9706D-01	.7450D-03	-.3879D-02	.1426D-05
.3622D-04	.7157D-06	.1455D-03	.3193D-06	.3090D-02	-.1000D-01
.9333D-06	.1723D-03	-.4170D-01	.7450D-03	.9991D+00	.394D-02
-.9754D-06	-.2505D-02	.1803D-01	.9998D+00	.7600D-05	-.2283D-05
-.9990D+00	-.4537D-01	.1557D-03	.1904D-04	.1527D-04	-.1156D-07

RESULTS OF SVD AND EIGENVALUE ANALYSES ---SVD OF JACOBIAN MATRIX---

EIGENVALUE ANALYSIS RUN NAME: SIXXHZ.DAT
INPUT DATA FOR ANALYSIS FROM: SSINOZ.DAT

DATE: 20-AUG-79
TIME: 18:02 45.6

INPUT STEADY STATE VALUES
T= .511555D+03 RO= .583692D-06 PO= .832444D-02
I= .151281D-04 R1= .256499D-03 P1= .448938D+01
M= .403754D+00 R2= .225177D+00 P2= .452538D+04
RAD= .133030D-08

JACOBIAN MATRIX VALUES

.5575D-03	.1725D-01	.0000D+00	.0000D+00	.0000D+00	.4030D+03
-.2225D-04	-.6135D-03	.0000D+00	.0000D+00	.0000D+00	-.1445D+02
.4597D-07	-.9216D-06	-.9921D-04	.0000D+00	.0000D+00	.3283D-01
-.2228D-04	.5141D-03	.0000D+00	-.9921D-04	.0000D+00	.1447D+02
.1282D-01	.8191D-01	.0000D+00	.0000D+00	-.9921D-04	.1126D+05
-.9610D-07	.0000D+00	.0000D+00	.0000D+00	.0000D+00	-.6951D-01

EIGENVALUES & SINGLE VALUES

	REAL	IMAG	SV(1)=
LAMHDA(1)=	-.992063D-04	.000000D+00	.112750D+05
LAMHDA(2)=	-.992063D-04	.000000D+00	SV(2)=
LAMHDA(3)=	-.992063D-04	.000000D+00	SV(3)=
LAMHDA(4)=	-.523485D-03	.000000D+00	SV(4)=
LAMHDA(5)=	-.688381D-01	.000000D+00	SV(5)=
LAMHDA(6)=	-.206357D-03	.000000D+00	SV(6)=

MATRIX U - ORTHONORMALIZED COLUMNS

-.4284D-01	.9980D+00	-.3689D-01	-.1525D-03	.2983D-01	.1058D-03
.1281D-02	-.3695D-01	-.9993D+00	-.3127D-02	.2028D-02	-.1407D-05
-.2912D-05	-.8458D-04	-.5204D-05	.1014D-07	-.3410D-02	.1000D+01
-.1283D-02	.2971D-01	-.3129D-02	.2210D-08	-.9995D+00	-.3406D-02
-.9991D+00	-.4287D-01	.3044D-03	.8701D-05	.7194D-05	-.6509D-05
.6165D-05	.3705D-04	-.3131D-02	.1000D+01	.1089D-04	.1386D-07

MATRIX V - UNITRIGONAL MATRIX

-.1138D-05	.5939D-03	.9984D+00	-.5470D-02	-.5632D-01	-.9825D-04
-.7324D-05	.1000D+01	-.5792D-03	.3128D-03	.2476D-03	.1398D-05
.2562D-13	.6107D-06	.9369D-04	-.7047D-05	.3406D-02	-.1000D+01
.1129D-14	-.2145D-03	.5632D-01	-.3159D-03	.9984D+00	.3406D-02
.8791D-08	.3096D-03	-.5480D-02	-.1000D+01	-.7186D-05	.6509D-05
-.1000D+01	-.7324D-05	-.1132D-05	-.4855D-08	.6230D-07	.1017D-09

RESULTS OF SVD AND EIGENVALUE ANALYSES --SVD OF JACOBIAN MATRIX---

EIGENVALUE ANALYSIS RUN NAME: FIVE12.DAT
INPUT DATA FOR ANALYSIS FROM: SSIN02.DAT

DATE: 20-AUG-79
TIME: 18:05 05.7

INPUT STEADY STATE VALUES
T= .3159420+03 RO= .1375050-07 PO= .9637150-04
I= .1051750-01 R1= .6938490-05 P1= .8879890-01
M= .4721350+01 M2= .6995380-02 P2= .1300490+03
RAD= .2734830-10

JACOBIAN MATRIX VALUES

--.1100D-03 --.8410D-04 .0000D+00 .0000D+00 .0000D+00
--.9528D-03 --.9719D-04 .0000D+00 .0000D+00 .0000D+00
.1384D-04 --.5014D-08 --.9921D-04 .0000D+00 .0000D+00
.9552D-06 --.2021D-05 .0000D+00 --.9921D-04 .0000D+00
.8382D-03 --.9846D-03 .0000D+00 .0000D+00 --.9921D-04

EIGENVALUES & SINGLE VALUES

	REAL	IMAG	
LAMBDA(1)=	-.9920630-04	.000000D+00	SV(1)=
LAMBDA(2)=	-.9920630-04	.000000D+00	SV(2)=
LAMBDA(3)=	-.1146060-03	.000000D+00	SV(3)=
LAMBDA(4)=	-.9920630-04	.000000D+00	SV(4)=
LAMBDA(5)=	-.9258980-04	.000000D+00	SV(5)=

.1298970-02
.152244D-03
.5323250-05
.9920510-04
.9920630-04

MATRIX U - ORTHONORMALIZED COLUMNS

-.5340D-04 .90830+00 --.41830+00 .60400-02 --.10480-19
.5644D-01 .41790+00 .90670+00 .27830-02 -.98540-19
.3056D-05 .17610-04 -.15340-06 -.26560-02 -.10000+01
.16670-02 .66200-02 -.85470-04 -.10000+01 .26560-02
.99840+00 --.18780-01 -.53500-01 .15450-02 -.13750-05

MATRIX V - ORTHOGONAL MATRIX

.64460+00 --.76220+00 .58650-01 --.33000-02 .00000+00
-.76070+00 --.64720+00 -.50240-01 -.28090-02 -.16630-19
-.23340-06 -.11470-04 .28590-05 .26560-02 .10000+01
-.12730-03 -.43140-02 .15930-02 .10000+01 -.26560-02
-.76250-01 .12240-01 .99700+00 -.15450-02 .13750-05

RESULTS OF SVD AND EIGENVALUE ANALYSES
 --SVD OF JACOBIAN MATRIX--

EIGENVALUE ANALYSIS RUN NAME: FIVEM2.DAT
 INPUT DATA FOR ANALYSIS FROM: SSIN02.DAT

DATE: 20-AUG-79
 TIME: 18104 13.3

INPUT STEADY STATE VALUES

T= .345124D+03 R0= .952324D-07 PO= .261393D-02
 I= .708052D-02 R1= .243300D-04 P1= .121652D+01
 M= .359771D+01 R2= .125096D-01 P2= .902797D+03
 RAD= .373847D-09

JACOBIAN MATRIX VALUES

.1590D-03	-.2143D-02	.0000D+00	.0000D+00	.0000D+00
-.8120D-05	-.4455D-04	.0000D+00	.0000D+00	.0000D+00
.2130D-07	-.1231D-06	-.9921D-04	.0000D+00	.0000D+00
.8157D-05	-.5483D-04	.0000D+00	-.9921D-04	.0000D+00
.4269D-02	-.4511D-01	.0000D+00	.0000D+00	-.9921D-04

EIGENVALUES & SINGLE VALUES

	REAL	IMAG	SV(1)=
LAMBDA(1)=	-.992063D-04	.000000D+00	.453647D-01
LAMBDA(2)=	.223833D-03	.000000D+00	.992619D-04
LAMBDA(3)=	-.992063D-04	.000000D+00	.454253D-04
LAMBDA(4)=	-.109381D-03	.000000D+00	.117801D-05
LAMBDA(5)=	-.992063D-04	.000000D+00	.992063D-04

MATRIX U - ORTHONORMALIZED COLUMNS

-.4735D-01	-.1650D-01	.9619D+00	-.2688D+00	.7040D-17
-.9608D-03	-.4650D-02	.2690D+00	.9631D+00	-.2474D-16
-.2745D-05	.3252D-02	.5568D-04	.1477D-06	-.1000D+01
-.1220D-02	.9998D+00	.1710D-01	.4985D-04	.3252D-02
-.9989D+00	-.4349D-03	-.4588D-01	.1161D-01	-.1225D-05

MATRIX V - ORTHOGONAL MATRIX

-.9416D-01	.3742D-01	-.9898D+00	-.9987D-01	.0000D+00
.9956D+00	.3541D-02	-.9384D-01	-.7263D-02	-.4844D-21
.6004D-06	-.3250D-02	-.1216D-03	-.1244D-04	.1000D+01
.2669D-05	-.9993D+00	-.3735D-01	-.4198D-02	-.3252D-02
.2184D-02	.4346D-03	.1002D+00	-.9950D+00	.1225D-05

RESULTS OF SVD AND EIGENVALUE ANALYSES
--SVD OF JACOBIAN MATRIX--

EIGENVALUE ANALYSIS RUN NAME: FIVEH2-DAT
INPUT DATA FOR ANALYSIS FROM: SSIN02.DAT

DATE: 20-AUG-79
TIME: 18:05 41.1

JACOBIAN MATRIX VALUES

-.11030-03	.17250-01	.00000+00	.00000+00	.00000+00	.00000+00
-.22810-05	-.61350-03	.00000+00	.00000+00	.00000+00	.00000+00
-.58570-04	-.92160-06	.00000+00	.00000+00	.00000+00	.00000+00
-.22810-05	.51410-03	.00000+00	.00000+00	.00000+00	.00000+00
-.27530-02	.81910-01	.00000+00	.00000+00	.00000+00	.00000+00

EIGENVALUES & SINGLE VALUES

	REAL	IMAG	
LAMBDA(1) =	-.9920630-04	.0000000+00	SV(1) =
LAMBDA(2) =	-.9920630-04	.0000000+00	SV(2) =
LAMBDA(3) =	-.5166660-03	.0000000+00	SV(3) =
LAMBDA(4) =	-.2070540-03	.0000000+00	SV(4) =
LAMBDA(5) =	-.9920630-04	.0000000+00	SV(5) =

MATRIX U - ORTHONORMALIZED COLUMNS

-.20590+00	-.97640+00	.48690-01	.43460-01	-.25010-18
.73200-02	.48170-01	.99880+00	-.21200-02	-.56670-17
.11000-04	.66770-04	-.65740-08	.15520-02	-.10000+01
-.61350-02	-.43180-01	.69090-05	-.99900+00	-.15530-02
-.97850+00	.20610+00	-.27730-02	-.28970-02	-.15000-05

MATRIX V - ORTHOGONAL MATRIX

.32440-01	-.99840+00	-.44420-01	.91750-02	.00000+00
-.99950+00	-.32450-01	-.28320-03	.30840-03	-.16900-21
-.13030-01	-.14380-04	.23680-05	-.15530-02	.10000+01
.72660-05	.93000-02	-.24890-02	.10000+01	.15530-02
.11590-02	-.44380-01	.99900+00	.29000-02	.15000-05

INPUT STEADY STATE VALUES
T= .4115550+03 R0= .5836920-06 P0= .8324440-02
I= .1512810-04 R1= .2564990-03 P1= .4409380-01
M= .4037540+00 R2= .2251770+00 P2= .4525380+04
RAD= .1330300-08

APPENDIX C

GRAMMIAN ANALYSES

The singular value decomposition analyses of the dynamic model, or grammian analyses, for three forms of normalization discussed in Chapter IV (techniques 2, 3, and 4) are given in this appendix. The sixth character of the DATA FILE of each analysis indicates the run number, as given also in TABLE 4-2 on page 52.

The first set of five analysis results (pages 160-164) were done according to normalization technique 2. Likewise, normalization technique 3 was used for the analyses given on pages 165-169 and normalization technique 4 was used for the final set of analyses (pages 170-174).

SVU ANALYSIS OF THE DYNAMIC MODEL
DATA FILE CONTAINING THE RESPONSE MATRIX: GRAM03.DAT
NUMBER OF RESPONSE VALUES: 10

DATE & TIME OF ANALYSIS: 11-JUL-79 16:20 48.7

GRAMMIAN MATRIX VALUES

.30250+00	.19830+00	.61950+00	.49800+00	.32410+00	.15200+00	.28480+02	.32830+01	-.12110+02	.73590+02
.19830+00	.13000+00	.53720+00	.32640+00	.21240+00	.99650+01	.18670+02	.21520+01	-.79380+01	.48240+02
.61950+00	.53720+00	.22200+01	.13490+01	.87800+00	.41190+00	.77150+02	.89500+01	-.32810+02	.19940+03
.49800+00	.32640+00	.13490+01	.61980+00	.53350+00	.25030+00	.44880+02	.54050+01	-.19940+02	.12110+03
.32410+00	.21240+00	.87800+00	.53350+00	.34720+00	.16290+00	.30510+02	.35180+01	-.12970+02	.78840+02
.15200+00	.99650+01	.41190+00	.25030+00	.16290+00	.76400+01	.14310+02	.16500+01	-.60860+01	.36980+02
.28480+02	.18670+02	.77150+02	.44880+02	.30510+02	.14310+02	.26810+04	.30910+03	-.11400+04	.69260+04
.32830+01	.21520+01	.89500+01	.54050+01	.35180+01	.16500+01	.30910+03	.35640+02	-.113140+03	.79870+03
-.12110+02	-.79380+01	-.32810+02	-.19940+02	-.12970+02	-.60860+01	-.11400+04	-.13140+03	.68480+03	-.29460+04
.73590+02	.48240+02	.19940+03	.12110+03	.78840+02	.36980+02	.69260+04	.79870+03	-.29460+04	.17900+05

SINGULAR VALUES FROM GRAMMIAN DECOMPOSITION

SV1 1)=	0.52819225271042530-15
SV1 2)=	0.2110715311166393060+05
SV1 3)=	0.4258517736446733800-14
SV1 4)=	0.663370705512428820-15
SV1 5)=	0.2263068231370274600-15
SV1 6)=	0.2592686561198076010-16
SV1 7)=	0.1207512636720621810-16
SV1 8)=	0.5705798700248507140-17
SV1 9)=	0.5501212014981519250-17
SV(10)=	0.2257477376195711600-17

MATRIX U - ORTHONORMALIZED COLUMNS

.10250-01	.37860-02	-.24940-01	-.74030+00	-.61350+00	.62650-01	.17410+00	-.67900-01	.12660+00	.14110+00
-.19310-02	.24810-02	.62890-02	.53240+00	-.49420+00	.13190+00	.11160+00	-.47070+00	.78880-01	.54360+00
-.25150-01	.10260-01	-.25680-01	-.76350-01	-.82920-01	.65860+00	-.65850+00	.50200-01	-.33270+00	.76030-01
.53990-02	.62320-02	.37120-03	-.11420+00	-.23480-01	-.29350+00	.28170-01	-.56200+00	.73130+00	-.22070+00
-.23210-02	.40560-02	-.22220-01	.18340+00	-.23520+00	.35670+00	.10350+00	-.30200+00	.30350+00	-.76760+00
.24910-02	.19030-02	.61730-02	-.15860+00	.12330+00	-.37340+00	-.63730+00	-.33500+00	.47350+00	.23020-01
-.93170+00	.35640+00	-.63590-01	-.66150-02	.29330-02	-.20650-01	.19220-01	-.32380-02	.81160-02	.15400-02
.29220-01	.41090-01	-.13880+00	-.29440+00	.61430+00	.42840+00	.32200+00	-.41380+00	.12480+00	.20020+00
-.12420+00	-.15160+00	.96870+00	-.63150-01	.68730-01	.90290-01	.42950-01	-.63260-01	.15680-01	.14230-01
.33900+00	.92090+00	.19070+00	.80540-02	-.11760-01	-.30280-02	-.77460-02	.16380-01	-.52070-03	-.52540-02

MATRIX V - ORTHOGONAL MATRIX

.10000+01	.37860-02	.00000+00	.00000+00	.00000+00	.00000+00	.00000+00	.00000+00	.00000+00	.00000+00
-.93940+05	.24810-02	.12990-01	.70460-03	.74800-02	.18800+00	-.19740+00	.75070+00	-.12850+00	-.58770+00
-.38820+00	.10260-01	.36440-01	-.72660-01	.21670+00	.37480+00	-.81300+00	-.54640-02	.67560-01	.37470+00
-.23590+00	.62320-02	.59600-01	.14930-01	.23400-01	.78030+00	.29850+00	.43990+00	-.23200+00	.38900+00
-.15350+00	.40560-02	.23060-01	.73690-02	-.27400-01	.19790+00	.15120+00	-.51720+00	.71960+00	.38900+00
-.72020+05	.19030-02	.95190-02	-.22280-01	-.34530-01	.40480+00	.38510+00	-.34400+00	-.51320+00	.55170+00
-.13490+02	.35640+00	-.30460+00	-.78850+00	-.39460+00	.47050-01	-.18790-01	-.17610-02	.14830-01	.46690-02
-.15560+03	.41090-01	.50790+00	.23350+00	-.80690+00	.34210-01	-.16280+00	.72120-02	.53120-01	.64610-01
.57370+03	-.15160+00	-.80130+00	.42880+00	-.35700+00	.93180-01	-.11390+00	-.10320-01	.35010-01	.24840-01
-.34860-02	.92090+00	-.37630-01	.36590+00	.12760+00	-.16070-01	.32210-02	-.21390-03	-.15020-02	-.10460-02

SVD ANALYSIS OF THE DYNAMIC MODEL
DATA FILE CONTAINING THE RESPONSE MATRIX: GRMA05.DAT
NUMBER OF RESPONSE VALUES: 10

DATE & TIME OF ANALYSIS: 11-JUL-79 16122 52.9

GRAMMIAN MATRIX VALUES

.66580+00	-.36010+00	.43270+01	.25840+01	.11750+01	-.87430+01	.31500+02	.70410+01	-.12150+02	.61760+02
-.36010+00	.19480+00	-.23410+01	-.13980+01	-.63550+00	.47300+01	-.17040+02	-.38090+01	.65710+01	-.33410+02
.43270+01	-.23410+01	.28130+02	.16790+02	.76360+01	-.56830+02	.20480+03	.45760+02	-.78960+02	.40140+03
.25840+01	.19480+01	.16790+02	.10030+02	.45590+01	-.33930+02	.12230+03	.27320+02	-.47140+02	.23960+03
.11750+01	-.63550+00	.76360+01	.45590+01	.20730+01	-.15430+02	.55590+02	.12420+02	-.21440+02	.10900+03
-.87430+01	.47300+01	-.56830+02	-.33930+02	-.15430+02	.11480+03	-.41370+03	-.92460+02	.15950+03	-.81100+03
.31500+02	-.17040+02	.20480+03	.12230+03	.55590+02	-.41370+03	.14910+04	.33320+03	-.57480+03	.29220+04
.70410+01	-.38090+01	.45760+02	.27320+02	.12420+02	-.92460+02	.33320+03	.74460+02	-.12850+03	.65310+03
-.12150+02	.65710+01	-.78960+02	-.47140+02	-.21440+02	.15950+03	-.57480+03	-.12850+03	.22170+03	-.11270+04
.61760+02	-.33410+02	.40140+03	.23960+03	.10900+03	-.81100+03	.29220+04	.65310+03	-.11270+04	.57280+04

SINGULAR VALUES FROM GRAMMIAN DECOMPOSITION

SV(1) =	0.9190572824044599850-15
SV(2) =	0.7670969057499875120+04
SV(3) =	0.148706089571574940-13
SV(4) =	0.3893660568301675040-14
SV(5) =	0.1073848053373030090-14
SV(6) =	0.3101447658175516080-14
SV(7) =	0.2040280218143988830-15
SV(8) =	0.2386118885708584570-15
SV(9) =	0.7637414377053547950-16
SV(10) =	0.3505330882585279430-17

MATRIX U - ORTHONORMALIZED COLUMNS

.41950-01	.93160-02	.59300-01	.48440-01	.27050+00	.22450-01	.33520+00	-.78970-03	-.85180+00	-.27610+00
-.67110-03	-.50390-02	.21620-01	-.18190-01	.18470-01	-.11060-01	-.41310-01	-.27540-01	-.31690+00	.94650+00
-.20940-02	.60550-01	-.45410+00	.59470+00	-.21960+00	.39370+00	.15470+00	.45480+00	-.13090-01	.46620-01
.36180-01	.36150-01	.16700+00	-.50750+00	-.61620+00	.49490+00	.28170+00	.25630-02	-.88450-01	-.12800-01
.45120-01	.16440-01	.96970-01	-.12360+00	-.16630+00	.19040-01	-.79670+00	.43430+00	-.22310+00	-.13130+00
-.18680+00	-.12230+00	-.21270+00	.20660+00	.65100+00	-.53600+00	-.14810-01	-.31000+00	-.32310+00	-.69980-01
.63280+00	.44080+00	-.53330+00	-.28680+00	.60290-02	-.18750+00	-.19080-02	-.53710-01	-.20660-01	-.14050-02
.17950+00	.98520-01	.28290-01	.31750+00	-.32580-02	.48360+00	-.35890+00	-.69600+00	-.82240-01	-.51640-01
-.54490+00	-.17000+00	-.63520+00	-.37800+00	.20630+00	.20220+00	.13740+00	-.14250+00	-.66470-01	-.28110-01
-.47990+00	.86410+00	.13630+00	.46290-01	-.112850-01	-.44550-01	.14440-02	-.55700-02	-.66840-02	-.56970-03

MATRIX V - ORTHOGONAL MATRIX

.10000+01	.93160-02	.00000+00	.00000+00	.00000+00	.00000+00	.00000+00	.00000+00	.00000+00	.00000+00
.46950+04	-.50390-02	.37120-02	-.11780-01	.31610-02	.19040-01	-.42220-01	-.14440+00	.61080+00	-.77680+00
-.56410-03	.60550-01	-.67950-01	.27930-01	-.15960+00	.80440-01	.39310-01	-.73440+00	-.56670+00	-.31140+00
-.33680+03	.36150-01	.28290-01	.27480+00	-.34060+00	.38240+00	.55450+00	.43830+00	-.29020+00	-.27660+00
-.15320+03	.16440-01	-.15940-01	-.14890-01	-.11510+00	-.40790+00	.54720+00	.46690+00	-.36250+00	-.41330+00
.11400-02	-.12230+00	.19440-01	-.87620+00	-.31720+00	-.16390+00	.29100+00	.39310-01	-.54010-01	-.17480-01
-.41070-02	.44080+00	-.76510+00	.52330-01	.83030-01	-.36050+00	.28280+00	.19060-01	.17160-01	.98310-02
-.91790-03	.98520-01	-.14080+00	.16050+00	-.84640+00	.37300-01	-.28760+00	-.90550-01	.29340+00	-.22360+00
.15840-02	-.17000+00	.38670+00	.33710+00	-.14600+00	-.72280+00	.37710+00	-.14020+00	.22870-01	.42400-01
-.80510-02	.86410+00	.48910+00	-.11600+00	.81370-02	.49070-03	-.50650-02	.19850-02	.16960-01	.12080-01

SVD ANALYSIS OF THE DYNAMIC MODEL
DATA FILE CONTAINING THE RESPONSE MATRIX: GRMA06.DAT
NUMBER OF RESPONSE VALUES: 10

DATE & TIME OF ANALYSIS: 11-JUL-79 16124 54.2

GRAMMIAN MATRIX VALUES

.2353D+00	.2100D+00	.2433D+01	.1285D+01	.6477D+00	.3080D+00	.9789D+01	.2428D+01	.1787D+01	.2287D+02
.2100D+00	.1874D+00	.2171D+01	.1147D+01	.5780D+00	.2749D+00	.8737D+01	.2166D+01	.1595D+01	.2041D+02
.2433D+01	.2171D+01	.2516D+02	.1329D+02	.6697D+01	.3185D+01	.1012D+03	.2510D+02	.1848D+02	.2364D+03
.1285D+01	.1147D+01	.1329D+02	.7020D+01	.3538D+01	.1682D+01	.5347D+02	.1326D+02	.9762D+01	.1249D+03
.6477D+00	.5780D+00	.6697D+01	.3538D+01	.1783D+01	.8477D+00	.2694D+02	.6681D+01	.4919D+01	.6293D+02
.3080D+00	.2749D+00	.3185D+01	.1682D+01	.8477D+00	.8031D+00	.1281D+02	.5317D+01	.2339D+01	.2993D+02
.9789D+01	.8737D+01	.1012D+03	.5347D+02	.2694D+02	.2694D+02	.4073D+03	.1010D+03	.7435D+02	.9513D+03
.2428D+01	.2166D+01	.2510D+02	.3185D+02	.6681D+01	.3177D+01	.1010D+03	.2504D+02	.1844D+02	.2359D+03
.1787D+01	.1595D+01	.1848D+02	.9762D+01	.4919D+01	.2339D+01	.7435D+02	.1844D+02	.1358D+02	.1737D+03
.2287D+02	.2041D+02	.2364D+03	.1249D+03	.6293D+02	.2993D+02	.9513D+03	.2359D+03	.1737D+03	.2222D+04

SINGULAR VALUES FROM GRAMMIAN DECOMPOSITION

SV(1)=	0.321555228845165193D-16
SV(2)=	0.270256577190275315D+04
SV(3)=	0.306568932105981443D-14
SV(4)=	0.344413570769409231D-15
SV(5)=	0.325677039605329972D-15
SV(6)=	0.196726577570881233D-15
SV(7)=	0.133384328595727645D-16
SV(8)=	0.120274124836701158D-15
SV(9)=	0.117551791256372672D-16
SV(10)=	0.978175140253688254D-17

MATRIX U - ORTHONORMALIZED COLUMNS

.3837D-02	-.9331D-02	-.1445D+00	.3429D-01	.1912D-01	-.1233D+00	.4214D+00	-.2044D+00	-.2021D+00	.8379D+00
.1774D+00	-.8328D-02	-.2040D+00	-.3295D+00	-.6614D+00	.5452D+00	-.2067D+00	-.1201D+00	.4150D-01	.1573D+00
.3927D+00	-.9649D-01	-.3580D+00	.7482D+00	-.1108D+00	.1038D+00	-.4976D-01	.3492D+00	-.4086D-02	.3178D-01
-.9882D-01	.5097D-01	-.1400D+00	-.2060D+00	-.2803D+00	-.1941D-01	.7537D+00	.4490D+00	.5191D-02	.2841D+00
-.3039D-01	-.2568D-01	.9798D-01	.1972D+00	.3290D+00	.1684D+00	.2728D+00	-.2887D+00	.8726D+00	.3541D-01
-.1305D+00	.1221D-01	.1833D+00	-.1860D+00	-.4764D-01	-.1706D+00	-.3028D+00	.6960D+00	.3591D+00	.4243D+00
-.8017D+00	.3982D+00	-.3653D+00	.1883D+00	-.9641D-01	.4740D-01	-.1532D+00	-.5025D-01	.1508D-01	.1028D-02
.1290D+00	-.9626D-01	-.5351D-01	.2947D-01	-.5352D+00	-.7705D+00	.1035D+00	-.2356D+00	.1279D+00	.8777D-01
-.2300D+00	.7087D-01	.7336D+00	.4030D+00	-.4032D+00	.1428D+00	.8080D-01	.2448D-02	-.2204D+00	.4491D-01
.2727D+00	-.9067D+00	.2684D+00	-.1257D+00	.9843D-01	.5191D-01	.3220D-01	.5287D-02	-.4181D-01	.2049D-01

MATRIX V - ORTHOGONAL MATRIX

.1000D+01	-.9331D-02	.0000D+00	.0000D+00	.0000D+00	.0000D+00	.0000D+00	.0000D+00	.0000D+00	.0000D+00
-.1771D-04	-.8328D-02	-.2111D-02	-.1246D+00	-.1147D+00	.1932D+00	-.3683D+00	.2917D-01	.6597D+00	-.6012D+00
-.9004D-03	-.9649D-01	-.1093D+00	.6457D+00	.1146D+00	.6916D+00	.1585D+00	-.1979D+00	.6730D-01	.3777D-01
-.2756D-03	-.5097D-01	.1960D+00	-.5184D+00	.3091D+00	.4576D+00	.4632D+00	.4050D+00	.7931D-01	.1999D-01
-.2397D-03	-.2568D-01	-.2925D-01	.2420D+00	.4353D-01	.3482D+00	.6390D+00	-.5515D-02	.6647D-01	-.6357D+00
.1140D-03	.1221D-01	.3922D-02	.1949D+00	.4264D+00	.3727D+00	.1620D+00	.7707D-02	.6750D+00	.3990D+00
-.3622D-02	-.3882D+00	.8921D+00	.1755D+00	.1031D-01	.6189D-01	-.1143D+00	-.5314D-01	.4133D-01	.3408D-01
-.8983D-03	-.9626D-01	.2208D+00	-.4064D+00	.9132D-02	.5853D-01	.2115D+00	-.8765D+00	.8841D-01	.2766D-01
.6614D-03	.7087D-01	-.5317D-01	-.2049D-01	.8325D+00	-.2565D-01	.3593D+00	-.1170D+00	-.2896D+00	-.2671D+00
-.8461D-02	-.9067D+00	-.3869D+00	-.7628D-01	.3569D-01	-.7799D-01	-.5702D-01	.1050D+00	-.2103D-01	.1454D-01

SVD ANALYSIS OF THE DYNAMIC MODEL
DATA FILE CONTAINING THE RESPONSE MATRIX: GRAM07.DAT
NUMBER OF RESPONSE VALUES: 10

DATE & TIME OF ANALYSIS: 11-JUL-79 16:27 18.9

GRAMMIAN MATRIX VALUES

.23630+00	.20960+00	.25800+01	.13300+01	.65100+00	.21220+00	.10360+02	.24670+01	-.19730+01	.24720+02
.20960+00	.18600+00	.22890+01	.11800+01	.57750+00	.18830+00	.91900+01	.21880+01	-.17500+01	.21930+02
.25800+01	.22890+01	.28180+02	.14530+02	.71090+01	.23180+01	.11310+03	.25940+02	-.21550+02	.26990+03
.13300+01	.11800+01	.14530+02	.74890+01	.36650+01	.11950+01	.58320+02	.13890+02	-.11110+02	.13920+03
.65100+00	.57750+00	.71090+01	.36650+01	.17940+01	.58470+00	.28540+02	.67960+01	-.54360+01	.68100+02
.21220+00	.18830+00	.23180+01	.11950+01	.58470+00	.19060+00	.93050+01	.22160+01	.17720+01	.22200+02
.10360+02	.91900+01	.11310+03	.58320+02	.28540+02	.93050+01	.45420+03	.10810+03	-.86500+02	.10840+04
.24670+01	.21880+01	.26940+02	.13890+02	.67960+01	.22160+01	.10810+03	.25750+02	-.20600+02	.25800+03
-.19730+01	-.17500+01	-.21550+02	-.11110+02	-.54360+01	-.17720+01	-.86500+02	-.20600+02	.16480+02	-.20640+03
.24720+02	.21930+02	.26990+03	.13920+03	.68100+02	.22200+02	.10840+04	.25800+03	-.20640+03	.25860+04

SINGULAR VALUES FROM GRAMMIAN DECOMPOSITION

SV(1)= 0.260430024914334664D-15
SV(2)= 0.3120365353193780027D-04
SV(3)= 0.295680279526866288D-14
SV(4)= 0.110978504822201868D-14
SV(5)= 0.208839702370259305D-15
SV(6)= 0.185465084130170199D-15
SV(7)= 0.455035617988138740D-16
SV(8)= 0.571087009057756123D-17
SV(9)= 0.186159918406820326D-16
SV(10)= 0.159723400450078893D-16

MATRIX U - ORTHONORMALIZED COLUMNS

-.1204D-01	.8702D-02	.8519D-02	.6446D-01	-.2068D+00	.1360D+00	-.1680D+00	-.4398D+00	-.4111D+00	.7373D+00
-.1661D-01	.7720D-02	-.1023D+00	-.7839D-01	.2890D+00	-.1588D+00	-.3687D-01	.7776D+00	-.2103D+00	.4735D+00
-.3880D-01	.9502D-01	-.3619D+00	-.8401D+00	-.1257D+00	.3232D+00	.2147D-01	-.1318D-01	.1671D+00	.6266D-01
-.3736D-01	.4899D-01	-.1751D+00	-.2191D+00	.6599D+00	-.4600D+00	.3233D+00	-.3602D+00	-.1674D+00	-.9074D-01
.4545D-01	.2398D-01	.4330D-01	-.1735D+00	-.7310D-01	.9821D-01	-.3051D+00	.3822D-01	-.8350D+00	-.3982D+00
.1544D-01	.7816D-02	-.1002D-01	-.6911D-01	.1957D+00	-.2009D+00	-.8740D+00	-.2610D+00	.1692D+00	.2355D+00
.8775D+00	.3815D+00	-.2391D+00	.1310D+00	.5776D-01	.7689D-01	.7674D-02	.2841D-02	.2575D-01	-.1120D-01
.1778D+00	.9084D-01	.6256D+00	-.2726D+00	.3299D+00	.2888D+00	.5557D-01	-.3131D-02	.6294D-01	.7015D-01
-.1900D+00	-.7266D-01	-.2921D+00	.3148D+00	.5150D+00	.7077D+00	-.6993D-01	-.4721D-01	-.1787D-01	-.2847D-01
-.3959D+00	.9103D+00	.4145D-01	.1021D+00	-.3864D-01	-.1435D-01	-.1974D-01	.1496D-01	-.6741D-03	-.8832D-02

MATRIX V - ORTHOGONAL MATRIX

.1000D+01	.8702D-02	.0000D+00	.0000D+00	.0000D+00	.0000D+00	.0000D+00	.0000D+00	.0000D+00	.0000D+00
-.6718D-04	.7720D-02	.2210D-02	-.2120D-01	.7027D-01	-.3118D+00	-.2675D+00	-.4828D-02	.8391D+00	-.3487D+00
-.8269D-03	.9502D-01	.7481D-02	-.6310D+00	.5037D+00	.2251D+00	-.5104D+00	.3652D-01	-.7862D-01	.1426D+00
-.4263D-03	.4899D-01	.3386D-02	-.1109D+00	-.4688D-01	.7645D+00	-.2473D+00	.3044D+00	-.4497D+00	.2063D+00
-.2086D-03	.2398D-01	-.2259D-01	-.1167D+00	.1642D-01	.4390D+00	.1020D+00	-.4455D+00	.1220D+00	-.7540D+00
-.6801D-04	.7816D-02	-.1497D-01	-.2677D-01	.2393D-01	.4131D-01	.7012D-01	.8323D+00	.2387D+00	.4921D+00
-.3320D-02	.3815D+00	-.9167D+00	.1034D+00	.7239D-02	.1310D-01	.5139D-01	.1940D-01	-.4910D-02	.1344D-01
-.7905D-03	.9084D-01	-.2069D-01	-.5362D+00	.6409D-01	.6409D-01	-.8979D-01	.9537D-01	.7545D-01	.6060D-01
.6323D-03	-.7266D-01	.7119D-01	.5105D+00	-.2549D+00	.2620D+00	-.7613D+00	-.7247D-01	-.9844D-01	.3035D-01
-.7922D-02	.9103D+00	.3917D+00	.1262D+00	.8472D-02	.1740D+00	.3536D+00	.8061D-02	.1313D-01	.5510D-02

SVD ANALYSIS OF THE DYNAMIC MODEL
DATA FILE CONTAINING THE RESPONSE MATRIX: GRMA08.DAT
NUMBER OF RESPONSE VALUES: 10

DATE & TIME OF ANALYSIS: 11-JUL-79 16:30 22.5

GRAMMIAN MATRIX VALUES

.41200-01	-.10200-03	.22300-02	.10830-02	.26430-01	-.93640-02	.34990-03	.56390-02	-.70700-02	.99930-03
-.10200-03	.25230-04	-.55200-03	-.26800-03	-.65400-02	.23170-04	-.86600-04	-.13950-04	-.19480-04	-.24730-05
.22300-02	-.55200-03	.12070-03	.58620-02	.14310-02	-.50690-03	.18940-04	.30530-03	-.42610-03	.54100-04
.10830-02	-.26800-03	.58620-02	.28460-02	.69450-01	-.24610-03	.91970-03	.14820-03	-.20680-03	.26260-04
-.26430-01	-.65400-02	.14310-02	.69450-01	.16950-01	-.60060-02	.22440-03	.36170-02	-.50480-02	.64090-03
-.93640-02	.23170-04	-.50690-03	-.24610-03	-.60060-02	.21280-04	-.79530-04	-.12820-04	.17890-04	-.22710-05
.34990-03	-.86600-04	.18940-04	.91970-03	.22440-03	.79530-04	.29720-05	.47890-04	-.66840-04	.84870-05
.56390-02	-.13950-04	.30530-03	.14820-03	.36170-02	-.79530-04	.29720-05	.47890-04	-.66840-04	.84870-05
-.70700-02	.19480-04	-.42610-03	-.20680-03	-.50480-02	.17890-04	-.66840-04	.77170-03	.10770-04	.13680-05
.99930-03	-.24730-05	.54100-04	.26260-04	.64090-03	-.22710-05	.84870-05	.13680-05	-.19090-05	.24230-06

SINGULAR VALUES FROM GRAMMIAN DECOMPOSITION

SVD 1)=	0.9275977894753231770-14
SVD 2)=	0.2791483306959489090-06
SVD 3)=	0.1396143072396779790-12
SVD 4)=	0.3312295850612974000-13
SVD 5)=	0.3107145769550693260-13
SVD 6)=	0.1497518147310723800-13
SVD 7)=	0.2055698591579721890-13
SVD 8)=	0.8521383614587422450-15
SVD 9)=	0.6822244701180049560-15
SVD 10)=	0.1695094697515940650-17

MATRIX U - ORTHONORMALIZED COLUMNS

.14300-02	.38420-02	-.13040-00	.68470-01	-.96200-02	-.76280-01	.89940-01	-.59830-00	-.76530-00	.14350-00
-.75620-01	-.95070-01	-.17810-00	-.59280-00	-.77340-00	-.54900-02	-.54480-01	-.14180-01	-.31220-02	.27890-01
-.36680-01	.20800-01	-.31220-00	.30980-00	-.17170-00	.71540-00	.13380-00	-.36980-00	.32610-00	.50430-01
.10330-01	.10100-01	.52070-01	-.11670-00	.77180-01	-.48590-00	.71110-01	-.65970-00	.51860-00	-.17960-00
.11100-02	.24640-02	-.36510-01	.20850-01	-.44750-01	.12330-00	.20100-01	.12280-01	-.19300-00	-.97120-00
-.26610-00	-.87320-01	-.65130-00	-.41950-00	.52140-00	.58420-01	-.21460-00	.25110-01	.13810-01	-.85020-02
.88880-00	.32630-00	-.19730-00	.15950-00	.53510-01	.58420-01	-.18200-00	-.15810-01	.84800-02	.45180-02
-.50020-01	.52580-01	-.52200-00	.57140-00	-.29790-00	-.43370-00	-.31130-00	.14240-00	.35420-01	-.21030-01
-.92850-01	-.73390-01	.33370-00	.16280-01	-.61760-02	.19090-00	-.88830-00	-.22060-00	-.82360-02	-.75130-02
-.34770-00	.93180-00	.52670-01	-.80810-01	-.29320-01	.14960-01	-.18540-01	-.11290-02	-.13870-01	.38590-02

MATRIX V - ORTHOGONAL MATRIX

.10000-01	.38420-02	.00000-00	.00000-00	.00000-00	.00000-00	.00000-00	.00000-00	.00000-00	.00000-00
.36530-03	-.95070-01	.11830-00	-.81510-01	-.27060-00	-.91710-00	-.23230-00	-.35410-01	-.17360-01	-.21630-01
-.79900-04	.20800-01	.25800-01	.10510-01	-.10860-00	-.24010-01	.32310-00	-.91940-01	-.87480-00	-.33170-00
-.36790-04	.10100-01	.11770-01	.76330-01	.11200-00	-.44530-01	.12380-00	.91760-00	-.15400-00	.31350-00
-.94670-05	.24640-02	-.11600-02	.81330-02	-.14940-01	-.50550-03	.85850-02	-.35600-00	-.29390-00	.86900-00
.33550-03	-.87320-01	.14600-00	.63310-00	.23410-00	.75380-01	-.65540-00	.46770-01	-.24780-00	-.58270-01
-.12540-02	.32630-00	-.91790-00	.98170-01	.39050-01	-.13890-00	-.12790-00	.10900-01	-.60790-01	-.16960-01
-.20200-03	.52580-01	-.18910-01	-.47420-00	-.56200-00	.343				

SVD ANALYSIS OF THE DYNAMIC MODEL
DATA FILE CONTAINING THE RESPONSE MATRIX: NORM03.DAT
NUMBER OF RESPONSE VALUES: 10

DATE & TIME OF ANALYSIS: 13-JUL-79 11:11 23.8

GRAMMIAN MATRIX VALUES

.44800+04	.16690+04	.45600+04	.48300+04	.53500+04	.22100+04	.50360+04	.60180+04	.64040+04	.22960+04
.16690+04	.62170+03	.16990+04	.17990+04	.19930+04	.82330+03	.18760+04	.22420+04	.23850+04	.85520+03
.45600+04	.16990+04	.46420+04	.49160+04	.54460+04	.22500+04	.51260+04	.61260+04	.65180+04	.23370+04
.48300+04	.17990+04	.49160+04	.52070+04	.57680+04	.23830+04	.54290+04	.64880+04	.69030+04	.24750+04
.53500+04	.19930+04	.54460+04	.57680+04	.63890+04	.26390+04	.60140+04	.71870+04	.76470+04	.27410+04
.22100+04	.82330+03	.22500+04	.23830+04	.26390+04	.10900+04	.24840+04	.29690+04	.31590+04	.11320+04
.50360+04	.18760+04	.51260+04	.54290+04	.60140+04	.24840+04	.56610+04	.67640+04	.71980+04	.25800+04
.60180+04	.22420+04	.61260+04	.64880+04	.71870+04	.29690+04	.67640+04	.80830+04	.86010+04	.30840+04
.64040+04	.23850+04	.65180+04	.69030+04	.76470+04	.31590+04	.71980+04	.86010+04	.91520+04	.32810+04
.22960+04	.85520+03	.23370+04	.24750+04	.27410+04	.11320+04	.25800+04	.30840+04	.32810+04	.11760+04

SINGULAR VALUES FROM GRAMMIAN DECOMPOSITION

SVD 1)=	0.461324197340150311D-13
SVD 2)=	0.465030202253422830+05
SVD 3)=	0.91080278710+0696280-13
SVD 4)=	0.7672726603301140510-13
SVD 5)=	0.5117297439627882980-13
SVD 6)=	0.7540460760846262670-13
SVD 7)=	0.3125248235213901160-13
SVD 8)=	0.1175831374841313980-13
SVD 9)=	0.1561689640375304730-13
SVD 10)=	0.3647653629816392800-14

MATRIX U - ORTHONORMALIZED COLUMNS

-.58920+00	-.31040+00	.26720+00	-.26150+00	-.46170+00	.10730+00	.11920+00	.17930+00	-.38160+00	.84050-02
-.20190-01	-.11560+00	.80220-02	-.13810+00	-.46170+00	-.18060+00	.17930+00	-.48680+00	.56330+00	.37030+00
-.33040+00	-.31590+00	-.20530+00	-.22070+00	.54470+00	.44610+00	-.79910-01	-.23760-01	.21330+00	.38990+00
-.22720+00	-.33460+00	-.37640+00	-.53220+00	.15220+00	-.28400+00	.26600+00	-.28000+00	-.29580+00	-.26650+00
-.29270+00	-.37070+00	-.38340+00	.35770+00	.18730+01	-.52510+00	-.90710-02	.39450+00	.25010+00	-.87750-01
.16570+00	-.15310+00	-.13350+00	-.95020-01	.18870+00	-.17160+00	-.82520+00	-.65900-01	-.26110+00	.32200+00
.36070+00	-.34890+00	-.36230+00	.19910+00	-.40960+00	.59320+00	.39000-01	.13230+00	.69500-01	.18370+00
.51100-01	-.41690+00	.24500+00	.60100+00	.17370+00	-.28170-01	.15550+00	-.44330+00	-.35370+00	.16260+00
.42730+00	-.44360+00	.59170+00	-.21210+00	.12770+00	-.10450+00	-.10680-01	.36950+00	.24760+00	.20000-01
-.25170+00	-.15900+00	.19640+00	.56120-03	.59310-01	.86070-01	-.41180+00	-.37720+00	.28660+00	-.68400+00

MATRIX V - ORTHOGONAL MATRIX

.95060+00	-.31040+00	.00000+00	.00000+00	.00000+00	.00000+00	.00000+00	.00000+00	.00000+00	.00000+00
-.37750-01	-.11560+00	.11010+00	-.20590+00	-.26740+00	-.14110+00	.21290+00	.16410+00	-.81790-01	.87200+00
-.10320+00	-.31590+00	.60880+00	.24290+00	-.11800+00	.28080+00	.40750+00	-.80910-01	-.40330+00	-.17870+00
-.10930+00	-.33460+00	-.29620+00	-.24520+00	.16270+00	-.44320+00	-.12030+00	.57580+00	.23460+00	-.32300+00
-.12100+00	-.37070+00	.21540+00	-.30660+00	.77730+00	.41830-01	.19350+00	-.18110+00	.26780-01	.17500+00
-.49990-01	-.15310+00	-.11500+00	-.34190+00	-.46380+00	-.18070+00	-.38500+00	-.65490+00	-.11100+00	-.82330-01
-.11390+00	-.34890+00	.27450+00	.58980+00	.19920+00	-.58720+00	-.46670-01	.12000+00	-.25220+00	.71530-01
-.113610+00	-.41690+00	.12260+00	.30510+00	-.22030+00	.54310+00	-.51620+00	.18760+00	.17530+00	.15380+00
-.14490+00	-.44360+00	.60860+00	-.38260+00	-.71780-01	.16790+00	.42950+00	.19720-02	-.10930+00	-.18690+00
-.51930-01	-.15900+00	-.96000-01	.20040+00	-.55870-01	-.49970-01	.36790+00	-.35180+00	.81010+00	.39030-01

SVU ANALYSIS OF THE DYNAMIC MODEL
DATA FILE CONTAINING THE RESPONSE MATRIX: NORM05.DAT
NUMBER OF RESPONSE VALUES: 10

DATE & TIME OF ANALYSIS: 13-JUL-79 11:20 41.4

GRAMMIAN MATRIX VALUES

.43540+04	.16850+04	.44170+04	.47200+04	.52630+04	.51060+04	.59160+04	.62860+04	.33410+04
.16950+04	.65200+03	.17090+04	.18270+04	.20370+04	.19760+04	.22890+04	.24330+04	.12930+04
.44170+04	.17090+04	.44800+04	.47880+04	.53390+04	.51800+04	.60010+04	.63770+04	.33690+04
.47200+04	.18270+04	.47880+04	.51180+04	.57060+04	.55360+04	.64140+04	.68150+04	.36220+04
.52330+04	.20370+04	.53390+04	.57060+04	.63620+04	.61720+04	.75990+04	.75990+04	.40360+04
.26630+04	.10310+04	.27010+04	.28870+04	.32190+04	.31230+04	.36180+04	.38450+04	.20430+04
.51060+04	.19760+04	.51800+04	.55360+04	.60010+04	.59880+04	.69380+04	.73730+04	.39180+04
.59160+04	.62860+04	.64140+04	.68150+04	.75990+04	.73730+04	.80380+04	.85410+04	.45390+04
.33410+04	.12930+04	.33690+04	.36220+04	.40360+04	.39180+04	.45390+04	.48230+04	.25630+04

SINGULAR VALUES FROM GRAMMIAN DECOMPOSITION

SV(1)= 0.3247704612866402610-12
SV(2)= 0.4826071845963315200+05
SV(3)= 0.2692913335739031510-12
SV(4)= 0.137017933150088730-12
SV(5)= 0.241563176680412210-12
SV(6)= 0.7656787114615154370-13
SV(7)= 0.1104460934396717190-12
SV(8)= 0.618661622573266570-13
SV(9)= 0.716367317949495420-13
SV(10)= 0.3497952001506484220-13

MATRIX U - ORTHONORMALIZED COLUMNS

-.31010+04	-.30040+00	-.81960+01	.18610+00	-.46080+00	-.15720+00	-.10800+00	-.44460+00	.38330+00	-.42300+00
-.25940+01	-.11620+00	.16300+00	.12750+00	.93240+01	-.35650+00	.11640+00	.67680+01	.62960+00	.62660+00
.49500+00	-.30470+00	.24520+01	-.60410+00	-.27980+00	-.36750+00	-.32450+00	-.11100+00	-.16120+00	.14360+00
.17470+00	-.32560+00	.73530+01	-.26800+01	-.81650+01	.59150+00	-.39340+00	.42900+00	.37990+00	-.74680+01
-.26950+00	-.36310+00	.39970+00	.25000+00	-.42520+00	.15520+00	.12520+00	.75620+01	-.46830+00	.35740+00
-.92500+01	-.18370+00	-.13950+01	-.17560+00	-.13070+00	-.34320+00	.47540+00	.65100+00	.41310+01	-.37450+00
-.98330+01	-.35230+00	-.47140+00	.41650+00	.28460+00	.32150+00	-.41320+00	.22260+00	-.25210+00	.49300+01
.19890+00	-.40810+00	.57150+00	.10040+00	.54670+00	-.86530+01	.66220+01	-.21140+00	-.39770+01	-.31660+00
-.38500+00	-.43370+00	-.35350+00	-.45430+00	.30200+00	.29740+00	.28740+00	-.20300+00	.11230+01	.16950+00
.65580+00	-.23050+00	-.35630+00	.31650+00	-.115860+00	.14890+00	.46400+00	-.11580+00	-.11970+02	.52830+01

MATRIX V - ORTHOGONAL MATRIX

.95390+00	-.30040+00	.00000+00	.00000+00	.00000+00	.00000+00	.00000+00	.00000+00	.00000+00	.00000+00
-.36600+01	-.11620+00	-.15200+01	-.10580+00	.45060+01	-.30410+00	.36560+00	-.61860+00	.59690+00	.81020+01
-.95940+01	-.30470+00	.33400+00	-.44760+00	-.47090+00	.50060+00	.15100+00	-.10050+00	-.34370+02	-.28410+00
-.10250+00	-.32560+00	.14900+00	.10430+00	.36250+00	-.14860+00	-.24420+00	.23530+00	.33590+00	-.68490+00
-.11430+00	-.36310+00	-.39200+00	-.47780+00	-.38070+01	-.30240+00	-.51310+00	-.22490+00	-.25050+00	.60000+01
-.57850+01	-.18370+00	-.13110+00	-.31370+00	-.17420+00	-.25490+00	.26790+00	.70700+00	.31500+00	.28470+00
-.11090+00	-.35230+00	-.52510+00	.11030+00	.28390+00	.20920+00	.56720+00	-.88270+02	-.31770+00	-.16950+00
-.12850+00	-.40810+00	.61940+00	.12420+00	.13890+00	.17680+00	.17680+00	-.25410+01	-.41490+00	.24470+00
-.13660+00	-.43370+00	-.16470+00	-.64310+00	-.48780+00	.90980+01	-.21170+00	-.24460+01	.18180+00	.16710+00
-.72570+01	-.23050+00	.93290+01	-.98210+01	.52470+00	.54000+00	-.22590+00	.76050+02	.25070+00	.49240+00

SVU ANALYSIS OF THE DYNAMIC MODEL
DATA FILE CONTAINING THE RESPONSE MATRIX: NORM06.DAT
NUMBER OF RESPONSE VALUES: 10

DATE & TIME OF ANALYSIS: 13-JUL-79 1123 34.7

GRAMMIAN MATRIX VALUES

.95220+04	.13840+03	.96400+04	.95570+04	.94740+04	.13750+03	.94820+04	.94810+04	.94660+04	.94630+04
.13840+03	.20110+01	.14010+03	.13890+03	.13770+03	.13780+03	.13780+03	.13780+03	.13760+03	.13750+03
.96400+04	.14010+03	.97580+04	.96740+04	.95910+04	.13920+03	.95990+04	.95980+04	.95830+04	.95800+04
.95570+04	.13890+03	.96740+04	.95910+04	.95080+04	.13800+03	.95160+04	.95150+04	.95000+04	.94970+04
.94740+04	.13770+03	.95910+04	.95080+04	.94260+04	.13680+03	.94340+04	.94330+04	.94180+04	.94150+04
.13750+03	.13920+03	.13800+03	.13680+03	.13680+03	.13690+03	.94410+04	.94410+04	.94260+04	.94230+04
.94820+04	.13780+03	.95990+04	.95160+04	.94340+04	.13690+03	.94410+04	.94410+04	.94260+04	.94230+04
.94810+04	.13780+03	.95990+04	.95160+04	.94340+04	.13690+03	.94410+04	.94410+04	.94260+04	.94230+04
.94660+04	.13760+03	.95830+04	.95000+04	.94180+04	.13670+03	.94260+04	.94250+04	.94110+04	.94070+04
.94630+04	.13750+03	.95800+04	.94970+04	.94150+04	.13660+03	.94230+04	.94220+04	.94070+04	.94040+04

SINGULAR VALUES FROM GRAMMIAN DECOMPOSITION

SV(1)= 0.3117657524307150120-12
SV(2)= 0.7599812517232121240-05
SV(3)= 0.3354816839297120350-12
SV(4)= 0.198769326693304370-12
SV(5)= 0.3469072194847585650-12
SV(6)= 0.9688238131608547950-13
SV(7)= 0.1531435257338668560-12
SV(8)= 0.1151476424029133070-12
SV(9)= 0.3076707086714111430-15
SV(10)= 0.7005515677367564670-16

MATRIX U - ORTHONORMALIZED COLUMNS

-.76560+00	-.35400+00	-.18270+00	.28750+00	-.10930+00	.20420+00	.28250+00	-.19610+00	.23730+01	-.71240-02
-.12240-02	-.51440-02	-.28980-02	.11600-02	-.21150-02	-.18860-01	-.31270-01	.59900-01	.63670+00	-.76790+00
.25140+00	-.35830+00	-.36500+00	-.56980+00	.26000+00	.48200+01	.46410+00	-.25040+00	.50460-01	.40310-02
.63160-01	-.35520+00	.71280+00	-.15650+00	.52930+02	.52460+00	.12040+00	.21790+00	-.28480-02	-.38110-02
.11270+00	-.35220+00	-.41180+00	.11670+00	-.11890+00	.59460-02	-.84490-03	.61210+00	-.79310-01	.17140-02
-.21390-02	-.51100-02	.12290-02	.16160-01	-.94580-02	-.87910-02	-.29810-01	.67140-01	.76420+00	.64040+00
.24170+00	-.35250+00	.10650+00	.58400+00	.64270+00	-.19290+00	-.77580-02	.12050+00	.31920-02	.10110-02
.36720+00	-.35240+00	.12380+00	.22160+00	-.69350+00	.30490+00	.17100+00	.27040+00	.15970-01	-.37730-02
-.36380+00	-.35190+00	.26250+00	-.39770+00	.82720-01	-.64930+00	-.27730+00	.10170+00	-.30350-01	.11130-01
.91520-01	-.35180+00	-.24520+00	-.77730-01	-.72940-01	.35840+00	-.76300+00	-.29280+00	-.22540-02	.78260-03

MATRIX V - ORTHOGONAL MATRIX

.93530+00	-.35400+00	.00000+00	.00000+00	.00000+00	.00000+00	.00000+00	.00000+00	.00000+00	.00000+00
-.19470-02	-.51440-02	.20740-02	-.32310-02	.65440-02	.50470-02	-.74690-02	.52380-02	.99300+00	-.11730+00
-.13560+00	-.35830+00	-.19880+00	.43670-01	.45620-01	-.56800+00	-.60790+00	.34290+00	-.53480-02	.96720+04
-.13450+00	-.35520+00	.66580-01	-.24630-01	-.70350+00	-.35430+00	.27100+00	-.39550+00	.61870-02	-.17370-01
-.13330+00	-.35220+00	-.83450-01	.19180+00	.50650+00	-.29400+00	.66340+00	.17680+00	-.16770-02	-.11470-01
-.19340-02	-.51100-02	.38650-02	.55220-02	-.39850-02	-.15070-01	.13810-01	.74440-02	.11750+00	.99280+00
-.13340+00	-.35250+00	-.68030+00	-.34270+00	.10190+00	.50740+00	-.79930-01	-.59540-01	-.33220-02	.55360-02
-.13340+00	-.35240+00	.90420-02	.80590+00	-.83760-01	.31630+00	.14930+00	.28120+00	-.11230-02	-.18910-02
-.13320+00	-.35190+00	.65670+00	-.42080+00	-.12020+00	.31570+00	-.11410+00	.35040+00	-.69050-02	.12170-01
-.13310+00	-.35180+00	.23440+00	.12920+00	.46310+00	.89880-01	-.27400+00	-.69940+00	-.39870-02	.38760-03

SU ANALYSIS OF THE DYNAMIC MODEL
DATA FILE CONTAINING THE RESPONSE MATRIX: NORMOT.DAT
NUMBER OF RESPONSE VALUES: 10

DATE & TIME OF ANALYSIS: 13-JUL-79 11:06 14.9

GRAMMIAN MATRIX VALUES

.9522D+00	.1385D+03	.9639D+04	.9556D+04	.974D+04	.3371D+02	.9479D+04	.9481D+04	.9467D+04	.9455D+04
.1385D+03	.2016D+01	.1402D+03	.1390D+03	.1378D+03	.4905D+00	.1379D+03	.1379D+03	.1377D+03	.1376D+03
.9639D+04	.1402D+03	.9758D+04	.9674D+04	.9590D+04	.3413D+02	.9590D+04	.9597D+04	.9584D+04	.9572D+04
.9556D+04	.1390D+03	.9674D+04	.9590D+04	.9508D+04	.3384D+02	.9513D+04	.9515D+04	.9501D+04	.9489D+04
.974D+04	.1378D+03	.9590D+04	.9508D+04	.9426D+04	.3354D+02	.9431D+04	.9433D+04	.9419D+04	.9408D+04
.3371D+02	.4905D+00	.3413D+02	.3384D+02	.3354D+02	.1194D+00	.3356D+02	.3357D+02	.3352D+02	.3348D+02
.9479D+04	.1379D+03	.9596D+04	.9513D+04	.9431D+04	.3356D+02	.9437D+04	.9438D+04	.9425D+04	.9413D+04
.9481D+04	.1370D+03	.9597D+04	.9515D+04	.9433D+04	.3357D+02	.9438D+04	.9440D+04	.9426D+04	.9414D+04
.9467D+04	.1377D+03	.9584D+04	.9501D+04	.9419D+04	.3352D+02	.9426D+04	.9426D+04	.9413D+04	.9401D+04
.9455D+04	.1376D+03	.9572D+04	.9489D+04	.9408D+04	.3348D+02	.9413D+04	.9414D+04	.9401D+04	.9389D+04

SINGULAR VALUES FROM GRAMMIAN DECOMPOSITION

SV(1)= 0.197359495965125139D-12
SV(2)= 0.759765132477834408D-05
SV(3)= 0.521316858382380613D-13
SV(4)= 0.115479608411434804D-12
SV(5)= 0.106399682680523194D-12
SV(6)= 0.448952291870176315D-13
SV(7)= 0.451442456187554653D-13
SV(8)= 0.822658632112234239D-13
SV(9)= 0.410049876693856349D-16
SV(10)= 0.822505977484516012D-18

MATRIX U - ORTHONORMALIZED COLUMNS

.3634D+00	-.3540D+00	-.2080D+00	.4034D+01	.2466D+00	.4168D+00	-.4273D+00	.5290D+00	.2701D+01	.5999D+02
.2563D+02	-.5151D+02	.2267D+01	.2533D+01	-.3144D+01	-.1361D+01	-.3376D+01	.8767D+02	.9572D+00	-.2833D+00
-.6099D+00	-.3584D+00	-.1158D+00	.1052D+00	.2592D+00	-.3519D+00	-.5223D+00	-.1471D+00	.2190D+01	-.3444D+02
.3286D+00	-.3553D+00	.3543D+00	-.5055D+00	.3255D+00	-.2536D+01	-.2872D+01	-.4354D+00	.1947D+01	-.5911D+03
-.3109D+00	.3522D+00	-.3986D+00	-.5356D+00	-.1265D+00	-.4683D+01	.4566D+00	.3267D+00	-.6516D+03	.2418D+02
.2741D+03	-.1253D+02	.6189D+02	.1021D+01	-.9349D+02	-.1106D+01	.1046D+01	-.3160D+02	.2827D+00	.9590D+00
-.2626D+00	.3524D+00	.7368D+00	.8497D+01	-.3853D+00	.1787D+00	.7425D+02	.2743D+00	.3295D+01	.2795D+02
-.1100D+00	.3525D+00	-.2679D+00	.2751D+00	-.1691D+00	.5972D+00	.1532D+00	-.5546D+00	.1038D+03	.8151D+04
.4438D+00	.3520D+00	-.1895D+00	.1067D+00	-.6078D+00	-.4770D+00	-.1607D+00	-.9255D+01	-.2277D+01	-.3767D+02
.1553D+00	-.3515D+00	.8825D+01	.5124D+00	.4500D+00	-.2885D+00	.5336D+00	.1036D+00	-.2785D+01	-.2735D+02

MATRIX V - ORTHOGONAL MATRIX

.9352D+00	-.3540D+00	.0000D+00	.0000D+00	.0000D+00	.0000D+00	.0000D+00	.0000D+00	.0000D+00	.0000D+00
-.1950D+02	-.5151D+02	.4252D+02	-.2012D+02	-.5639D+02	.1493D+01	-.1045D+01	.1433D+00	.9741D+00	.1738D+00
-.1357D+00	-.3584D+00	.2893D+00	.4574D+00	.2177D+00	-.5059D+00	.4908D+00	.1265D+00	-.1093D+01	.8951D+02
-.1345D+00	-.3553D+00	.2778D+00	-.9166D+00	.1781D+00	.7757D+00	.2852D+00	.2306D+00	-.4588D+01	-.8165D+02
-.1333D+00	.3522D+00	.1280D+00	-.6719D+01	.5080D+00	-.1615D+01	-.3781D+00	-.6544D+00	.8759D+01	-.4999D+02
-.4745D+00	-.1253D+02	.2822D+03	.2621D+02	.2190D+02	.8386D+02	.6250D+02	-.2449D+01	-.1723D+00	.9847D+00
-.1334D+00	.3524D+00	-.3973D+00	.5838D+00	-.4804D+00	.2418D+00	-.7642D+01	-.2507D+00	.3604D+01	-.4800D+03
-.1334D+00	.3525D+00	-.4598D+00	-.6022D+00	.1289D+00	.2177D+00	.4553D+00	-.1659D+00	.3073D+01	.3693D+02
-.1332D+00	.3520D+00	.5472D+00	-.2724D+00	-.5801D+00	-.1883D+00	-.3230D+00	.9040D+01	-.1547D+01	-.6946D+03
-.1331D+00	-.3515D+00	-.3925D+00	-.1509D+01	.2807D+00	-.1280D+00	-.4661D+00	.6188D+00	-.9535D+01	-.4447D+02

SVD ANALYSIS OF THE DYNAMIC MODEL
DATA FILE CONTAINING THE RESPONSE MATRIX: NORM08.DAT
NUMBER OF RESPONSE VALUES: 10

DATE & TIME OF ANALYSIS: 13-JUL-79 11:26 38.6

GRAMMIAN MATRIX VALUES

.75080-02	-.83030-03	.95220-02	.46230-02	.11280-02	-.86580-03	.14940-04	.24070-03	-.33600-03	.42660-04
-.83030-03	.91820-04	-.10530-04	-.51120-03	-.12480-03	.95750-04	-.16520-05	-.26620-04	.37150-04	-.47170-05
.95220-02	-.10530-04	.12070-03	.58620-02	.14310-02	-.10980-04	.18940-04	.30530-03	-.42610-03	.54100-04
.46230-02	-.51120-03	.58620-02	.28460-02	.69450-01	-.53310-03	.91970-03	.14820-03	-.20680-03	.26260-04
.11280-02	-.12480-03	.14310-02	.69450-01	.16950-01	-.13010-03	.22440-03	.36170-02	-.50480-02	.64090-03
-.86580-03	.95750-04	-.10980-04	-.53310-03	-.13010-03	.99850-04	-.17230-05	-.27760-04	.38740-04	-.49190-05
.14940-04	-.16520-05	.18940-04	.91970-03	.22440-03	-.17230-05	.29720-05	.47890-04	-.66840-04	.84670-05
.42660-04	-.26620-04	.30530-03	.14820-03	.36170-02	-.27760-04	.47890-04	.77170-03	-.10770-04	.13680-05
-.33600-03	.37150-04	-.42610-03	-.20680-03	.50480-02	.38740-04	-.66840-04	.77170-03	.10770-04	.13680-05
.42660-04	-.47170-05	.54100-04	.26260-04	.64090-03	-.49190-05	.84670-05	.13680-05	-.19090-05	.24230-06

SINGULAR VALUES FROM GRAMMIAN DECOMPOSITION

SV(1)= 0.4382566030777477400-13
SV(2)= 0.2937344040533440870-06
SV(3)= 0.3182346155635657600-12
SV(4)= 0.1700369213663623150-12
SV(5)= 0.4982310767838956850-13
SV(6)= 0.3062650227960991030-13
SV(7)= 0.1327171653860731230-13
SV(8)= 0.1891503441313234400-14
SV(9)= 0.1900214947795770860-14
SV(10)= 0.5079547835758504210-17

MATRIX U - ORTHONORMALIZED COLUMNS

.11700-01	.15990-01	.73700-01	.58150-01	.55730-02	.51470-00	.74570-00	.27750-00	-.30460-00	-.21230-02
-.24110-00	-.17680-00	.57330-00	-.82660-01	.75230-00	-.24890-01	-.39450-01	-.50380-01	-.66310-01	.78160-02
.46340-01	.20280-01	-.12370-00	-.40030-01	.18520-01	-.47900-01	-.19260-01	.25310-01	-.86520-00	-.33560-01
.91220-02	.98430-02	-.25450-01	-.40000-01	.08290-01	-.33210-00	-.16350-01	.91140-00	.21760-00	.33960-01
.69670-02	.24020-02	-.33160-02	.55370-03	-.10500-01	.33910-02	-.63610-02	-.25550-01	-.40580-01	.99870-00
-.41560-00	-.18440-00	-.25560-00	.84520-00	.10060-00	-.31500-01	-.18600-01	.15720-01	-.86420-02	.32080-02
.70590-00	.31810-00	.35550-00	.51090-00	.80380-01	-.33640-01	-.74020-01	.23320-02	.70720-02	-.45320-02
.43910-01	.51260-01	-.67430-01	.42690-03	.10080-00	.65790-00	.45550-01	-.25580-00	.32270-00	.12170-01
-.31690-00	-.71540-01	.67350-00	.10560-00	-.62470-00	.18940-00	.45550-01	.26570-01	-.28500-01	-.15530-02
-.40730-00	.90830-00	-.61960-02	-.114740-01	.84010-01	.24530-01	-.31590-01	-.39090-02	-.10220-01	.72810-03

MATRIX V - ORTHOGONAL MATRIX

.99390-00	.15990-01	.00000-00	.00000-00	.00000-00	.00000-00	.00000-00	.00000-00	.00000-00	.00000-00
.28270-02	-.17680-00	.14280-00	.68800-00	-.25880-00	-.75090-01	-.47480-00	.29900-00	-.36440-00	.21220-01
-.32420-03	.20280-01	-.25400-02	.13550-00	-.59160-00	.23950-00	.41570-01	.74420-00	.13520-00	.91010-02
-.15740-03	.98430-02	-.25150-02	.16940-00	-.39450-00	.13240-00	.11620-00	-.52130-00	.70850-00	.10400-00
-.38410-04	.24020-02	.19810-02	-.17160-01	.66240-02	-.70100-02	-.10900-01	.42220-01	.10390-00	.99340-00
.29480-02	-.18440-00	-.19800-00	.10550-00	.35000-00	.87080-00	-.18400-00	-.11730-01	.29160-01	.80050-02
-.50860-02	.31810-00	.90550-00	.47850-01	.15900-00	.21270-00	.49640-00	.31730-01	.50900-01	.32120-02
-.81960-03	.51260-01	.53620-01	-.38480-00	.79030-02	.12160-00	-.84400-00	.10160-00	.32980-00	-.13130-01
.11440-02	-.71540-01	-.62000-01	.52820-00	.52820-00	-.31170-00	.24870-01	.33990-00	.46720-00	-.38390-01
-.14520-01	.90830-00	-.33730-00	.19710-00	.23590-01	.63210-01	-.99720-01	-.44210-01	-.75080-01	.48990-02

SVD ANALYSIS OF THE DYNAMIC MODEL
DATA FILE CONTAINING THE RESPONSE MATRIX: NOR103.DAT
NUMBER OF RESPONSE VALUES: 10

DATE & TIME OF ANALYSIS: 16-JUL-79 14:07 05.1

GRAMMIAN MATRIX VALUES

.44800+00	.50250+04	.45600+04	.48300+04	.53500+04	.22100+04	.50360+04	.60180+04	.64040+04	.22960+04
.50250+04	.56350+04	.51140+04	.54170+04	.60000+04	.24790+04	.56480+04	.67490+04	.71810+04	.25750+04
.45600+04	.51140+04	.46420+04	.49160+04	.54460+04	.22500+04	.51260+04	.61260+04	.65180+04	.23370+04
.48300+04	.54170+04	.49160+04	.52070+04	.57680+04	.23830+04	.54290+04	.64880+04	.69030+04	.24750+04
.53500+04	.60000+04	.54460+04	.57680+04	.63890+04	.26390+04	.60140+04	.71870+04	.76470+04	.27410+04
.22100+04	.24790+04	.22500+04	.23830+04	.26390+04	.10900+04	.24840+04	.29690+04	.31590+04	.11320+04
.50360+04	.56480+04	.51260+04	.54290+04	.60140+04	.24840+04	.56610+04	.67640+04	.71980+04	.25800+04
.60180+04	.67490+04	.71810+04	.76470+04	.80830+04	.29690+04	.67640+04	.86010+04	.91520+04	.30840+04
.22960+04	.25750+04	.23370+04	.24750+04	.27410+04	.11320+04	.25800+04	.30840+04	.32810+04	.11760+04

SINGULAR VALUES FROM GRAMMIAN DECOMPOSITION

SV(1)= 0.9844518297551274290-13
SV(2)= 0.5151622842353854060+05
SV(3)= 0.9016884419292091260-13
SV(4)= 0.7118957656224595110-13
SV(5)= 0.514246656540258200-13
SV(6)= 0.1133772840184849750-12
SV(7)= 0.1280008947592676230-13
SV(8)= 0.4998789564030968790-13
SV(9)= 0.3595169421769443050-13
SV(10)= 0.1223525124188093480-13

MATRIX U - ORTHONORMALIZED COLUMNS

-.44230+00	.29490+00	.16700+00	.18550+00	-.36220+00	.16610+00	.60730+00	.35600+00	-.27400+01	.58730+02
-.50830+00	.33070+00	.93810+01	.24910+00	.11990+00	-.44880+00	-.27460+00	-.30850+00	-.40130+00	-.11830+00
-.17750+00	.30020+00	-.49760+00	.16720+00	.54330+00	.23270+00	-.41370+01	.19300+00	.10690+00	.45020+00
.21960+00	.31790+00	.15320+00	-.13160+00	.23050+00	.61140+00	.11560+01	-.97980+01	-.51090+00	-.33490+00
-.16910+00	.35220+00	-.29070+00	.35250+00	-.53320+00	.26890+00	-.29340+00	-.35700+00	.23640+00	.73630+01
.23690+00	.14550+00	-.52880+00	.34770+00	-.84990+02	.13790+00	.33260+00	-.24760+00	.18710+00	-.54420+00
.34100+00	.33150+00	-.28390+00	-.26480+00	-.22270+00	-.39530+00	-.10470+00	.52900+00	-.35500+00	.20650+01
.98320+01	.39610+00	.27200+00	.50230+00	.33670+00	.30610+00	.39380+00	-.23780+00	.28560+00	.82740+01
.45650+00	.42150+00	.38080+00	.53470+00	-.15970+00	.17550+01	-.20830+00	-.41450+01	.22360+00	.24950+00
-.20020+00	.15110+00	.16900+00	-.69230+01	.18230+00	.36200+01	-.38440+00	.45210+00	.46570+00	-.54780+00

MATRIX V - ORTHOGONAL MATRIX

.95550+00	.29490+00	.00000+00	.00000+00	.00000+00	.00000+00	.00000+00	.00000+00	.00000+00	.00000+00
-.10210+00	.33070+00	.51220+00	.80180+02	-.57710+00	.25690+00	.66380+02	.97180+02	-.43970+00	-.15880+00
-.92640+01	.30020+00	-.42480+00	-.34800+00	-.34060+00	-.62020+01	.53790+00	.35540+00	.86800+01	.23810+00
-.98120+01	.31790+00	-.43840+00	.36340+00	-.94680+01	.49010+01	.16120+00	-.43050+00	.11120+00	-.57440+00
-.10870+00	.35220+00	-.11530+00	.28720+01	.57950+00	.63200+00	.36970+01	.16540+00	-.27110+00	.11200+00
-.44900+01	.14550+00	-.88790+01	.18240+00	-.17350+00	.12760+00	-.51870+00	.63180+00	.41080+00	-.22880+00
-.10230+00	.33150+00	.30930+00	.56970+00	.11480+00	.11830+00	-.82310+01	-.32650+00	.55980+00	-.74340+01
-.12230+00	.39610+00	-.19650+00	-.27920+00	.15870+00	-.55410+00	-.44280+00	-.28370+02	-.42330+00	-.64110+01
-.13010+00	.42150+00	.38720+00	.51550+00	.21210+00	-.40110+00	.25600+00	.10340+00	.21000+00	.25190+00
-.46640+01	.15110+00	-.24420+00	.21060+00	-.30440+00	.17360+00	-.38190+00	-.38000+00	.88340+01	.67090+00

SVD ANALYSIS OF THE DYNAMIC MODEL
DATA FILE CONTAINING THE RESPONSE MATRIX: MOR105.DAT
NUMBER OF RESPONSE VALUES: 10

DATE & TIME OF ANALYSIS: 16-JUL-79 14114 16.9

GRAMMIAN MATRIX VALUES

.43540+0	.49140+0	.44170+0	.47200+0	.52630+0	.26630+0	.51060+0	.59160+0	.62860+0	.33410+0
.49140+0	.55450+0	.49840+0	.53270+0	.59400+0	.30050+0	.57630+0	.66760+0	.70950+0	.37700+0
.44170+0	.49840+0	.44800+0	.47880+0	.53390+0	.27010+0	.51800+0	.60010+0	.63770+0	.33890+0
.47200+0	.53270+0	.47880+0	.51180+0	.57060+0	.28870+0	.55360+0	.64140+0	.68150+0	.36220+0
.52630+0	.59400+0	.53390+0	.57060+0	.63620+0	.32190+0	.61720+0	.71510+0	.75990+0	.40380+0
.26630+0	.30050+0	.27010+0	.28870+0	.32190+0	.16290+0	.31230+0	.36180+0	.38450+0	.20430+0
.51060+0	.57630+0	.51800+0	.55360+0	.61720+0	.31230+0	.59880+0	.69380+0	.73730+0	.39180+0
.59160+0	.66760+0	.60010+0	.64140+0	.67150+0	.36180+0	.69380+0	.80380+0	.85410+0	.45390+0
.62860+0	.70950+0	.63770+0	.68150+0	.75990+0	.38450+0	.73730+0	.85410+0	.90770+0	.48230+0
.33410+0	.37700+0	.33890+0	.36220+0	.40380+0	.20430+0	.39180+0	.45390+0	.48230+0	.25630+0

SINGULAR VALUES FROM GRAMMIAN DECOMPOSITION

SV(1) =	0.3458369967783570960-12
SV(2) =	0.5315396742247342300+05
SV(3) =	0.3198111412345459370-12
SV(4) =	0.1815204665080948170-12
SV(5) =	0.1268634657436787650-12
SV(6) =	0.2326257646864556100-12
SV(7) =	0.5743265020118746010-13
SV(8) =	0.3367714935937077290-12
SV(9) =	0.5241917435843856980-13
SV(10) =	0.1262675488670735740-12

MATRIX U - ORTHONORMALIZED COLUMNS

-.33380+0	-.28620+0	.59910-01	-.36610+0	.43760-01	-.61890+0	.64220-01	-.44570+0	-.20120+0
.33040+0	-.32300+0	.15820+0	.44680+0	-.15250+0	-.45920+0	.37090+0	-.40660+0	.15290+0
.39100+0	-.29030+0	-.26140-01	.38380+0	-.17490+0	.10670+0	-.18290+0	.55120+0	-.45840+0
.11890+0	-.31030+0	-.13010+0	-.84830-01	-.16620+0	.25110+0	-.47040+0	-.40840+0	.25100+0
-.30520+0	-.34600+0	-.40180+0	-.11400+0	-.67290+0	.76490-01	.13270+0	.10880+0	.33080+0
-.10210+0	-.17510+0	-.95000-02	.43840-01	.12340+0	-.30880+0	-.66220+0	-.26240+0	.50710+0
-.87530-01	-.33570+0	.58470+0	.27740-02	.80130-01	.638820-01	-.18780+0	.38030+0	-.28600+0
.14940+0	-.38890+0	-.50310+0	-.26310-01	.62460+0	.12030-01	.12500+0	.16700+0	.56530+0
-.44390+0	-.41320+0	.24720+0	.16200+0	.22220+0	.45600+0	.26840+0	.25830+0	.22590+0
.53090+0	-.21960+0	.22190+0	-.68560+0	-.51450-01	.13490+0	.15680+0	-.11350+0	-.38530+0
								-.21680+0

MATRIX V - ORTHOGONAL MATRIX

.95820+0	-.28620+0	.00000+0	.00000+0	.00000+0	.00000+0	.00000+0	.00000+0	.00000+0
-.94480-01	.32300+0	.35320-01	.92170-01	.83440+0	-.19390+0	-.39330+0	.50440+0	.47100+0
-.86720-01	-.29030+0	-.45370+0	.30160+0	-.31340-01	.34320+0	-.36460+0	.52540-03	.57600+0
-.92680-01	.31030+0	-.24710+0	.36260+0	.45880+0	.25180-01	.36170+0	.88840-01	-.19340+0
-.10330+0	.34600+0	.28610+0	.39340+0	.12160+0	-.29020+0	.48540+0	.85910-01	.37660+0
-.52290-01	.17510+0	.15340+0	.47250+0	-.35110+0	.23500+0	-.25590+0	.94550-01	-.67200+0
-.10030+0	-.33570+0	.43440+0	.11660+0	.26530+0	.29170-01	-.30360+0	-.71430+0	.12410+0
-.11620+0	-.38890+0	-.56900+0	-.11970+0	-.20240+0	-.83940-01	-.42080+0	-.53190-01	.26060-01
-.12340+0	-.41320+0	.33570+0	-.50690+0	-.56730+0	.74840-01	.15830+0	.22900+0	-.44540+0
-.65590-01	-.21960+0	.36000-01	.32590+0	.42220-01	.89880+0	-.35820-01	.13690-01	-.88620-01

SVD ANALYSIS OF THE DYNAMIC MODEL
DATA FILE CONTAINING THE RESPONSE MATRIX: NOR106.DAT
NUMBER OF RESPONSE VALUES: 10

DATE & TIME OF ANALYSIS: 16-JUL-79 14:20 32.9

GRAMMIAN MATRIX VALUES

.95220+04	.96200+04	.96400+04	.95570+04	.94740+04	.13750+03	.94820+04	.94810+04	.94660+04	.94630+04
.96200+04	.97180+04	.97380+04	.96540+04	.95710+04	.13890+03	.95790+04	.95780+04	.95630+04	.95600+04
.96400+04	.97380+04	.97580+04	.96740+04	.95910+04	.13920+03	.95990+04	.95980+04	.95830+04	.95800+04
.95570+04	.96540+04	.96740+04	.95910+04	.95080+04	.13800+03	.95160+04	.95150+04	.95000+04	.94970+04
.94740+04	.95910+04	.95910+04	.95080+04	.94260+04	.13680+03	.94340+04	.94330+04	.94180+04	.94150+04
.13750+03	.13890+03	.13920+03	.13800+03	.13680+03	.13680+03	.13690+03	.13690+03	.13670+03	.13660+03
.94820+04	.95790+04	.95990+04	.95160+04	.94340+04	.94420+03	.94410+04	.94400+04	.94260+04	.94230+04
.94660+04	.95780+04	.95980+04	.95150+04	.94330+04	.13690+03	.94410+04	.94400+04	.94250+04	.94220+04
.94630+04	.95600+04	.95830+04	.95000+04	.94180+04	.13670+03	.94260+04	.94250+04	.94110+04	.94070+04
					.13660+03	.94230+04	.94220+04		.94040+04

SINGULAR VALUES FROM GRAMMIAN DECOMPOSITION

SV(1) = 0.3405116176739689930-12
SV(2) = 0.8571451918520546590+05
SV(3) = 0.368992576881258310-12
SV(4) = 0.2044062316755552350-12
SV(5) = 0.3798725196291068640-12
SV(6) = 0.2507696898811017450-12
SV(7) = 0.1461307091406241660-12
SV(8) = 0.2234775149287309090-12
SV(9) = 0.1227685185828153040-12
SV(10) = 0.1409430862683976450-15

MATRIX U - ORTHONORMALIZED COLUMNS

.65820+00	-.33330+00	-.31780+00	.30310+00	-.41040+01	-.49480+00	.68150+01	.10720+00	.15190+02	.14640+01
.27960+00	-.33670+00	.26080+01	.11950+00	-.23160+00	.54760+00	.75850+01	-.63760+00	.16620+00	.11890+01
-.34630+00	-.33740+00	-.45580+00	-.51640+00	.07850+01	-.29190+00	.22190+00	-.27410+00	.27260+00	.10710+01
-.84430+01	-.33450+00	.61260+00	.38920+01	.10870+01	.30050+00	-.34510+00	.10600+01	.54240+00	.17600+01
-.14910+00	-.33160+00	-.37270+00	.62600+02	.60590+01	.19190+00	-.79220+00	.13430+00	-.20550+00	-.23270+01
.19850+02	-.48120+02	-.15040+02	.17540+01	-.78570+02	-.96680+02	.19450+01	-.53510+02	.37480+01	-.99880+00
-.28030+00	-.33190+00	.22280+01	.48460+00	.71200+00	.85810+01	.18210+00	-.60230+01	-.15800+00	.10280+02
-.36380+00	-.33190+00	.22240+00	.16020+00	-.55730+00	-.24500+00	.21010+00	-.62100+01	-.51350+00	.47330+02
.35220+00	-.33130+00	.34640+00	-.60390+00	.27790+00	.10370+00	.38010+01	.11240+00	-.42270+00	-.27740+01
-.66220+01	-.33120+00	-.79610+01	.11760+01	-.19600+00	.40580+00	.33850+00	.68450+00	.30480+00	.13770+01

MATRIX V - ORTHOGONAL MATRIX

.94280+00	-.33330+00	.00000+00	.00000+00	.00000+00	.00000+00	.00000+00	.00000+00	.00000+00	.00000+00
-.11900+00	-.33670+00	-.39640+00	-.38880+01	-.91020+01	-.79440+00	-.25670+00	.00000+00	.00000+00	.00000+00
-.11930+00	-.33740+00	-.10100+00	-.12090+01	.16530+00	.82170+01	.24580+00	.71600+01	.55860+01	.18340+01
-.11830+00	-.33450+00	.28400+00	-.18160+01	-.68400+00	-.85400+01	.50470+00	.72970+00	.48410+00	.17170+01
-.11720+00	-.33160+00	-.22180+01	-.35140+00	.52440+00	.27620+01	.13160+00	-.24810+01	.24980+00	.18740+01
-.17010+02	-.48120+02	.31130+02	.74660+02	-.10660+01	-.25570+01	.20580+01	.97390+01	-.67060+00	.91300+02
-.11730+00	-.33190+00	-.62620+00	-.15070+00	.22770+00	.55660+00	.63400+01	-.13080+01	.90200+02	-.99920+00
-.11730+00	-.33190+00	.91320+01	.78330+00	.87180+02	.16190+00	-.37070+00	.29990+00	.73340+01	.13160+01
-.11710+00	-.33130+00	.54510+00	-.43440+00	-.91850+01	.11940+00	-.56740+00	.44170+01	.20940+00	-.51510+02
-.11710+00	-.33120+00	.23200+00	-.22260+00	.40130+00	-.56670+01	.37130+00	.58470+00	.35940+00	.31410+02

SVD ANALYSIS OF THE DYNAMIC MODEL
DATA FILE CONTAINING THE RESPONSE MATRIX: N0H107.DAT
NUMBER OF RESPONSE VALUES: 10

DATE & TIME OF ANALYSIS: 16-JUL-79 14126 22.5

GRAMMIAN MATRIX VALUES

.95220+00	.96190+00	.96390+00	.95560+00	.94740+00	.33710+02	.94790+00	.94810+00	.94670+00	.94550+00
.96190+00	.97180+00	.97380+00	.96540+00	.95710+00	.34060+02	.95760+00	.95780+00	.95640+00	.95520+00
.96390+00	.97380+00	.97580+00	.96740+00	.95900+00	.34130+02	.95960+00	.95970+00	.95840+00	.95720+00
.95560+00	.96540+00	.96740+00	.95900+00	.95080+00	.33840+02	.95130+00	.95150+00	.95010+00	.94890+00
.94740+00	.95710+00	.95900+00	.95080+00	.94260+00	.33540+02	.94310+00	.94330+00	.94190+00	.94080+00
.33710+02	.34060+02	.34130+02	.33840+02	.33540+02	.11940+00	.33560+02	.33570+02	.33520+02	.33480+02
.94790+00	.95760+00	.95960+00	.95130+00	.94310+00	.33560+02	.94370+00	.94380+00	.94250+00	.94130+00
.94550+00	.95520+00	.95720+00	.95010+00	.94190+00	.33520+02	.94250+00	.94260+00	.94140+00	.94010+00
					.33480+02	.94130+00	.94140+00		.93890+00

SINGULAR VALUES FROM GRAMMIAN DECOMPOSITION

SV(1)= 0.2021054177505708110-12
SV(2)= 0.8539257528775645280+05
SV(3)= 0.1001790650883269860-12
SV(4)= 0.1718591140876482320-12
SV(5)= 0.9474219905370792430-13
SV(6)= 0.9233297229663280710-13
SV(7)= 0.578432283473418000-13
SV(8)= 0.5041364704808871940-13
SV(9)= 0.7376577329710454180-13
SV(10)= 0.4385854001510889210-18

MATRIX U - ORTHONORMALIZED COLUMNS

.32990+00	-.33330+00	.24270+00	.14520+00	.14180+00	-.11250+00	.46900+01	-.26370+00	.77170+00	.38500+03
.11360+00	-.33680+00	-.85250+00	.19850+00	-.85870+01	-.21550+00	.28440+01	-.22310+00	-.56790+01	.43980+02
-.60450+00	-.33740+00	.67780+01	.53730+01	.59010+00	-.29480+00	.25750+00	.94570+01	-.53250+01	.31380+02
.30440+00	-.33450+00	.10090+00	-.68310+00	.22550+00	.53600+01	.66780+02	.38370+00	.34300+00	.35810+02
-.29830+00	-.33170+00	.22850+00	-.17110+02	.68340+00	.33890+01	.47850+00	-.21920+00	.60240+01	-.25170+02
.82660+00	-.11800+02	.26810+02	.16350+03	.32900+02	-.36220+02	.10320+02	-.52080+02	-.22680+02	.10000+01
-.28400+00	-.33180+00	-.20930+00	-.47650+00	.18560+00	.23180+00	-.34120+00	.44150+00	.37270+00	.35770+02
-.16730+00	-.33190+00	.26120+00	.34860+00	-.4690+01	-.20630+01	.73570+00	-.24700+00	.24570+00	.20070+02
.43930+00	-.33140+00	.18730+00	.77340+01	-.13220+00	-.44150+00	.52280+01	.62100+00	-.23540+00	.17840+02
.17220+00	-.33100+00	-.16740+01	.33980+00	.21310+00	.77520+00	.26330+00	.18690+00	-.14970+00	-.22320+02

MATRIX V - ORTHOGONAL MATRIX

.94280+00	-.33330+00	.00000+00	.00000+00	.00000+00	.00000+00	.00000+00	.00000+00	.00000+00	.00000+00
-.11910+00	-.33680+00	-.16900+00	.27020+00	-.30650+00	.14790+00	.20550+00	.68680+00	.35700+00	-.11700+00
-.11930+00	-.33740+00	-.29000+00	.38070+00	.30700+00	.23940+01	.58980+00	.44690+00	.24710+02	.21310+01
-.11730+00	-.33450+00	-.22020+00	.27470+00	.50210+00	.23140+00	.44880+00	.25630+00	.40740+00	.10700+00
-.11730+00	-.33170+00	-.86830+01	-.820710+00	.51270+00	.46740+00	.45040+00	.62940+01	.35310+00	.11410+00
-.41730+00	-.11800+02	.25140+03	.35860+02	-.85260+02	.83830+02	-.22030+01	.13510+01	.28600+00	.95780+00
-.11730+00	-.33180+00	.35560+00	.34610+00	.11410+00	.67390+00	.33350+00	.56180+01	.21010+00	.64550+01
-.11730+00	-.33190+00	.54610+00	.39530+00	.40940+00	.16040+00	.27990+00	.31620+00	.21590+00	.57720+01
-.11720+00	-.33140+00	-.50970+00	-.61940+00	-.48750+01	.46380+00	.26030+01	.62890+01	.98490+01	.34740+01
-.11700+00	-.33100+00	.38330+00	-.63450+01	.33750+00	.10220+00	.12220+00	.38940+00	.63220+00	.18790+00

SVD ANALYSIS OF THE DYNAMIC MODEL
DATA FILE CONTAINING THE RESPONSE MATRIX: MORIO8.DAT
NUMBER OF RESPONSE VALUES: 10

DATE & TIME OF ANALYSIS: 16-JUL-79 14:31 09.5

GRAMMIAN MATRIX VALUES

.75080+02	-.36200+02	.95220+02	.46230+02	.11280+02	-.86580+03	.14940+04	.24070+03	-.33600+03	-.42660+04
-.36200+02	-.17450+02	-.45910+02	-.22290+02	-.54390+01	.41740+03	-.72020+03	-.11610+03	.16200+03	-.20570+04
.95220+02	-.45910+02	.12070+03	.58620+02	.14310+02	-.10980+04	.18940+04	.30530+03	-.20680+03	.54100+04
.46230+02	-.22290+02	.58620+02	.28460+02	.69450+01	-.53310+03	.91970+03	.14820+03	-.20680+03	.26260+04
.11280+02	-.54390+01	.14310+02	.69450+01	.16950+01	-.13010+03	.22440+03	.36170+02	-.50480+02	.64090+03
-.86580+03	.41740+03	-.10980+04	-.53310+03	-.13010+03	.99850+04	-.17230+05	-.27760+04	.38740+04	-.49190+05
.14940+04	-.72020+03	.18940+04	.91970+03	.22440+03	-.17230+05	.29720+05	.47890+04	-.66840+04	.84870+05
.24070+03	-.11610+03	.30530+03	.14820+03	.36170+02	-.27760+04	.47890+04	.77170+03	-.10770+04	.13680+05
-.33600+03	.16200+03	-.42660+04	-.20680+03	-.50480+02	.38740+04	-.66840+04	.10770+04	.15030+04	-.19090+05
.42660+04	-.20570+04	.54100+04	.26260+04	.64090+03	-.49190+05	.84870+05	.33600+03	-.19090+05	.24230+06

SINGULAR VALUES FROM GRAMMIAN DECOMPOSITION

SV(1)= 0.41672244414692020D-13
SV(2)= 0.204569922460461163D-06
SV(3)= 0.26037130715164749D-12
SV(4)= 0.132110061409690292D-12
SV(5)= 0.39042856409663698D-13
SV(6)= 0.63253460937606188D-14
SV(7)= 0.384726054816323293D-14
SV(8)= 0.163595770109429096D-15
SV(9)= 0.169278279503864030D-15
SV(10)= 0.104600132962718392D-16

MATRIX U - ORTHONORMALIZED COLUMNS

.94540-04	.16240-01	.93420-01	.82310-01	.10380+00	-.35350+00	.90600+00	-.73430-02	-.16570+00	.77260-02
-.21540-01	-.78310-02	.14160-01	.52090-02	.26190-01	.14290+00	-.10530+00	.32920+00	-.85330+00	.36120+00
.48590-01	.20600-01	-.16260+00	-.13470+00	-.69820+00	.50240+00	.27720+00	-.59640+00	-.15030+00	-.14050+00
.10390-01	.10000-01	.32360-01	-.48560-01	-.21600+00	.21920+00	.19590+00	.81760+00	.39960+00	.18770+00
.73020-02	.24410-02	-.59550-02	-.72810-02	-.28350-01	.39650-01	.53590-01	-.35650+00	.24200+00	.84940+00
-.43730+00	-.14730+00	-.23970+00	.83340+00	-.14040+00	.39860-01	-.87730-02	-.44930-02	.24200+00	-.21690-02
.74060+00	.32320+00	.25550+00	.51740+00	-.79010-01	.73240-01	.89230-01	-.29000-03	.14670-01	-.10220-03
.47810-01	.52080-01	-.99840-01	-.60680-01	-.61360+00	-.73720+00	-.21290+00	.87640-01	-.54770-01	.73640-01
-.33390+00	-.72680-01	.90960+00	.29420-01	-.22380+00	.42310-01	.46480-01	.22450-01	.17210-01	-.10510-01
-.37870+00	.92280+00	-.58380-01	-.36870-02	.32560-01	.21110-01	-.14790-02	-.59030-02	.15210-02	-.24120-02

MATRIX V - ORTHOGONAL MATRIX

.99900+00	-.16240-01	.00000+00	.00000+00	.00000+00	.00000+00	.00000+00	.00000+00	.00000+00	.00000+00
.12720-03	-.78310-02	-.11650-01	.37380-01	.39800-01	.85630-02	-.33950+00	-.81250+00	.19820+00	-.42630+00
-.33460-03	.20600-01	-.55200-02	-.96730-02	.32400+00	-.16460+00	.83360+00	-.31250+00	-.22930+00	-.14900+00
-.16250-03	.10000-01	.59320-02	.23210-01	.13800+00	-.93640-01	.15510+00	.21460+00	.71090+00	.62920+00
-.39650-04	.24410-02	.20960-02	-.13020-01	.39660-02	.10740-01	.21060+00	.39680+00	.63290+00	-.63040+00
.30430-02	-.14730+00	.18850+00	.82600+00	.40770+00	.25970+00	-.68080-01	.90470-01	-.26090-01	-.34090-02
-.52500-02	.32320+00	.26690+00	.26690+00	.15790-01	.18550-01	-.45290-02	-.46250-02	-.11040-02	-.63590-02
-.84600-03	.52040-01	.56780-01	-.32770+00	.16170+00	.91850+00	.10470+00	-.60030-01	.21330-01	.42440-01
.11810-02	-.72680-01	-.66250-01	.34980+00	-.82560+00	.22850+00	.32480+00	-.16320+00	.33400-01	.30240-01
-.14990-01	.92280+00	-.36450+00	.12060+00	-.53400-02	.17110-01	-.16290-01	.11870-01	-.60590-02	-.39210-02

APPENDIX D

INPUT RESPONSE ANALYSES

The input response analyses discussed in Chapter IV are given in this appendix. The cross reference of variable given in TABLE B-1 on page 146 is also applicable to these analysis results. Scaling factors for each process input is indicated at the base of each analysis. Run numbers are given as the fifth and sixth characters of the RUN NAME. Pertinent information about these runs are given in TABLE D-1.

TABLE D-1. INFORMATION ON INPUT RESPONSE ANALYSES

RUN NUMBER	STEADY STATE	MODEL	VARIABLE TESTED
1	L	10	*
2	M	10	*
3	H	10	*
4	M	10	Θ
5	M	10	M I O T C Q
6	M	10	
7	M	10	
8	M	10	
9	M	9	*
10	M	6	*
11	M	5	*

* all input variables tested.

RESULTS OF SVD OF INPUT RESPONSE ANALYSIS

INPUT RESPONSE ANALYSIS RUN NAME: SVDR02.DAT
INPUT DATA FOR ANALYSIS FROM: SSINO2.DAT

DATE: 17-SEP-79
TIME: 09:49 14.2

INPUT STEADY STATE VALUES
T= .3451240+03 RO= .9523240-07
I= .7088520-02 RI= .2443800-04
M= .3597710-01 R2= .1250960-01
RAD= .3738470-09

P0= .2613930-02
P1= .1216520-01
P2= .9027970-03

JACOBIAN MATRIX VALUES

-.18600-04	-.13110-02	.00000+00	.00000+00	.00000+00	.49520+05	.00000+00	.00000+00	.00000+00
-.35930-05	-.13260-03	.00000+00	.00000+00	.00000+00	-.12630+04	.00000+00	.00000+00	.00000+00
-.50400-08	-.23480-06	-.99210-04	.00000+00	.00000+00	.49400+01	.00000+00	.00000+00	.00000+00
.19240-05	.11700-03	.00000+00	.00000+00	.00000+00	.11360+00	.49400+01	.00000+00	.00000+00
.13080-02	.87610-01	.00000+00	.00000+00	.00000+00	.58190+06	.22730+04	.49400+01	.00000+00
-.45440-07	.00000+00	.00000+00	.00000+00	.00000+00	.00000+00	.00000+00	.00000+00	.00000+00
.50000-07	-.61790-06	.00000+00	.00000+00	.00000+00	-.14850-03	.00000+00	.00000+00	.00000+00
.17230-05	-.83750-04	.00000+00	.00000+00	.00000+00	.59580-04	.00000+00	.00000+00	.00000+00
.86030-03	-.42740-01	.00000+00	.00000+00	.00000+00	.12640+03	-.49400+01	.00000+00	.00000+00
.36330-05	.33120-04	.00000+00	.00000+00	.00000+00	-.58070+06	.25250+04	-.49400+01	.00000+00
					.59580-04	.49250+00	.00000+00	.00000+00
								.12670+04

INPUT MATRIX B & SINGULAR VALUES

.59000-03	.00000+00	.00000+00	.99630-03	.24800-02	SV(1)=	0.2122251237132796460+04
-.23850-04	.99210-04	.00000+00	.00000+00	.00000+00	SV(2)=	0.7737693212749480280+01
.51450-07	-.16550-06	.00000+00	.00000+00	.00000+00	SV(3)=	0.1850242186652594250+00
.23950-04	-.84930-04	.00000+00	.00000+00	.00000+00	SV(4)=	0.1264127860189150120+01
.17770-01	-.65270-01	.00000+00	.00000+00	.00000+00	SV(5)=	0.7713808595453017000+19
-.69280-07	.00000+00	.39680-05	.00000+00	.00000+00	SV(6)=	0.0000000000000000000+00
.18750-11	.19990-06	.00000+00	.00000+00	.00000+00	SV(7)=	0.0000000000000000000+00
.48090-09	.84800-04	.00000+00	.00000+00	.00000+00	SV(8)=	0.0000000000000000000+00
.24620-06	.43490-01	.00000+00	.00000+00	.00000+00	SV(9)=	0.0000000000000000000+00
.73590-14	-.12490-06	.00000+00	.00000+00	.00000+00	SV(10)=	0.0000000000000000000+00

MATRIX U - ORTHONORMALIZED COLUMNS

.16900-04	.99910+00	-.34340-01	.19010-01	.59760-03	.00000+00	.00000+00	.00000+00	.00000+00
-.68960-03	-.28060-01	-.28690+00	.95750+00	-.58190-02	.00000+00	.00000+00	.00000+00	.00000+00
.50100-06	-.12010-03	-.39360-02	-.13650-02	.45140+00	.00000+00	.00000+00	.00000+00	.00000+00
.78760-03	-.27420-01	.95710+00	-.28770+00	-.20040-01	.00000+00	.00000+00	.00000+00	.00000+00
.99990+00	-.16890-01	.11360-02	.56570-03	.19830-04	.00000+00	.00000+00	.00000+00	.00000+00
-.16940-04	.14080-02	-.22260-01	.54260-03	.88060+00	.00000+00	.00000+00	.00000+00	.00000+00
.31780-10	-.31210-08	-.15780-06	-.47860-07	-.19960-05	.00000+00	.00000+00	.00000+00	.00000+00
.19870-07	-.22110-06	-.20680-04	-.59090-05	-.42490+03	.00000+00	.00000+00	.00000+00	.00000+00
.16190-04	.18420-03	-.43680-03	.24170-03	-.23500+00	.00000+00	.00000+00	.00000+00	.00000+00
.29640-10	.20690-08	-.85770-08	.25020-07	-.32560-05	.00000+00	.00000+00	.00000+00	.00000+00

MATRIX V - ORTHOGONAL MATRIX

-.27850-01	-.45610+00	.88950+00	.31910-02	.00000+00	.00000+00	.00000+00	.00000+00	.00000+00
-.20740+00	-.42760+00	-.22880+00	.84960+00	.14820-15	.00000+00	.00000+00	.00000+00	.00000+00
-.93430+00	-.32730+00	-.13870+00	.26000-01	.98060-17	.00000+00	.00000+00	.00000+00	.00000+00
-.10760+00	-.26410+00	.13810+00	.19640+00	-.92790+00	.00000+00	.00000+00	.00000+00	.00000+00
-.26780+00	.65740+00	.34380+00	.48890+00	.37280+00	.00000+00	.00000+00	.00000+00	.00000+00
.00000+00	.00000+00	.00000+00	.00000+00	.00000+00	.00000+00	.00000+00	.00000+00	.00000+00
.00000+00	.00000+00	.00000+00	.00000+00	.00000+00	.00000+00	.00000+00	.00000+00	.00000+00
.00000+00	.00000+00	.00000+00	.00000+00	.00000+00	.00000+00	.00000+00	.00000+00	.00000+00
.00000+00	.00000+00	.00000+00	.00000+00	.00000+00	.00000+00	.00000+00	.00000+00	.00000+00
.00000+00	.00000+00	.00000+00	.00000+00	.00000+00	.00000+00	.00000+00	.00000+00	.00000+00

SCALING FACTORS: THETA/2000.00 MO/ 1.000 IO/ 0.040 IC/ 20.000 TO/ 25.000

RESULTS OF SVD OF INPUT RESPONSE ANALYSIS

INPUT RESPONSE ANALYSIS RUN NAME: R92.DAT
INPUT DATA FOR ANALYSIS FROM: SSIN02.DAT

DATE: 21-AUG-79
TIME: 09:31 22.6

INPUT STEADY STATE VALUES

T= .345124D+03 R0= .952324D-07 P0= .261393D-02
I= .708052D-02 R1= .244300D-04 P1= .121652D-01
M= .359771D+01 R2= .125096D-01 P2= .902797D+03
RAD= .373847D-09

JACOBIAN MATRIX VALUES

-.1860D-04	.1311D-02	.0000D+00	.0000D+00	.0000D+00	.4952D+05	.0000D+00	.0000D+00	.0000D+00
-.3591D-05	-.1326D-03	.0000D+00	.0000D+00	.0000D+00	-.1263D+04	.0000D+00	.0000D+00	.0000D+00
.3578D-06	-.2214D-06	.0000D+00	.0000D+00	.0000D+00	.4940D+01	.0000D+00	.0000D+00	.0000D+00
.1923D-05	.1170D-03	.0000D+00	.0000D+00	.0000D+00	.1136D+04	.0000D+00	.0000D+00	.0000D+00
.1308D-02	.8761D-01	.0000D+00	.0000D+00	.0000D+00	-.2397D-07	.5819D+06	.2273D+04	.4940D+01
-.4544D-07	.0000D+00	.0000D+00	.0000D+00	.0000D+00	-.9921D-04	.0000D+00	.0000D+00	.0000D+00
.5000D-07	.6179D-06	.0000D+00	.0000D+00	.0000D+00	-.1485D-03	.0000D+00	.0000D+00	.0000D+00
.1723D-05	-.8375D-04	.0000D+00	.0000D+00	.0000D+00	.5958D-04	.0000D+00	.0000D+00	.0000D+00
.8633D-03	-.4274D-01	.0000D+00	.0000D+00	.0000D+00	.1264D+03	-.4940D+01	.0000D+00	.0000D+00
.5900D-03	.0000D+00	.0000D+00	.0000D+00	.0000D+00	.5958D-04	.2525D+04	-.4940D+01	.0000D+00
-.2386D-04	.9921D-04	.0000D+00	.0000D+00	.0000D+00	.0000D+00	.0000D+00	.0000D+00	.0000D+00
.5145D-07	-.1655D-06	.0000D+00	.0000D+00	.0000D+00	.0000D+00	.0000D+00	.0000D+00	.0000D+00
.2395D-04	-.8493D-04	.0000D+00	.0000D+00	.0000D+00	.0000D+00	.0000D+00	.0000D+00	.0000D+00
.1777D-01	-.6527D-01	.0000D+00	.0000D+00	.0000D+00	.0000D+00	.0000D+00	.0000D+00	.0000D+00
-.6928D-07	.0000D+00	.3968D-05	.0000D+00	.0000D+00	.0000D+00	.0000D+00	.0000D+00	.0000D+00
.1875D-11	.1999D-06	.0000D+00	.0000D+00	.0000D+00	.0000D+00	.0000D+00	.0000D+00	.0000D+00
.4809D-04	.8480D-04	.0000D+00	.0000D+00	.0000D+00	.0000D+00	.0000D+00	.0000D+00	.0000D+00
.2462D-06	.4349D-01	.0000D+00	.0000D+00	.0000D+00	.0000D+00	.0000D+00	.0000D+00	.0000D+00

INPUT MATRIX U & SINGULAR VALUES

.5900D-03	.0000D+00	.9963D-03	.2480D-02	SV1 11=	0.212225123713279646D+04
-.2386D-04	.9921D-04	.0000D+00	.0000D+00	SV1 21=	0.773769321274948038D+01
.5145D-07	-.1655D-06	.0000D+00	.0000D+00	SV1 31=	0.185024218665259416D+00
.2395D-04	-.8493D-04	.0000D+00	.0000D+00	SV1 41=	0.126412786018915772D+01
.1777D-01	-.6527D-01	.0000D+00	.0000D+00	SV1 51=	0.353273935950016119D-19
-.6928D-07	.0000D+00	.3968D-05	.0000D+00	SV1 61=	0.0000000000000000D+00
.1875D-11	.1999D-06	.0000D+00	.0000D+00	SV1 71=	0.0000000000000000D+00
.4809D-04	.8480D-04	.0000D+00	.0000D+00	SV1 81=	0.0000000000000000D+00
.2462D-06	.4349D-01	.0000D+00	.0000D+00	SV1 91=	0.0000000000000000D+00

MATRIX U - ORTHONORMALIZED COLUMNS

.1690D-01	.9991D+00	-.3434D-01	.1901D-01	.5966D-03	.0000D+00	.0000D+00	.0000D+00	.0000D+00
-.6896D-03	-.2806D-01	-.2869D+00	.9575D+00	-.5841D-02	.0000D+00	.0000D+00	.0000D+00	.0000D+00
-.5010D-06	-.1201D-03	-.3936D-02	-.1365D-02	.4529D+00	.0000D+00	.0000D+00	.0000D+00	.0000D+00
.7876D-03	-.2742D-01	-.9571D+00	-.2877D+00	-.2011D-01	.0000D+00	.0000D+00	.0000D+00	.0000D+00
.9990D+00	-.1689D-01	.1136D-02	.5657D-03	.1972D-04	.0000D+00	.0000D+00	.0000D+00	.0000D+00
-.1694D-04	-.1408D-02	-.2226D-01	.5426D-03	.8631D+00	.0000D+00	.0000D+00	.0000D+00	.0000D+00
.3178D-10	-.3121D-08	-.1578D-06	-.4786D-07	-.5575D+06	.0000D+00	.0000D+00	.0000D+00	.0000D+00
.1987D-07	-.2211D-06	-.2068D-04	-.5909D-05	-.3263D-03	.0000D+00	.0000D+00	.0000D+00	.0000D+00
.1619D-04	.1842D-03	-.4368D-03	.2417D-03	-.2223D+00	.0000D+00	.0000D+00	.0000D+00	.0000D+00

MATRIX V - ORTHOGONAL MATRIX

.2785D-01	-.4561D+00	.8895D+00	.3191D-02	.0000D+00	.0000D+00	.0000D+00	.0000D+00	.0000D+00
.2074D+00	-.4276D+00	-.2288D+00	.8496D+00	.5943D-16	.0000D+00	.0000D+00	.0000D+00	.0000D+00
-.9343D+00	-.3273D+00	-.1387D+00	.2600D-01	.4077D-17	.0000D+00	.0000D+00	.0000D+00	.0000D+00
-.1076D+00	.2641D+00	.1301D+00	.1964D+00	-.9279D+00	.0000D+00	.0000D+00	.0000D+00	.0000D+00
-.2678D+00	.6574D+00	.3438D+00	.4889D+00	.3728D+00	.0000D+00	.0000D+00	.0000D+00	.0000D+00
.0000D+00	.0000D+00	.0000D+00	.0000D+00	.0000D+00	.0000D+00	.0000D+00	.0000D+00	.0000D+00
.0000D+00	.0000D+00	.0000D+00	.0000D+00	.0000D+00	.0000D+00	.0000D+00	.0000D+00	.0000D+00
.0000D+00	.0000D+00	.0000D+00	.0000D+00	.0000D+00	.0000D+00	.0000D+00	.0000D+00	.0000D+00
.0000D+00	.0000D+00	.0000D+00	.0000D+00	.0000D+00	.0000D+00	.0000D+00	.0000D+00	.0000D+00

SCALING FACTORS: THETA/2000.000 MO/ 1.000 IO/ 0.040 TC/ 20.000 TO/ 25.000

RESULTS OF SVD OF INPUT RESPONSE ANALYSIS

INPUT RESPONSE ANALYSIS RUN NAME: R62.DAT
 INPUT DATA FOR ANALYSIS FROM: SSIN02.DAT
 DATE: 21-AUG-79
 TIME: 09132 54.3
 INPUT STEADY STATE VALUES
 T= .3451240+03 R0= .9523240-07 P0= .2413930-02
 I= .7080520-02 R1= .2443000-04 P1= .1216520-01
 M= .3597710+01 R2= .1250960-01 P2= .9027970-03
 RAD= .3738470-09

JACOBIAN MATRIX VALUES

.26090-04	-.21430-02	.00000+00	.00000+00	.00000+00	.33300+00
-.10720-04	-.44550-04	.00000+00	.00000+00	.00000+00	-.04910-02
.31460-07	-.12310-06	-.99210-04	.00000+00	.00000+00	.33190-04
.10770-04	-.54830-04	.00000+00	-.99210-04	.00000+00	.85510-02
.45420-02	-.45110-01	.00000+00	.00000+00	-.99210-04	.89180+00
-.45440-07	.00000+00	.00000+00	.00000+00	.00000+00	-.14850-03

INPUT MATRIX B & SINGULAR VALUES

.59000-03	.11170-02	.00000+00	.99630-03	.24900-02	SV(1)=	0.2122251236854654590+04
-.23860-04	.70720-04	.00000+00	.00000+00	.00000+00	SV(2)=	0.7737693081542198150+01
.51450-07	-.54050-07	.00000+00	.00000+00	.00000+00	SV(3)=	0.1850242009776558380+00
.23950-04	.28350-04	.00000+00	.00000+00	.00000+00	SV(4)=	0.1264127823234555860+01
.17770-01	.63360-01	.00000+00	.00000+00	.00000+00	SV(5)=	0.7299192938323151560-19
-.69280-07	.00000+00	.39680-05	.00000+00	.00000+00	SV(6)=	0.0000000000000000000+00

MATRIX U - ORTHONORMALIZED COLUMNS

.16900-01	.99910+00	-.34340-01	.19010-01	.36280-03	.00000+00
-.68960-03	-.28060-01	-.28690+00	.95750+00	-.37390-02	.00000+00
.50100-06	-.12010-03	-.39360-02	-.13650-02	.82910+00	.00000+00
.78760-03	-.27420-01	-.95710+00	-.28770+00	-.15300-01	.00000+00
.99990+00	-.16890-01	.11360-02	.56570-03	.12390-04	.00000+00
-.16940-04	-.14080-02	-.22260-01	.54260-03	.55890+00	.00000+00

MATRIX V - ORTHOGONAL MATRIX

.27850-04	-.45610+00	.88950+00	.31910-02	.00000+00	.00000+00
.20740+00	-.42760+00	-.22880+00	.84960+00	.11210-15	.00000+00
-.93430+00	-.32730+00	-.13870+00	.26000-01	.71110-17	.00000+00
-.10760+00	.26410+00	.13810+00	.19640+00	.92790+00	.00000+00
-.226780+00	.65740+00	.34380+00	.48890+00	-.37280+00	.00000+00
.00000+00	.00000+00	.00000+00	.00000+00	.00000+00	.00000+00

SCALING FACTORS: THETA/2000.000 MO/ 1.000 IO/ 0.040 TC/ 20.000 TO/ 25.000

RESULTS OF SVD OF INPUT RESPONSE ANALYSIS

INPUT RESPONSE ANALYSIS RUN NAME: RS2.DAT
 INPUT DATA FOR ANALYSIS FROM: SSIN02.DAT

DATE: 21-AUG-79
 TIME: 09133 3.4

INPUT STEADY STATE VALUES
 T= .3451240-03 R0= .9523240-07 P0= .2613930-02
 I= .7080520-02 R1= .2443000-04 P1= .1216520-01
 M= .3597710-01 R2= .1250960-01 P2= .9027970-03
 RAD= .3738470-09

JACOBIAN MATRIX VALUES

.15900-03	-.21430-02	.00000+00	.00000+00	.00000+00	.00000+00
-.01200-05	-.44550-04	.00000+00	.00000+00	.00000+00	.00000+00
-.21300-07	-.12310-06	-.99210-04	.00000+00	.00000+00	.00000+00
-.01570-05	-.54030-04	.00000+00	-.99210-04	.00000+00	.00000+00
.42690-02	-.45110-01	.00000+00	.00000+00	-.99210-04	.00000+00

INPUT MATRIX B & SINGULAR VALUES

.43470-03	.11170-02	.08960-02	.99630-03	.24800-02	SV(1)= 0.2122251236550149800+04
-.19900-04	.10720-04	-.22690-03	.00000+00	.00000+00	SV(2)= 0.7737685406324953610+01
.35970-07	-.54050-07	.08680-06	.00000+00	.00000+00	SV(3)= 0.1849783459974766990+00
.19960-04	.28350-04	.22850-03	.00000+00	.00000+00	SV(4)= 0.1264127637150689450+01
.17360-01	.63360-01	.23830-01	.00000+00	.00000+00	SV(5)= 0.1702136351751408730-19

MATRIX U - ORTHONORMALIZED COLUMNS

.16900-01	.99910+00	-.34320-01	.19010-01	.10820-04
-.68960-03	-.28060-01	-.28700+00	.95750+00	.17420-03
.50100-06	-.12010-03	-.39370-02	-.13650-02	.10000+01
.78760-03	-.27420-01	-.95730+00	-.28770+00	-.41650-02
.99990+00	-.16890-01	.11360-02	.56570-03	.27170-05

MATRIX V - ORTHOGONAL MATRIX

.27850-01	-.45610+00	.08950+00	.31930-02	.00000+00
.20740+00	-.42760+00	-.22880+00	.84960+00	.13500-16
-.93430+00	-.32730+00	-.13870+00	.26000-01	.10140-17
-.10760+00	.26410+00	.13810+00	.19640+00	.92790+00
-.26780+00	.65740+00	.34380+00	.48890+00	-.37280+00

SCALING FACTORS: THETA/2000.000 MO/ 1.000 IO/ 0.040 TC/ 20.000 TO/ 25.000

VITA

John H. E. Stelling III was born on October 3, 1952 in Charleston, South Carolina to Mr. John H. E. Stelling Jr. and Mrs. Louise Myers Stelling.

He attended Porter-Gaud School where he graduated in June 1970.

He attended Clemson University from 1970 to May 1974 when he graduated with a B. S. in Chemical Engineering. He has worked as a technical trainee in Project Engineering for Tennessee Eastman Company in Kingsport, Tennessee. Upon completion of his undergraduate study, Mr. Stelling accepted a position in Research and Development with Dow Chemical USA in Plaquemine, Louisiana. He worked in the process development area of ethylene oxide research and was promoted to Research Engineer in March 1976.

In 1978, he accepted a teaching assistantship with the University of Tennessee where he graduated in December 1979 with an M. S. in Chemical Engineering.

Mr. Stelling is a member of The Honor Society of Phi Kappa Phi, Tau Beta Pi, Sigma Xi, and The American Institute of Chemical Engineers.